

*Partial Differential Equations (PDEs)*

# معادلات دیفرانسیل جزئی

Ghasemzadeh

فهرست عناوین و فصول

حل دستگاه معادلات دیفرانسیل جزئی

## یادآوری - جبر خطی

$$A = \begin{bmatrix} 0 & 8 \\ 2 & 0 \end{bmatrix} \quad \det(A - \lambda I) = 0 \quad \begin{vmatrix} -\lambda & 8 \\ 2 & -\lambda \end{vmatrix} = 0 \quad \lambda = \pm 4 \quad \text{مثال}$$

$$Ax - \lambda x = 0$$

$$\lambda = 4 \quad \begin{bmatrix} -4 & 8 \\ 2 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow P_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\lambda = -4 \quad \begin{bmatrix} 4 & 8 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow P_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \quad P = \text{eigen vectors of } A$$

$$P^{-1} A P = \begin{bmatrix} 2 & -2 \\ 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 0 & 8 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 2 & -2 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 0 & -4 \end{bmatrix} = \Lambda$$

$P^{-1} A P = \Lambda$   
Dr. Hasan Ghasemzadeh

## یادآوری - جبر خطی

$$y' = \bar{A}y = \begin{bmatrix} 2 & -4 \\ 1 & -3 \end{bmatrix} y \quad \text{مثال: مقادیر ویژه و بردارهای ویژه را محاسبه نمایید}$$

جواب خصوصی با ارضای شرط ذیل

$$y^T(0) = [3 \quad 0]$$

$$\det(A - \lambda I) = 0 \quad \begin{vmatrix} 2 - \lambda & -4 \\ 1 & -3 - \lambda \end{vmatrix} = 0 \quad \lambda^2 + \lambda - 2 = 0$$

$$\lambda = -2$$

$$\lambda = 1$$

مقادیر ویژه اعداد صحیح و مختلف العلامه

Dr. Hasan Ghasemzadeh

## یادآوری - جبر خطی

مثال

$$\lambda = -2 \quad (A - \lambda I)X_1 = 0 \quad \begin{bmatrix} 4 & -4 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow X_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda = 1 \quad (A - \lambda I)X_2 = 0 \quad \begin{bmatrix} 1 & -4 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow X_2 = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

$$y(x) = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-2x} + c_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} e^x \quad y_1 = c_1 e^{-2x} + 4c_2 e^x \\ y_2 = c_1 e^{-2x} + c_2 e^x$$

Dr. Hasan Ghasemzadeh

## یادآوری - جبر خطی

مثال

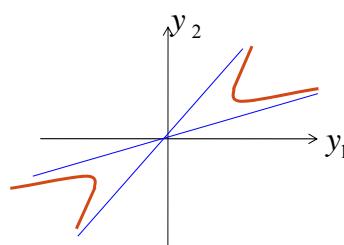
$$c_1 = 0 \Rightarrow y_1 = 4c_2 e^x, y_2 = c_2 e^x \quad y_1 = 4y_2 \\ c_2 = 0 \Rightarrow y_1 = c_1 e^{-2x}, y_2 = c_1 e^{-2x} \quad y_1 = y_2$$

$$y_1(0) = c_1 + 4c_2 = 3 \quad c_1 = -1, c_2 = 1 \\ y_2(0) = c_1 + c_2 = 0$$

$$y_1 = -e^{-2x} + 4e^x$$

$$y_2 = -e^{-2x} + e^x$$

شرط مرزی



Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

دستگاه معادلات همگن مرتبه اول

$$\begin{cases} x_1' - a_{11}x_1 - a_{12}x_2 - \dots - a_{1n}x_n = 0 \\ x_2' - a_{21}x_1 - a_{22}x_2 - \dots - a_{2n}x_n = 0 \\ \vdots \\ x_n' - a_{n1}x_1 - a_{n2}x_2 - \dots - a_{nn}x_n = 0 \end{cases}$$

حالت استاندارد - معادله همگن

$$\left\{ \begin{array}{c} x_1 \\ \vdots \\ x_n \end{array} \right\}' = \left( \begin{array}{ccc} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{array} \right) \left\{ \begin{array}{c} x_1 \\ \vdots \\ x_n \end{array} \right\} \quad \{X\}' = [A]\{X\} \quad \{X\} = \left\{ \begin{array}{c} x_1 \\ \vdots \\ x_n \end{array} \right\}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

فرض جواب معادله بصورت نمایی

$$\left\{ \begin{array}{c} x_1 \\ \vdots \\ x_n \end{array} \right\} = \left( \begin{array}{ccc} c_{11} & \dots & c_{1n} \\ \vdots & \ddots & \vdots \\ c_{n1} & \dots & c_{nn} \end{array} \right) \left\{ \begin{array}{c} e^{\lambda_1 t} \\ \vdots \\ e^{\lambda_n t} \end{array} \right\} \quad \{X\} = \{c_1\}e^{\lambda_1 t} + \dots + \{c_n\}e^{\lambda_n t}$$

$$\{c_k\} = \left\{ \begin{array}{c} c_{1k} \\ \vdots \\ c_{nk} \end{array} \right\}$$

$$\begin{aligned} \{X\}' &= \{c_1\}\lambda_1 e^{\lambda_1 t} + \dots + \{c_n\}\lambda_n e^{\lambda_n t} \\ &= [A]\{X\} = [A]\{c_1\}e^{\lambda_1 t} + \dots + [A]\{c_n\}e^{\lambda_n t} \end{aligned}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

برای برقراری رابطه باید داشته باشیم

$$\{c_1\} \lambda_1 = [A] \{c_1\}$$

⋮

$$\{c_n\} \lambda_n = [A] \{c_n\} \quad \lambda_1 \neq \lambda_2 \neq \dots \neq \lambda_n$$

$$[A] \{c_k\} = \lambda_k \{c_k\} = \lambda_k I \{c_k\}$$

$$([A] - \lambda_k I) \{c_k\} = 0 \quad \text{بردارهای ویژه}$$

$$\Rightarrow ([A] - \lambda_k I) = 0$$

با حل این دستگاه معادلات مقادیر ویژه تعیین می شوند

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

- Consider two coupled first-order PDEs

مثال

$$\begin{aligned} -2x' + 2x + y' + 6y &= 0 \\ + 2x' + 3x + 3y' + 8y &= 0 \end{aligned} \quad \begin{cases} x = f(t) \\ y = g(t) \end{cases}$$

$$\begin{cases} -x + y' - 4y = 0 \\ x' + 3x + 10y = 0 \end{cases} \quad \begin{cases} y' = x + 4y \\ x' = -3x - 10y \end{cases}$$

