RESEARCH ARTICLE

A Multiple Power Level Random Access Method for M2M Communications in LTE-A Network

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ABSTRACT

Access Control is an effective way to protect the radio access part of Long-Term Evolution-Advanced (LTE-A) network from the overload caused by a huge number of Machine Type Communication Devices (MTCD). A class of access control mechanisms is the Access Class Barring (ACB), which regulates the machine-to-machine (M2M) traffic in accordance with the available random access (RA) resources. In this paper, we extend the single power level ACB scheme to a multiple power level method in order to increase the number of successfully transmitted requests in the case of overload. Our analysis is based on the capture effect in the third step of RA procedure of the LTE-A system in which one of the transmitted requests by two or more co-tagged MTCDs, MTCDs which use the same preamble in the first step, can be decoded by the eNB. We first formulate the power level selection as an optimization problem assuming the perfect capture model without considering MTCDs’ energy budget. Then, to take into account MTCDs’ energy consumption, the scenario is extended for the Signal to Interference Ratio (SIR) based capture model. In addition, we investigate the advantages of the proposed multiple power level RA method on discriminating the access of MTCDs with different priorities. The numerical results show that using the optimal parameters, the RA throughput can be improved in comparison with the single power level system at the cost of slightly increasing MTCDs’ energy consumption and the complexity of RA procedure. Copyright © 2012 John Wiley & Sons, Ltd.

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1. INTRODUCTION

Machine-to-Machine (M2M) communications enable the connectivity between billions of Machine-Type Communication Devices (MTCD) in the context of the Internet of Things (IoT). In the IoT paradigm, MTCDs will be able to measure, analyse and deliver information in an autonomous manner with minimal human interaction. M2M solutions for remote monitoring show great market opportunities in many fields such as smart metering, health care, transportation, and industrial automation [1].

In order to achieve a ubiquitous connectivity of MTCDs, Long-Term Evolution (LTE) and LTE-Advanced (LTE-A) networks are envisaged to provide cost-effective solutions for the deployment of M2M applications [2].

In the LTE / LTE-A networks, unconnected MTCDs may get connected to the evolved-Node B (eNB) through the Random Access (RA) procedure. In the contention-based RA procedure, the Physical Random Access Channel (PRACH) is used to transmit orthogonal preamble codes. If two or more MTCDs select the same preamble code on the same PRACH opportunity simultaneously, they will grant and transmit their requests on the same Resource Blocks (RB) of Physical Uplink Shared Channel (PUSCH). In this case, it is probable that the eNB cannot detect the transmitted requests and hence the contending MTCDs could not successfully pass the RA procedure [3]. Due to the slotted ALOHA-based RA contention, the performance of RA is suffering from the collisions caused by a lot of connection requests of MTCDs which typically is greater than user equipments by orders of magnitude.

Collision in the RA procedure will waste the system resources, decreases MTCD’s energy, and increases the access delay. In order to control the RACH overload in the LTE/LTE-A caused by M2M communications, several proposals have been discussed in Third-Generation Partnership Project (3GPP) and different literature [4, 5, 6, 7]. Although, these overload control solutions mainly focus on barring requests of MTCDs or increasing the number of contention resources upon overload detection to enhance the performance of RA procedure. Providing more RA resources leads to rising the costs of resource usage; while barring more MTCDs increases the access delay.

In order to decrease the average access delay of MTCDs without increasing the number of contention resources,
in this paper, the advantage of the power capture effect is used to improve the success probability of MTCDs in the RA procedure. According to this effect, the transmitted request of one MTCD with a high enough transmission power will be detected by the eNB, while, it has collided with other MTCDs’ requests [9]. In order to benefit from the power capture effect, the number of contending MTCDs at each power level must be determined in accordance with the available RA resources. To do this, we formulate an optimization problem to find the optimum values of the ACB parameters and the corresponding selection probabilities for each power level. It is well known that the energy consumption of MTCDs is of paramount importance and depends on the specified application requirements [2,9]. By considering the energy consumption of battery-powered MTCDs, we aim to determine the transmission power at each power level in the signal to interference (SIR) based capture model. Beside the RA throughput enhancement, we also show that the power capture effect can be used to discriminate the access of MTCDs with different priorities which is important for emergency alarm notifications as a significant application of M2M communications. It is notable to mention that in the multiple power level RA method, the eNB computes and broadcasts the power levels and their corresponding probabilities in the RA procedure which may incur additional complexity in comparison with the single power level RA procedure. The main contributions of this paper include:

- We extend the single power level ACB scheme to a multiple power level scheme to enhance the throughput of RA procedure. We first compute the optimum transmission probability for each power level assuming a simple capture model in which the interference of lower power MTCDs does not affect the successful transmission of a higher power level transmission.
- Adopting a more realistic SIR-based capture model, we then take into account the interference of the lower power MTCDs and find the transmission power and the corresponding transmission probability for each level. We show that using the proposed scheme, the average access delay and the RA throughput are enhanced compared to the single power level ACB scheme.
- Finally, we use the multiple power level RA method for the emergency applications which require higher priority in channel access against the low priority applications.

The outline of the paper is as follow. In Section 2, the related works are reviewed. The system model is presented in Section 3. Section 4 is dedicated to the proposed RA method for the perfect capture model and the SIR-based capture model. Also, in this section, the priority point of view of the proposed RA method has been investigated. The performance of the proposed method is demonstrated in Section 5. Finally, conclusions are presented in Section 6.

2. RELATED WORKS

The deployment of a huge number of MTCDs in the LTE leads to the overload problem. There are various solutions for the overload control problem in literature, some of them have been summarized in [10]. The proposed solutions can be classified into two main categories: in the first, excessive access requests of MTCDs are barred and in the second, the number of contention resources in an overload condition is increased.

In the first category, 3GPP introduced some specific solutions to protect the radio access network of the LTE. In these solutions, the access of delay-tolerant MTCDs are barred upon overload detection. One suggestion by 3GPP working groups for the RACH overload is the ACB scheme [2]. In the ACB, the eNB broadcasts the barring probability and the barring timer to guide the MTCDs how to initiate the RA procedure. When an unconnected MTCD attempts to connect to the eNB, it uniformly selects a random number between 0 and 1. If the selected number is below the barring probability, it can initiate the RA procedure. Otherwise, it postpones its attempt for a random time. The barring timer determines the mean duration of access control. In the optimal dynamic ACB scheme, the eNB knows the number of active MTCDs in each RA procedure and hence can compute the optimum ACB barring factor taking into account the the number of RA resources. In [11, 12], the eNB is empowered with load estimation techniques to adjust the ACB factor in accordance with the optimal ACB in each RA procedure. In [13], a Proportional-Integral-Derivative (PID) controller is proposed to adjust the ACB factor in order to control the congestion level in the core network node. The authors of [14] apply the dynamic ACB factor to control the overload of MTCDs in both the radio access network and the core network of the LTE/LTE-A, simultaneously. 3GPP also specified the EAB for M2M communications, where individual applications can be controlled through broadcasting RA information called System Information Block (SIB) [3]. The performance of the EAB scheme for M2M communications and the optimal values of EAB parameters are analyzed in [15]. In addition to the EAB method, the specific backoff adjustment scheme for M2M communications has been introduced by 3GPP [7] where the requests of MTCDs are delayed in the case of overload. The authors in [16] investigated the throughput of the RA procedure in the LTE-A under different backoff timer. Although these works can control the congestion through barring the excessive access requests of MTCDs, they did not take into account the maximum acceptable delay of the barred MTCDs.

In the second category, the dynamic allocation of RA resources is introduced in [17], where the excessive
access requests are mitigated through allocating more RA resource. Authors in [13] used additional preambles to guarantee the access delay of emergency devices in an overload condition which improved the conventional RA procedure. In [6] the average number of successful transmissions increased through allocating more PUSCH to successfully detected preambles by the eNB. The number of contention resources is enhanced in [5] through a new codeword method. In this method, the MTCD selects one preamble on each RA sub-frame of a virtual frame. The virtual frame consists of some RA sub-frames that RA is performed over it. These approaches improve the throughput of the RA procedure at the cost of using more RA resources.

