# M. J. Mirshojaeian Hosseini

Mechatronic Engineer

#### contact

# **education**

#52, Beheshti 30, Beheshti street Mashhad, Khorasan Razavi Iran

+98 (915) 308 6302 +98 (511) 842 7784

mj.mirshojaeian@gmail.com http://wp.kntu.ac.ir/aliyari/ fdi/people/alumni.html

#### languages

Farsi mother tongue English fluency Arabic Basic

#### Software

Matlab, SolidWorks FlowMaster, C++ Code Vision, Abaqus Automation Studio S7 Lite, Winproladder COMSOL & Latex

2011–2013	Master of Mechatronic Engineering	K.N.Toosi University of Technology, Tehran
	Design, Simulation and Control of an Electro	-Hydrostatic Actuator and Improve-
	ment of Its Performance	
	Superviser: Dr. Mahdi Aliyari Shoorehdeli	
2005–2010	Bachelor of Mechanical Engineering	Ferdowsi University of Mashhad, Mashhad
	Governing Equations of DC an AC Motors	

Superviser: Dr. Alireza Akbarzadeh Tootoonchi

### experience

2009-Now	FDI Lab, Electerical Engineering Faculty, K.N.Toosi University of Technology Tehran Research Assistant		
	Designing, simulating, controlling and developing electro-hydrostatic actuator for a dynamic load simulator. Detailed achievements:		
	<ul> <li>Researched generally on electro-mechanical, electro-hydraulic and electro-hydrostatic actuators</li> </ul>		
	<ul> <li>Finally electro-hydrostatic actuator was chosen for DYNAMIC LOAD SIM- ULATOR:</li> </ul>		
	<ul> <li>Designed electro-hydrostatic actuator</li> <li>Simulated electro-hydrostatic actuator by two methods:</li> </ul>		
	<ul><li>* multidisciplinary method</li><li>* mathematical method</li></ul>		
	<ul><li>Designed new controller method for electro-hydrostatic actuator</li><li>Developed a new hydraulic circuit for electro-hydrostatic actuator</li></ul>		
2009–2011	Faculty of Engineering, Ferdowsi UniversityMashhadResearch EngineerMashhad		
	Designed a novel DC motor characterizator. This new equipment has now been patented (Iran patent # 72956).		
2008–2009	Parallel Robot Group, Faculty of Engineering, Ferdowsi UniversityMashhadGroup MemberGenerated structural equations for AC servo motors.		
2006–2008	CAD/CAM Lab, Faculty of Engineering, Ferdowsi University Mashhad		
	Research Assistant Designed a USB communicated circuit for a DC servo motor and implemented STR control on that.		
Honour			
2013	Mechanical Engineering Faculty, K.N.Toosi University of Technology Receiving MSc in Mechatronic Engineering as the 1st rank student.		
2008	Microsoft Certified System Administrator (MCSA) MCP ID # 6027811		

Microsoft Certified System Administrator (MCSA), MCP ID # 6027811 2008 Microsoft Certified Professional (MCP) Microsoft Certified System Engineer (MCSE), MCP ID # 6027811

# communication skills

- 2012 **Oral Presentation** Electerical Engineering Faculty, K.N.Toosi University of Technology Presented the research I conducted for my Masters of Science degree.
- 2013 **Poster** Annual Research Exhibition of K.N.Toosi University of Technology, Tehran Presented the research I conducted for my Masters of Science degree.

# interests

**professional:** rehabilitation engineering, systems and control, bio engineering, fault detection and identification, system identification, simulation by collaborative methods, modeling by multidisciplinary and mathematical methods, hydraulic circuit design, intelligent controller design, system biology **personal:** hiking, cooking, climbing, running

# publications

#### **Journal Papers**

Mohammad Javad Mirshojaeian Hosseini, Mahdi Aliyari Shoorehdeli, "Analysis and examination of the factors contributing to rapidness of response time in non-linear model of electro-hydrostatic actuator," ISC Journal of Solid and Fluid Mechanics, 2013 (Accepted, In Farsi)

Mohammad Javad Mirshojaeian Hosseini, Soheil Alidoosti, Mahdi Aliyari Shoorehdeli, "Multidisciplinary modeling and position tracking control of an electro-hydrostatic actuator using a novel adaptive fuzzy-PID controller," ISA Transactions, 2013 (Under Review)

#### **International Conference Papers**

Mohammad Javad Mirshojaeian Hosseini, Soheil Alidoosti, Mahdi Aliyari Shoorehdeli, "Multidisciplinary modeling and position control of an electrohydrostatic actuation system using an adaptive PID controller based on neurofuzzy network", The 3rd International Conference on Control, Instrumentation and Automation, 2013 (Accepted)