**Standard Form**

$$\begin{Bmatrix} x \\ y \end{Bmatrix}' = \begin{bmatrix} -3 & -10 \\ 1 & 4 \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

### حالت استاندارد - معادله همگن

$$([A] - \lambda_k I) = 0$$

برای حالت همگن می توان از روش مقادیر ویژه استفاده نمود

$$\begin{bmatrix} -3 & -10 \\ 1 & 4 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = 0 \quad \Rightarrow \quad \begin{cases} \lambda_1 = 2 \\ \lambda_2 = -1 \end{cases}$$

بردارهای ویژه باید محاسبه شوند

$$\lambda = 2 \Rightarrow \begin{bmatrix} -3-2 & -10 \\ 1 & 4-2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow P_1 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

بردارهای ویژه

$$\lambda = -1 \Rightarrow \begin{bmatrix} -3+1 & -10 \\ 1 & 4+1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow P_2 = \begin{bmatrix} 1 \\ -1/5 \end{bmatrix}$$

$$x = \begin{bmatrix} 1 \\ -1/2 \end{bmatrix} e^{2t} + \begin{bmatrix} 1 \\ -1/5 \end{bmatrix} e^{-t} = \begin{bmatrix} e^{2t} & e^{-t} \\ -1/2 e^{2t} & -1/5 e^{-t} \end{bmatrix} \begin{Bmatrix} c_1 \\ c_2 \end{Bmatrix} = \underline{X} \underline{C} x = \begin{bmatrix} 1 & 1 \\ -1/2 & -1/5 \end{bmatrix} \begin{bmatrix} e^{2t} \\ e^{-t} \end{bmatrix}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

### معادله همگن - جواب مضاعف

$$\begin{Bmatrix} x \\ y \end{Bmatrix}' = \begin{bmatrix} 0 & 1 \\ -4 & 4 \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix}$$

$$([A] - \lambda_k I) = 0$$

روش مقادیر ویژه

$$\begin{vmatrix} 0-\lambda & 1 \\ -4 & 4-\lambda \end{vmatrix} = \lambda^2 - 4\lambda + 4 = 0 \quad \lambda_1 = 2$$

مقادیر ویژه مضاعف

بردار ویژه

$$\lambda = 2 \Rightarrow \begin{bmatrix} 0-2 & 1 \\ -4 & 4-2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = 0 \quad c_1 = 1 \Rightarrow P_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t} \quad X_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

معادله همگن - جواب مضاعف

جواب دوم به صورت مقابل است

جایگذاری در معادله

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t} + \begin{bmatrix} c_3 \\ c_4 \end{bmatrix} e^{2t} = \begin{bmatrix} 0 & 1 \\ -4 & 4 \end{bmatrix} \left( \begin{bmatrix} 1 \\ 2 \end{bmatrix} t e^{2t} + \begin{bmatrix} c_3 \\ c_4 \end{bmatrix} e^{2t} \right)$$

$$\begin{bmatrix} -2 & 1 \\ -4 & 2 \end{bmatrix} \begin{bmatrix} c_3 \\ c_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \Rightarrow \begin{bmatrix} c_3 \\ c_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$X = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t} + c_2 \left( \begin{bmatrix} 1 \\ 2 \end{bmatrix} t e^{2t} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{2t} \right)$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

معادله همگن - جواب مختلط

$$\begin{Bmatrix} x \\ y \end{Bmatrix}' = \begin{bmatrix} 2 & -5 \\ 2 & -4 \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix}$$

$$([A] - \lambda_k I) = 0$$

روش مقادیر ویژه

$$\begin{vmatrix} 2-\lambda & -5 \\ 2 & -4-\lambda \end{vmatrix} = \lambda^2 + 2\lambda + 2 = 0 \quad \lambda = -1 \pm i$$

مقادیر ویژه مزدوج

بردارهای ویژه

$$\lambda = -1 + i \Rightarrow \begin{bmatrix} 3-i & -5 \\ 2 & -3-i \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = 0 \quad c_1 = 5 \Rightarrow P_1 = \begin{bmatrix} 5 \\ 3-i \end{bmatrix}$$

بردار ویژه مزدوج

$$\lambda = -1 - i \Rightarrow \begin{bmatrix} 3+i & -5 \\ 2 & -3+i \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = 0 \quad c_1 = 5 \Rightarrow P_2 = \begin{bmatrix} 5 \\ 3+i \end{bmatrix}$$

جواب

$$X = c_1 \begin{bmatrix} 5 \\ 3-i \end{bmatrix} e^{(-1+i)t} + c_2 \begin{bmatrix} 5 \\ 3+i \end{bmatrix} e^{(-1-i)t}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

معادله ناهمگن

$$\begin{Bmatrix} x \\ y \end{Bmatrix}' = \begin{bmatrix} 0 & 1 \\ -2 & 3 \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix} + \begin{Bmatrix} f(t) \\ g(t) \end{Bmatrix}$$

$$\begin{Bmatrix} x \\ y \end{Bmatrix}' = \begin{bmatrix} 0 & 1 \\ -2 & 3 \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix}$$

معادله همگن

$$\begin{Bmatrix} x \\ y \end{Bmatrix}_c = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + c_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t}$$

جواب

$$\begin{Bmatrix} x \\ y \end{Bmatrix}_p = c_1(t) \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + c_2(t) \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t}$$

جواب خصوصی

15

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

معادله ناهمگن

جایگذاری در معادله

$$c_1(t) \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + 2c_2(t) \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t} + c'_1(t) \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + c'_2(t) \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t} =$$

$$\begin{pmatrix} 0 & 1 \\ -2 & 3 \end{pmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} c_1(t) e^t + \begin{pmatrix} 0 & 1 \\ -2 & 3 \end{pmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} c_2(t) e^{2t} + \begin{Bmatrix} f(t) \\ g(t) \end{Bmatrix}$$

$$c'_1(t) \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + c'_2(t) \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t} = \begin{Bmatrix} f(t) \\ g(t) \end{Bmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{bmatrix} c'_1(t) e^t \\ c'_2(t) e^{2t} \end{bmatrix} = \begin{Bmatrix} f(t) \\ g(t) \end{Bmatrix}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