To decrease the access delay of MTCDs without increasing RA resources, we have offered a multiple power level RA method in this paper. The proposed method is based on the capture effect in the RA which previously evaluated for the slotted ALOHA [19, 20, 21, 22, 23] and 802.11 [24] networks. We show that the access delay and the throughput of RA can be reduced and improved in the case of the overload through the proposed method.

3. SYSTEM MODEL AND PROBLEM STATEMENT

We consider the Frequency Division Duplexing (FDD) mode of the LTE-A system. In this mode, there are some Random Access Opportunities (RAO) in each frame in accordance with FDD configurations [25]. Each frame composed of ten subframes with 1ms duration each one. The number of RA O in each frame determines the total number of RA resources in each frame as given by the multiplication of the number of PRACH subframes and the number of RA preambles. We use PRACH configuration index 6 as the typical configuration [7, 25], in which one PRACH subframe with 54 preambles is provided every 5ms. Notice that in this configuration, there are 54 preambles within one PRACH opportunity, the number of RA O is equal to the number of preambles for each RA procedure.

Fig. 1 shows the system model considered in this paper. Event-driven M2M applications such as secure alarm, health emergency notification, the location update, and remote control have been considered. In the assumed traffic model, each idle MTCD triggers with probability $\alpha$ to transmit the early sensing data. We model the traffic of each MTCD by a two-state Markov chain that its states represent active and idle modes of MTCD operation, see Fig. 2. In Fig. 2, $q_S$ refers to the probability of successfully transmitted requests among all active MTCDs.

There are $N_T$ MTCDs in the system where some of them are active. The active MTCDs include the new-triggered devices as well as the barred and unsuccessful devices from the previous RA procedure. The remaining MTCDs which are in the idle state called inactive devices. To initiate the connection setup, each active MTCD will draw a random number between $[0, 1]$ uniformly. The MTCD is allowed to start the RA procedure only if the drawing number is less than the ACB factor $q_{ACB}$ announced by the eNB. The MTCD which passed the ACB check, referred as the contending MTCD in this paper, initiates the multiple power level RA procedure. We do not consider a limit on the number of retransmission attempts and the back-off time interval before each transmission as in [26, 27]. That is, if the contending MTCD could not pass the RA procedure successfully, it continues the aforementioned process until its data is successfully received by the eNB.

In this paper we consider a single cell in which all MTCDs experience similar RA channel and configuration as in [19, 20, 21, 22, 23]. That is by comparing the SIRs, the powers of MTCDs which transmit simultaneously is the key factor in deciding which MTCD can capture the granted uplink resources in the RA procedure.

The multiple power level RA procedure is shown in Fig. 3. The considered RA procedure consists of four steps as similar to the contention-based RA procedure in the LTE-A [3]. In the proposed multiple power level RA method, in contrast to [3], each MTCD which receives the Random Access Response (RAR) message in the access-granting step successfully, selects its transmission power according to a given probability mass function. The MTCD which its transmission power is high enough in comparison with the interference caused by the transmissions of other
MTCDs on the same RBs can capture the channel in the third step of the RA procedure. In what follows, the steps of the proposed multiple power level method will be explained.

In step 1, the contending MTCD randomly selects one preamble from the M2M dedicated RA preambles. We define the contending MTCDs which select the same preamble as co-tagged MTCDs. Notice that the eNB can decode the received preamble while it has been transmitted by the co-tagged MTCDs. However in this step, the eNB cannot differentiate whether the preamble is chosen by more than one MTC device [28] [29]. We do not consider the channel conditions and power ramping factor on successful preamble detection in the first step of the RA procedure. Hence, the preamble transmission power is adjusted according to the maximum transmit power, \(P_{C_{MAX}}\), as described by 3GPP [30]. The preamble transmission power is considered to be high enough that can be detected by the eNB. In the next step, the eNB replies the corresponding RAR messages through the Physical Downlink Control Channel (PDCCH) to acknowledge the received preambles (see step 2 in Fig. 3). The RAR message contains some information to inform the contending MTCD about the index of received preamble, timing advance command, and the dedicated PUSCH for transmitting message 3. We assume that in the considered massive access scenario, sufficient downlink and uplink resources are available in the second and third steps of the RA procedure if all dedicated M preambles are detected successfully. A comprehensive study of the constraints on the connection establishment in the LTE from downlink and uplink resources point of view is presented in [31].