معادله ناهمگن

جواب از کرامر

$$c_1'(t)e^t = \frac{\begin{vmatrix} f(t) & 1 \\ g(t) & 2 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}} = 2f(t) - g(t) \quad c_1'(t) = (2f(t) - g(t))e^{-t}$$

$$c_2'(t)e^{2t} = \frac{\begin{vmatrix} 1 & f(t) \\ 1 & g(t) \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}} = g(t) - f(t) \quad c_2'(t) = (g(t) - f(t))e^{-2t}$$

$$(g(t) = 1, f(t) = e^t) \Rightarrow c_1(t) = 2t + e^{-t}, c_2(t) = -0.5e^{-2t} + e^{-t}$$

$$\begin{Bmatrix} x \\ y \end{Bmatrix}_p = (2t + e^{-t}) \begin{Bmatrix} 1 \\ 1 \end{Bmatrix} e^t + (-0.5e^{-2t} + e^{-t}) \begin{Bmatrix} 1 \\ 2 \end{Bmatrix} e^{2t} \quad \text{جواب خصوصی}$$

$$\begin{Bmatrix} x \\ y \end{Bmatrix}_p = (2te^t + 1) \begin{Bmatrix} 1 \\ 1 \end{Bmatrix} + (e^t - 0.5) \begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

حل به روش اپراتور

$$\begin{cases} x' + y' + 2x + 2y = 0 \\ 2x' + y' + 3x - 3y = 0 \end{cases} \quad D = \frac{d}{dt}$$

$$\begin{bmatrix} D+2 & D+2 \\ 2D+3 & D-3 \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix} = 0 \quad \Rightarrow \quad \begin{cases} x = c_{11} e^{\lambda_1 t} + c_{12} e^{\lambda_2 t} \\ y = c_{21} e^{\lambda_1 t} + c_{22} e^{\lambda_2 t} \end{cases}$$

$$\begin{cases} Dx = \lambda_1 c_{11} e^{\lambda_1 t} + \lambda_2 c_{12} e^{\lambda_2 t} \\ Dy = \lambda_1 c_{21} e^{\lambda_1 t} + \lambda_2 c_{22} e^{\lambda_2 t} \end{cases}$$

$$\begin{cases} (D+2)x + (D+2)y = 0 \\ (2D+3)x + (D-3)y = 0 \end{cases} \quad \Rightarrow$$

$$\begin{cases} (\lambda_1 c_{11} + 2c_{11}) e^{\lambda_1 t} + (\lambda_2 c_{12} + 2c_{12}) e^{\lambda_2 t} + (\lambda_1 c_{21} + 2c_{21}) e^{\lambda_1 t} + (\lambda_2 c_{22} + 2c_{22}) e^{\lambda_2 t} = 0 \\ (2\lambda_1 c_{11} + 3c_{11}) e^{\lambda_1 t} + (2\lambda_2 c_{12} + 3c_{12}) e^{\lambda_2 t} + (\lambda_1 c_{21} - 3c_{21}) e^{\lambda_1 t} + (\lambda_2 c_{22} - 3c_{22}) e^{\lambda_2 t} = 0 \end{cases}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

### حل به روش اپراتور

$$\begin{cases} (\lambda_1 + 2)(c_{11} + c_{21}) e^{\lambda_1 t} + (\lambda_2 + 2)(c_{12} + c_{22}) e^{\lambda_2 t} = 0 \\ [(2\lambda_1 + 3)c_{11} + (\lambda_1 - 3)c_{21}] e^{\lambda_1 t} + [(2\lambda_2 + 3)c_{12} + (\lambda_2 - 3)c_{22}] e^{\lambda_2 t} = 0 \end{cases}$$

$$\begin{cases} (\lambda_1 + 2)c_{11} + (\lambda_1 + 2)c_{21} = 0 \\ (2\lambda_1 + 3)c_{11} + (\lambda_1 - 3)c_{21} = 0 \end{cases}, \quad \begin{cases} (\lambda_2 + 2)c_{12} + (\lambda_2 + 2)c_{22} = 0 \\ (2\lambda_2 + 3)c_{12} + (\lambda_2 - 3)c_{22} = 0 \end{cases}$$

$$\begin{vmatrix} \lambda_1 + 2 & \lambda_1 + 2 \\ 2\lambda_1 + 3 & \lambda_1 - 3 \end{vmatrix} = 0 \quad \text{مقایسه شود با} \quad \begin{vmatrix} D+2 & D+3 \\ 2D+3 & D-3 \end{vmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix} = 0$$

$$\begin{vmatrix} \lambda + 2 & \lambda + 2 \\ 2\lambda + 3 & \lambda - 3 \end{vmatrix} = 0 \Rightarrow (\lambda + 2)(\lambda - 3) - (\lambda + 2)(2\lambda + 3) = 0 \Rightarrow (\lambda + 2)(-\lambda - 6) = 0 \rightarrow \begin{cases} \lambda_1 = -2 \\ \lambda_2 = -6 \end{cases}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

### حل به روش اپراتور

$$\begin{bmatrix} \lambda + 2 & \lambda + 2 \\ 2\lambda + 3 & \lambda - 3 \end{bmatrix} \begin{Bmatrix} c_{11} \\ c_{12} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \quad \lambda = \lambda_1 = -2$$

$$\begin{bmatrix} 0 & 0 \\ -1 & -5 \end{bmatrix} \begin{Bmatrix} c_{11} \\ c_{12} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \Rightarrow \begin{cases} -c_{11} - 5c_{12} = 0 \\ c_{11} = 1 \end{cases} \Rightarrow c_{12} = -\frac{1}{5}$$

یک بردار ویژه بازاء مقادیر ویژه  $\lambda_1 = -2$  می باشد  $\begin{Bmatrix} 1 \\ -\frac{1}{5} \end{Bmatrix}$

$$\lambda = \lambda_2 = -6 \Rightarrow \begin{bmatrix} -4 & -4 \\ -9 & -9 \end{bmatrix} \begin{Bmatrix} c_{12} \\ c_{22} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \Rightarrow \begin{cases} c_{21} = 1 \\ c_{22} = -1 \end{cases} \quad \begin{Bmatrix} 1 \\ -1 \end{Bmatrix}$$

بردار ویژه  $\begin{Bmatrix} 1 \\ -1 \end{Bmatrix}$

$$\begin{Bmatrix} x \\ y \end{Bmatrix} = c_1 \begin{Bmatrix} 1 \\ -\frac{1}{5} \end{Bmatrix} e^{-2t} + c_2 \begin{Bmatrix} 1 \\ -1 \end{Bmatrix} e^{-6t}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل

مثال

$$\begin{cases} x'_1 + x_1 + x'_2 + 2x_2 = 0 \\ 5x'_1 + x_1 + 6x'_2 + 3x_2 = 0 \end{cases}$$

$$\begin{bmatrix} D+1 & D+2 \\ 5D+1 & 6D+3 \end{bmatrix} \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \Rightarrow \begin{vmatrix} \lambda+1 & \lambda+2 \\ 5\lambda+1 & 6\lambda+3 \end{vmatrix} = 0$$

$$(\lambda+1)(6\lambda+3) - (5\lambda+1)(\lambda+2) = 0 \Rightarrow \lambda=1,1 \Rightarrow \lambda_1=\lambda_2=1$$

$$\begin{bmatrix} \lambda_1+1 & \lambda_1+2 \\ 5\lambda_1+1 & 6\lambda_1+3 \end{bmatrix} \begin{Bmatrix} c_{11} \\ c_{12} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \Rightarrow \begin{bmatrix} 2 & 3 \\ 6 & 9 \end{bmatrix} \begin{Bmatrix} c_{11} \\ c_{12} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

$$c_{12} = -\frac{2}{3}, \quad c_{11} = 1 \quad \text{جگز!}$$

$$\begin{Bmatrix} 1 \\ -\frac{2}{3} \end{Bmatrix}$$

یک بردار مشخصه است  
Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

مثال

- Consider two coupled first-order PDEs

$$\begin{cases} u_t + 8v_x = 0 \\ v_t + 2u_x = 0 \end{cases} \quad \begin{cases} -\infty < x < \infty \\ 0 < t < \infty \end{cases}$$

**Initial condition**

$$\begin{cases} u(x, 0) = f(x) \\ v(x, 0) = g(x) \end{cases} \quad -\infty < x < \infty$$

**Matrix Form**

$$\begin{Bmatrix} u_t \\ v_t \end{Bmatrix} + \begin{bmatrix} 0 & 8 \\ 2 & 0 \end{bmatrix} \begin{Bmatrix} u_x \\ v_x \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \quad \text{or} \quad U_t + A U_x = 0$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

- **Changing variable**

مثال

$$U = P\bar{U} \quad U = \begin{Bmatrix} u \\ v \end{Bmatrix} \quad \bar{U} = \begin{Bmatrix} \bar{u} \\ \bar{v} \end{Bmatrix} \quad P = \text{eigen vectors of } A$$

$$U_t = P\bar{U}_t$$

$$U_x = P\bar{U}_x$$

$$\textbf{PDE} \quad P\bar{U}_t + A P\bar{U}_x = 0$$

$$P^{-1}P\bar{U}_t + P^{-1}A P\bar{U}_x = 0 \Rightarrow \bar{U}_t + \Lambda \bar{U}_x = 0 \quad \Lambda = \begin{bmatrix} 4 & 0 \\ 0 & -4 \end{bmatrix}$$

$$\begin{cases} \bar{u}_t + 4\bar{u}_x = 0 \\ \bar{v}_t - 4\bar{v}_x = 0 \end{cases}$$

Uncoupled system of PDE

Dr. Hasan-Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

$$\begin{cases} \bar{u}(x, t) = \phi(x - 4t) \\ \bar{v}(x, t) = \psi(x + 4t) \end{cases} \quad U = P\bar{U} = \begin{bmatrix} 2 & -2 \\ 1 & 1 \end{bmatrix} \begin{Bmatrix} \bar{u} \\ \bar{v} \end{Bmatrix} = \begin{bmatrix} 2 & -2 \\ 1 & 1 \end{bmatrix} \begin{Bmatrix} \phi(x - 4t) \\ \psi(x + 4t) \end{Bmatrix}$$

$$\begin{cases} u(x, t) = 2\phi(x - 4t) - 2\psi(x + 4t) \\ v(x, t) = \phi(x - 4t) + \psi(x + 4t) \end{cases}$$

$$\begin{cases} \phi(z) = \sin(z) \\ \psi(z) = z^2 \end{cases} \quad \begin{array}{l} \text{Arbitrary} \\ \text{functions} \end{array}$$

$$\begin{cases} u(x, t) = 2\sin(x - 4t) - 2(x + 4t)^2 \\ v(x, t) = \sin(x - 4t) + (x + 4t)^2 \end{cases}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

**ICS** 
$$\begin{cases} u(x, 0) = f(x) \\ v(x, 0) = g(x) \end{cases} \quad \begin{cases} 2\phi(x) - 2\psi(x) = f(x) \\ \phi(x) + \psi(x) = g(x) \end{cases}$$

$$\begin{cases} \phi(x) = 0.25(f(x) + 2g(x)) \\ \psi(x) = 0.25(2g(x) - f(x)) \end{cases}$$

$$\begin{cases} u(x, t) = 2\phi(x - 4t) - 2\psi(x + 4t) \\ \quad = 0.5(f(x - 4t) + 2g(x - 4t)) - 0.5(2g(x + 4t) - f(x + 4t)) \\ v(x, t) = \phi(x - 4t) + \psi(x + 4t) \\ \quad = 0.25(f(x - 4t) + 2g(x - 4t)) + 0.25(2g(x + 4t) - f(x + 4t)) \end{cases}$$

Dr. Hasan Ghasemzadeh

## دستگاه معادلات دیفرانسیل جزئی

• دینامیک مایعات

$$\begin{cases} u_t + uu_x + vu_y + (1/\rho)P_x = 0 \\ v_t + uv_x + vv_y + (1/\rho)P_x = 0 \\ P_t + (\rho u)_x + (\rho v)_y = 0 \\ \left(\frac{\rho}{\rho'}\right)_t + u\left(\frac{\rho}{\rho'}\right)_x + v\left(\frac{\rho}{\rho'}\right)_y = 0 \end{cases}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

- Consider two coupled first-order PDEs

$$\begin{cases} A_{11}u_x + B_{11}u_y + A_{12}v_x + B_{12}v_y = E_1 \\ A_{21}u_x + B_{21}u_y + A_{22}v_x + B_{22}v_y = E_2 \end{cases}$$

- In matrix form

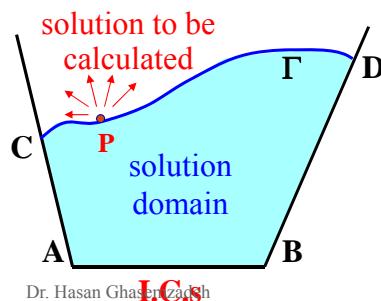
$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} u_x \\ v_x \end{bmatrix} + \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} \begin{bmatrix} u_y \\ v_y \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \end{bmatrix}$$

or  $\bar{\bar{A}} \bar{q}_x + \bar{\bar{B}} \bar{q}_y = \vec{E}, \quad \bar{q} = \begin{bmatrix} u \\ v \end{bmatrix}$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

- Questions: Is the behavior of the solution just above P uniquely determined by the information below and on the curve  $\Gamma$ ?
- Are the data sufficient to determine the directional derivatives at P in directions that lie above the curve  $\Gamma$ ?



$$\begin{cases} du = u_x dx + u_y dy \\ dv = v_x dx + v_y dy \end{cases}$$

Find  $dy/dx$  (characteristic direction) along which only the total differentials  $du$  and  $dv$  appear

## حل دستگاه معادلات دیفرانسیل جزئی

- Under what conditions are the derivatives ( $u_x, u_y, v_x, v_y$ ) uniquely determined at P by values of ( $u, v$ ) on  $\Gamma$ ?

$$\begin{cases} A_{11}u_x + B_{11}u_y + A_{12}v_x + B_{12}v_y = E_1 \\ A_{21}u_x + B_{21}u_y + A_{22}v_x + B_{22}v_y = E_2 \\ u_x dx + u_y dy = du \\ v_x dx + v_y dy = dv \end{cases}$$

**Determinant  $\neq 0$ : unique solution (linearly independent)**  
**Determinant  $= 0$ : multiple or no solutions**

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

- Determinant  $\neq 0$ : unique solution

$$\left[ \begin{array}{cc|cc} A_{11} & A_{12} & B_{11} & B_{12} \\ A_{21} & A_{22} & B_{21} & B_{22} \\ \hline dx & 0 & dy & 0 \\ 0 & dx & 0 & dy \end{array} \right] \begin{Bmatrix} u_x \\ v_x \\ u_y \\ v_y \end{Bmatrix} = \begin{Bmatrix} E_1 \\ E_2 \\ du \\ dv \end{Bmatrix} \Leftrightarrow \bar{\bar{C}} = \begin{bmatrix} \bar{\bar{A}} & \bar{\bar{B}} \\ \bar{\bar{I}}dx & \bar{\bar{I}}dy \end{bmatrix}$$

**Characteristic equation  $\det [C] = 0$**

$$\begin{aligned} \det \bar{\bar{C}} &= \det \begin{bmatrix} \bar{\bar{A}}dy - \bar{\bar{B}}dx \\ \bar{\bar{I}}dx \end{bmatrix} = \begin{vmatrix} A_{11}dy - B_{11}dx & A_{12}dy - B_{12}dx \\ A_{21}dy - B_{21}dx & A_{22}dy - B_{22}dx \end{vmatrix} \\ &= (A_{11}A_{22} - A_{12}A_{21})dy^2 + (A_{12}B_{21} + A_{21}B_{12} - A_{11}B_{22} - A_{22}B_{11})dxdy \\ &\quad + (B_{11}B_{22} - B_{12}B_{21})dx^2 \\ &= A'dy^2 + B'dxdy + C'dx^2 = 0 \end{aligned}$$

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

- Characteristic directions along which  $(u_x, u_y, v_x, v_y)$  are not defined uniquely
- Multiple solutions possible, discontinuity may occur

$$A' \left( \frac{dy}{dx} \right)^2 + B' \left( \frac{dy}{dx} \right) + C' = 0 \quad \text{Characteristic equation}$$

$$\frac{dy}{dx} = \frac{-B' \pm \sqrt{B'^2 - 4A'C'}}{2A'} \quad \text{Characteristic directions}$$

**Classification of equation types -- depends on the discriminant of the characteristic equation**

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

- Discriminant DIS

$$DIS = B'^2 - 4A'C' = (A_{12}B_{21} + A_{21}B_{12} - A_{11}B_{22} - A_{22}B_{11}) - 4(A_{11}A_{22} - A_{12}A_{21})(B_{11}B_{22} - B_{12}B_{21})$$

$$B'^2 - 4A'C' \begin{cases} > 0, & 2 \text{ real roots, 2 characteristics directions; Hyperbolic} \\ = 0, & 1 \text{ real root, 1 characteristics direction; Parabolic} \\ < 0, & 2 \text{ complex roots, no real characteristics; Elliptic} \end{cases}$$

- DIS < 0 (elliptic), cannot identify characteristic directions along which discontinuity may occur across  $\Gamma$
- Elliptic equation - continuous (smooth) solution

Dr. Hasan Ghasemzadeh

## حل دستگاه معادلات دیفرانسیل جزئی

- Transformation of higher-order PDE to first-order PDEs

$$A\phi_{xx} + B\phi_{xy} + C\phi_{yy} + H = 0$$

let  $\begin{cases} u = \phi_x \\ v = \phi_y \end{cases}$  (i.e.,  $\vec{V} = \nabla \phi$ )  $\Rightarrow \begin{cases} u_x = \phi_{xx}, & u_y = \phi_{xy} \\ v_x = \phi_{xy}, & v_y = \phi_{yy} \end{cases}$

- Convert to first-order PDEs

$$\begin{cases} Au_x + Bu_y + Cv_y + H = 0 \\ -u_y + v_x = 0 \end{cases}$$

$$\begin{bmatrix} A & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} u_x \\ v_y \end{bmatrix} + \begin{bmatrix} B & C \\ -1 & 0 \end{bmatrix} \begin{bmatrix} u_y \\ v_y \end{bmatrix} = \begin{bmatrix} -H \\ 0 \end{bmatrix}$$

Dr. Hasan Ghasemzadeh

$$\bar{\bar{A}}\vec{q}_x + \bar{\bar{B}}\vec{q}_y = \vec{E}$$

## حل دستگاه معادلات دیفرانسیل جزئی

- Transformation of second-order PDE to two first-order PDEs

$$\bar{\bar{A}}\vec{q}_x + \bar{\bar{B}}\vec{q}_y = \vec{E}$$

$$\det \bar{\bar{C}} = \det \left| \begin{array}{cc} \bar{\bar{A}} dy - \bar{\bar{B}} dx & -C dx \\ dx & dy \end{array} \right| = Ady^2 - Bdx dy + Cdx^2 = 0$$

**Characteristics equation and characteristic directions**

$$A\left(\frac{dy}{dx}\right)^2 - B\left(\frac{dy}{dx}\right) + C = 0 \Rightarrow \frac{dy}{dx} = \frac{B \pm \sqrt{B^2 - 4AC}}{2A}$$

**Hyperbolic:**  $B^2 - 4AC > 0$ ; 2 characteristics

**Parabolic:**  $B^2 - 4AC = 0$ ; 1 characteristic

**Elliptic:**  $B^2 - 4AC < 0$ ; no real characteristics

## حل دستگاه معادلات دیفرانسیل جزئی

- One variable,  $n = 1$

$$\bar{\bar{A}}\bar{q}_x + \bar{\bar{B}}\bar{q}_y = \bar{E} \Rightarrow Au_x + Bu_y = C$$

$$\begin{bmatrix} A & B \\ dx & dy \end{bmatrix} \begin{Bmatrix} u_x \\ u_y \end{Bmatrix} = \begin{Bmatrix} C \\ du \end{Bmatrix}$$

$$\det \begin{bmatrix} \bar{\bar{A}} dy - \bar{\bar{B}} dx \\ Ady - Bdx \end{bmatrix} = Ady - Bdx = 0 \Rightarrow \frac{dy}{dx} = -\frac{\lambda_x}{\lambda_y} = \frac{B}{A}$$

One real root  $\Rightarrow$  hyperbolic

$$d\lambda = \lambda_x dx + \lambda_y dy = Ady - Bdx = 0$$

$$\lambda = Ay - Bx = \text{const} \quad (\text{or } \xi = Ay - Bx)$$

Dr. Hasan Ghasemzadeh

## خطوط مشخصه

### Hyperbolic PDEs

- Two real roots, two characteristic directions
- Two propagation (marching) directions
- Domain of dependence
- Domain of influence
- $(u_x, u_y, v_x, v_y)$  are not uniquely defined along the characteristic lines, discontinuity may occur
- Boundary conditions must be specified according to the characteristics

Dr. Hasan Ghasemzadeh

## خطوط موجی

### *Parabolic PDEs*

- One real (double) root, one characteristic direction (typically  $t = \text{const}$ )
- **The solution is marching in time (or spatially) with given initial conditions**
- The solution will be modified by the boundary conditions (time-dependent, in general) during the propagation
- Any change in boundary conditions at  $t_1$  will not affect solution at  $t < t_1$ , but will change the solution after  $t = t_1$
- **Irreversible: You can control your future, but not changing what already happened (history)!**

Dr. Hasan Ghasemzadeh

## خطوط موجی

### *Elliptic PDEs*

- **$\det [C] \neq 0$  in every direction**
- The derivatives  $(u_x, u_y, v_x, v_y)$  can always be uniquely determined at every point in the solution domain
- **No marching or propagation direction !**
- Boundary conditions needed on all boundaries
- The solution will be continuous (smooth) in the entire solution domain
- **Jury problem** - all boundary conditions must be satisfied simultaneously

Dr. Hasan Ghasemzadeh

## System of Equations

- Two variables,  $n = 2$

$$\begin{aligned} \bar{\bar{A}}\vec{q}_x + \bar{\bar{B}}\vec{q}_y &= \vec{E} \\ \det[\bar{\bar{A}}dy - \bar{\bar{B}}dx] &= A'dy^2 + B'dxdy + C'dx^2 = 0 \\ \frac{dy}{dx} = -\frac{\lambda_x}{\lambda_y} &= \frac{-B' \pm \sqrt{B'^2 - 4A'C'}}{2A'} = \begin{cases} \alpha \\ \beta \end{cases} \Rightarrow \begin{cases} dy - \alpha dx = 0 \\ dy - \beta dx = 0 \end{cases} \end{aligned}$$

$$d\lambda = \lambda_x dx + \lambda_y dy = 0$$

$$\lambda_1 = \xi = y - \alpha x = \text{const}$$

Dr. Hasan Ghasemzadeh

$$\lambda_2 = \eta = y - \beta x = \text{const}$$

## System of N first-order PDEs

- Two-dimensional (two variables x, y)

$$\begin{cases} \bar{\bar{A}}\vec{q}_x + \bar{\bar{B}}\vec{q}_y = \bar{\bar{E}} \\ dx\vec{q}_x + dy\vec{q}_y = d\vec{q} \end{cases} \Rightarrow \begin{bmatrix} \bar{\bar{A}} & \bar{\bar{B}} \\ Idx & Idy \end{bmatrix} \begin{bmatrix} \vec{q}_x \\ \vec{q}_y \end{bmatrix} = \begin{bmatrix} \bar{\bar{E}} \\ d\vec{q} \end{bmatrix}; \quad \vec{q} = \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \\ \vdots \\ \mathbf{u}_n \end{bmatrix}$$

**Characteristic equation**  $\det \bar{\bar{C}} = \det [\bar{\bar{A}}dy - \bar{\bar{B}}dx] = 0$

**Characteristic lines**  $\lambda = \text{const}, \quad d\lambda = \lambda_x dx + \lambda_y dy = 0$

**Characteristic directions**  $\frac{dy}{dx} = -\frac{\lambda_x}{\lambda_y}, \quad \det [\bar{\bar{A}}\lambda_x + \bar{\bar{B}}\lambda_y] = 0$

Dr. Hasan Ghasemzadeh

## Example

- Steady 2D incompressible Navier-Stokes equations

$$\begin{cases} u_x + v_y = 0 \\ uu_x + vu_y + p_x - (u_{xx} + u_{yy})/Re = 0 \\ uv_x + vv_y + p_y - (v_{xx} + v_{yy})/Re = 0 \end{cases}$$

3 coupled PDEs for (u, v, p)

let  $R = v_x$ ,  $S = v_y = -u_x$ ,  $T = u_y$ , then

$$\begin{cases} -R_y + S_x = -v_{xy} + v_{xy} = 0 \\ S_y + T_x = -u_{xy} + u_{xy} = 0 \\ -uS + vT + p_x - (-S_x + T_y)/Re = 0 \\ uR + vS + p_y - (R_x + S_y)/Re = 0 \end{cases}$$

Convert to 4 first-order PDEs for 4 unknowns (R, S, T, p)

Dr. Faranak Ghasemzadeh

## Example

- Steady 2D incompressible Navier-Stokes equations

$$\bar{\bar{A}}\bar{q}_x + \bar{\bar{B}}\bar{q}_y = \bar{E}$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1/Re & 0 & 1 \\ -1/Re & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} R_x \\ S_x \\ T_x \\ p_x \end{bmatrix} + \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1/Re & 0 \\ 0 & -1/Re & 0 & 1 \end{bmatrix} \begin{bmatrix} R_y \\ S_y \\ T_y \\ p_y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ uS - vT \\ -uR - vS \end{bmatrix}$$

- Characteristic equation

$$\det[\bar{\bar{A}}\lambda_x + \bar{\bar{B}}\lambda_y] = \begin{vmatrix} -\lambda_y & \lambda_x & 0 & 0 \\ 0 & \lambda_y & \lambda_x & 0 \\ 0 & \lambda_x/Re & -\lambda_y/Re & \lambda_x \\ -\lambda_x/Re & -\lambda_y/Re & 0 & \lambda_y \end{vmatrix} = \frac{1}{Re}(\lambda_x^2 + \lambda_y^2)^2 = 0$$

Dr. Faranak Ghasemzadeh  
Elliptic system (all complex roots, no real roots)

## System of Equations

- Three variables (Fourier analysis)

$$\begin{cases} \bar{A}\vec{q}_x + \bar{B}\vec{q}_y + \bar{C}\vec{q}_z = \bar{E} \\ dx\vec{q}_x + dy\vec{q}_y + dz\vec{q}_z = d\vec{q} \end{cases} ; \quad \vec{q} = \begin{bmatrix} \vec{u}_1 \\ \vec{u}_2 \\ \vdots \\ \vec{u}_n \end{bmatrix}$$

**Characteristic equation**  $\det \bar{C} = \det [\bar{A}\lambda_x + \bar{B}\lambda_y + \bar{C}\lambda_z] = 0$

**Characteristic surface**  $d\lambda = \lambda_x dx + \lambda_y dy + \lambda_z dz = 0 \quad (\lambda = \text{const})$   
 $(\lambda_x, \lambda_y, \lambda_z)$

**Characteristic directions**

Normal to characteristic  
surface  $\lambda = \text{constant}$

Dr. Hasan Ghasemzadeh

## System of N Equations

- Classification for first-order equations in n variables
- Hyperbolic: n real roots
- Parabolic: m real roots,  $1 \leq m < n$ , and no complex roots
- Elliptic: no real roots
- Mixed: some real and some complex roots, assumed to be elliptic if any complex roots occur

Dr. Hasan Ghasemzadeh

## Canonical Forms of PDEs

- Any PDE can also be transformed into Canonical form  $(x,y) \rightarrow (\xi, \eta)$

$$\begin{cases} A\phi_{xx} + B\phi_{xy} + C\phi_{yy} + D\phi_x + E\phi_y + F\phi = G \\ A'\phi_{\xi\xi} + B'\phi_{\xi\eta} + C'\phi_{\eta\eta} + D'\phi_\xi + E'\phi_\eta + F'\phi = G' \\ A' = C' = 0 \end{cases}$$

$$\begin{cases} A' = A\xi_x^2 + B\xi_x\xi_y + C\xi_y^2 = 0 \\ C' = A\eta_x^2 + B\eta_x\eta_y + C\eta_y^2 = 0 \end{cases}$$

Dr. Hasan Ghasemzadeh

## Canonical Forms of PDEs

- Characteristic equations:  $A' = C' = 0$

$$\begin{cases} A\left(\frac{\xi_x}{\xi_y}\right)^2 + B\left(\frac{\xi_x}{\xi_y}\right) + C = 0 \Rightarrow \frac{\xi_x}{\xi_y} = \frac{-B \pm \sqrt{B^2 - 4AC}}{2A} \\ A\left(\frac{\eta_x}{\eta_y}\right)^2 + B\left(\frac{\eta_x}{\eta_y}\right) + C = 0 \Rightarrow \frac{\eta_x}{\eta_y} = \frac{-B \pm \sqrt{B^2 - 4AC}}{2A} \end{cases}$$

- Characteristic directions:  $\xi = \text{const}, \eta = \text{const}$  ( $d\xi, d\eta = 0$ )

$$\begin{cases} \xi = c_1, \quad d\xi = \xi_x dx + \xi_y dy = 0 \\ \eta = c_2, \quad d\eta = \eta_x dx + \eta_y dy = 0 \end{cases} \Rightarrow \frac{dy}{dx} = -\frac{\xi_x}{\xi_y} = -\frac{\eta_x}{\eta_y} = \frac{B \pm \sqrt{B^2 - 4AC}}{2A}$$

$$A' = C' = 0 \Rightarrow A\left(\frac{dy}{dx}\right)^2 - B\left(\frac{dy}{dx}\right) + C = 0 \quad \text{Characteristic equation}$$

Dr. Hasan Ghasemzadeh

## Canonical Forms

- Hyperbolic PDE:  $B'^2 - 4A'C' > 0$ , 2 real characteristics

$$\begin{cases} \phi_{\xi\eta} = h_1(\xi, \eta, \phi, \phi_\xi, \phi_\eta), & A' = C' = 0, B' = 1 \\ \phi_{\xi\xi} - \phi_{\eta\eta} = h'_1(\xi, \eta, \phi, \phi_\xi, \phi_\eta), & A' = 1, B' = 0, C' = -1 \end{cases} \quad \begin{cases} \bar{\xi} = \xi + \eta \\ \bar{\eta} = \xi - \eta \end{cases}$$

- Parabolic PDE:  $B'^2 - 4A'C' = 0$ , 1 real characteristic

$$\phi_{\xi\xi} = h_2(\xi, \eta, \phi, \phi_\xi, \phi_\eta), \quad A' = 1, B' = C' = 0$$

- Elliptic PDE:  $B'^2 - 4A'C' < 0$ , no real characteristics

$$\phi_{\xi\xi} + \phi_{\eta\eta} = h_3(\xi, \eta, \phi, \phi_\xi, \phi_\eta), \quad A' = 1, B' = 0, C' = 1$$

### 2.1.5 Classification by Fourier Analysis

#### Characteristic polynomial

- The root determine the characteristic surfaces ( $\lambda = \text{const}$ ) or directions ( $\lambda_x, \lambda_y, \lambda_z, \dots$ )

#### Fourier Analysis

- The roots have a different physical interpretation
- Produces the same characteristic polynomial from the “principal part” of the governing equation. However, ( $\lambda_x, \lambda_y, \lambda_z, \dots$ ) also determine the solution of PDE, e.g., **oscillatory, exponential growth, wavelike, ...**
- **Avoids the construction of intermediate first-order PDEs**

## Classification by Fourier Analysis

- Consider second-order PDE

$$Au_{xx} + Bu_{xy} + Cu_{yy} = 0$$

- General solution in Fourier series

$$u(x, y) = \frac{1}{4\pi^2} \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \hat{u}_{jk} \exp[i(\sigma_x)_j x] \exp[i(\sigma_y)_k y]$$

$\hat{u}_{jk}$	- amplitude	Determined by boundary conditions
$\sigma_x, \sigma_y$	- exponents	Determine the nature of solutions

Dr. Hasan Ghasemzadeh

## Classification by Fourier Analysis

- Take derivatives of the general solution

$$\begin{cases} u_x = \frac{1}{4\pi^2} \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} i(\sigma_x)_j \hat{u}_{jk} \exp[i(\sigma_x)_j x] \exp[i(\sigma_y)_k y] \\ u_y = \frac{1}{4\pi^2} \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} i(\sigma_y)_k \hat{u}_{jk} \exp[i(\sigma_x)_j x] \exp[i(\sigma_y)_k y] \end{cases}$$

- If A, B, C are not function of u (linear), then the relation between  $\sigma_x$  and  $\sigma_y$  is the same for all modes
- “Superposition” gives all possible functional forms for linear equation

Dr. Hasan Ghasemzadeh

## Classification by Fourier Analysis

- Consider one single model only  $(\sigma_x)_j = \sigma_x, (\sigma_y)_k = \sigma_y$

$$u(x, y) = \frac{1}{4\pi^2} \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \hat{u}_{jk} \exp(i\sigma_x x) \exp(i\sigma_y y)$$

$$\begin{cases} u_x = i\sigma_x u, & u_{xx} = (i\sigma_x)^2 u = -\sigma_x^2 u, & u_{xy} = -\sigma_x \sigma_y u \\ u_y = i\sigma_y u, & u_{yy} = (i\sigma_y)^2 u = -\sigma_y^2 u \end{cases}$$

$$\therefore Au_{xx} + Bu_{xy} + Cu_{yy} = 0 \Leftrightarrow -A\sigma_x^2 - B\sigma_x \sigma_y - C\sigma_y^2 = 0$$

- Characteristic polynomial

Dr. Hasan Ghasemzadeh

$$A\left(\frac{\sigma_x}{\sigma_y}\right)^2 + B\left(\frac{\sigma_x}{\sigma_y}\right) + C = 0$$

## Characteristic Equation

- Fourier analysis (discrete mode)

$$A\left(\frac{\sigma_x}{\sigma_y}\right)^2 + B\left(\frac{\sigma_x}{\sigma_y}\right) + C = 0 \Rightarrow \frac{\sigma_x}{\sigma_y} = \frac{-B \pm \sqrt{B^2 - 4AC}}{2A}$$

- Discrete mode

$$B^2 - 4AC \begin{cases} \geq 0, & \text{real } \left(\frac{\sigma_x}{\sigma_y}\right) \\ < 0, & \text{complex } \left(\frac{\sigma_x}{\sigma_y}\right) \end{cases}$$

Propagation/marching problems (sin/cos functions)

Growth/decay/propagation  
Exponential Growth/decay  
– pure imaginary ( $\sigma_x/\sigma_y$ )

Dr. Hasan Ghasemzadeh

# Characteristic Equation

- Fourier Transform (continuous spectrum)

$$\begin{cases} \hat{u}(\sigma_x, \sigma_y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} u(x, y) \exp(-i\sigma_x x) \exp(-i\sigma_y y) dx dy = Fu \\ i\sigma_x \hat{u}(\sigma_x, \sigma_y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{\partial u}{\partial x}(x, y) \exp(-i\sigma_x x) \exp(-i\sigma_y y) dx dy = F \frac{\partial u}{\partial x} \\ i\sigma_y \hat{u}(\sigma_x, \sigma_y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{\partial u}{\partial y}(x, y) \exp(-i\sigma_x x) \exp(-i\sigma_y y) dx dy = F \frac{\partial u}{\partial y} \end{cases}$$

- Integration by parts

$$\begin{aligned} F \frac{\partial u}{\partial x} &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{\partial u}{\partial x}(x, y) e^{-i\sigma_x x} e^{-i\sigma_y y} dx dy \quad \text{Fourier transform of } \frac{\partial u}{\partial x} \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{\partial}{\partial x} (ue^{-i\sigma_x x} e^{-i\sigma_y y}) dx dy - \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (-i\sigma_x) ue^{-i\sigma_x x} e^{-i\sigma_y y} dx dy \\ &\stackrel{\text{Dr. Hasan Ghasemzadeh}}{=} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} ue^{-i\sigma_x x} e^{-i\sigma_y y} \Big|_{-\infty}^{\infty} dy + i\sigma_x Fu = i\sigma_x \hat{u} \\ &= 0, \text{ if } u = 0 \text{ at } x \rightarrow \pm\infty \end{aligned}$$

# Characteristic Equation

- Classification by Fourier transform

$$\begin{aligned} \hat{u} = Fu &\Rightarrow \begin{cases} i\sigma_x \hat{u} = F \frac{\partial u}{\partial x}, \quad (i\sigma_x)^2 \hat{u} = F \frac{\partial^2 u}{\partial x^2} \\ i\sigma_y \hat{u} = F \frac{\partial u}{\partial y}, \quad (i\sigma_y)^2 \hat{u} = F \frac{\partial^2 u}{\partial y^2} \end{cases} \\ &\therefore Au_{xx} + Bu_{xy} + Cu_{yy} = 0 \Rightarrow \\ &\quad [A(i\sigma_x)^2 + B(i\sigma_x)(i\sigma_y) - C(i\sigma_y)^2] \hat{u} = 0 \end{aligned}$$

- Characteristic polynomial

Dr. Hasan Ghasemzadeh

$$A \left( \frac{\sigma_x}{\sigma_y} \right)^2 + B \left( \frac{\sigma_x}{\sigma_y} \right) + C = 0$$

# Fourier Analysis

- Particularly useful for system of equations with higher-order PDEs (avoid the construction of first-order PDEs)
- Example: Navier-Stokes equations

$$\begin{cases} u_x + v_y = 0 \\ uu_x + vu_y + p_x - (u_{xx} + u_{yy})/Re = 0 \\ uv_x + vv_y + p_y - (v_{xx} + v_{yy})/Re = 0 \\ i\sigma_x \hat{u} + i\sigma_y \hat{v} = 0 \\ iu\sigma_x \hat{u} + iv\sigma_y \hat{u} + i\sigma_x \hat{p} - [(i\sigma_x)^2 \hat{u} + (i\sigma_y)^2 \hat{u}] / Re = 0 \\ iu\sigma_x \hat{v} + iv\sigma_y \hat{v} + i\sigma_y \hat{p} - [(i\sigma_x)^2 \hat{v} + (i\sigma_y)^2 \hat{v}] / Re = 0 \end{cases}$$

Dr. Hasan Ghasemzadeh

# Fourier Analysis

- Characteristic equations

$$\begin{bmatrix} i\sigma_x & i\sigma_y & 0 \\ i(u\sigma_x + v\sigma_y) + (\sigma_x^2 + \sigma_y^2)/Re & 0 & i\sigma_x \\ 0 & i(u\sigma_x + v\sigma_y) + (\sigma_x^2 + \sigma_y^2)/Re & i\sigma_y \end{bmatrix} \begin{bmatrix} \hat{u} \\ \hat{v} \\ \hat{p} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

- Determinant = 0

$$-i(\sigma_x^2 + \sigma_y^2) \left[ i(u\sigma_x + v\sigma_y) + \frac{I}{Re} (\sigma_x^2 + \sigma_y^2) \right] = 0$$

first-derivative    second-derivative

- Consider only the highest-order derivatives

$$\frac{I}{Re} (\sigma_x^2 + \sigma_y^2)^2 = 0$$

Elliptic system (complex roots)

Dr. Hasan Ghasemzadeh