In step 3, each contending MTCD successfully received the RAR from the eNB, selects its transmission power from a set of the candidate power levels, \(\{p_1, p_2, \ldots, p_L\}\), with their associated probabilities, \(\{q_1, q_2, \ldots, q_L\}\), to transmit message 3. Without loss of generality, we assume that \(p_1 < p_2 < \ldots < p_L\). Message 3 indicates the purpose of connection setup by the MTCD which may be data transmission [28] [29] or scheduled request [3]. In this step, the co-tagged MTCDs receive the same RAR through the PDCCH and hence, transmit their data/scheduled-requests on the same PUSCH. In this case, in contrast to the preamble transmission in step 1, only one co-tagged MTCD can capture the channel if its transmission power is high enough in comparison with other co-tagged MTCDs’ interferences. It is worth noting that the advantage of the power capture effect is also used in the power ramping technique which has been introduced by 3GPP working group [32]. At last in step 4, the eNB acknowledges the successfully received data/scheduled-requests of step 3, as shown in Fig. 3 for the \(MTC_D_1\) that capture the channel. Those contending MTCDs which did not receive the corresponding message in step 4, attempt at the next PRACH opportunity.

In the massive access scenario, the RA procedure suffers from the collisions caused by the simultaneous transmissions of message 3 via the same granted RBs when two or more MTCDs select the same preamble in the RAR requests. Hence, two relevant capture models which are known as perfect model and SIR-based model are adopted for unconstrained and constrained energy budget scenarios in this paper, respectively, to evaluate the conditions that the simultaneous transmissions of message 3 in the eNB can be decoded. In the perfect model, \(MTC_D_i\) can transmit its data/scheduled-request among all other co-tagged \(MTC_D_j, j = 1, \ldots, L, j \neq i\), successfully if \(p_i > p_j\). While, in the SIR-based model, \(MTC_D_i\) can successfully accomplish the RA procedure if \(p_i\) be greater than the interference of other co-tagged MTCDs, as:

\[
p_i > \beta \left( \sum_{j=1, j \neq i}^L n_j p_j + (n_i - 1)p_i \right) \tag{1}
\]

where \(\beta\) denotes the minimum required SIR which can be detected by the eNB, \(n_j\) and \(n_i\) refer to the number of co-tagged MTCDs which select power level \(j\) and \(i\), respectively. In the multiple power level RA method, the eNB broadcasts the PRACH configuration index, a vector of transmission powers, and power level selection probabilities in each RA procedure.

The objective of this paper is to increase the successful transmissions of MTCDs while decreasing the access delay.
in the case of the overload. That is by proper selection of barring factors and the corresponding power levels, we can determine the proper number of contending MTCDs in each power level in order to maximize the RA throughput. This causes the number of barring MTCDs and hence the average access delay of MTCDs to be decreased in comparison with the single power level RA procedure.

4. PROPOSED MULTIPLE POWER LEVEL RANDOM ACCESS METHOD

In this section, we first derive the RA throughput of the proposed method in the perfect capture model. In this paper, the RA throughput refers to the expected number of MTCDs which passes the RA procedure successfully in each PRACH opportunity. Then, the proposed method has been extended to the SIR-based model. We use an adaptive method to determine the ACB factor and the corresponding transmission powers according to the number of active MTCDs. Finally, we discuss how the proposed method can be deployed to serve MTCDs with different priorities in a real scenario. In what follows we exploit the capture effect at the eNB to improve the performance of the RA procedure and don’t consider the successive interference cancelation which may also be used at the eNB.

4.1. Model 1: Perfect Capture Model

We first formulate the RA throughput of multiple power level RA procedure in the perfect capture model as an optimization problem and then the optimum values of the ACB factor and corresponding power levels selection probabilities are derived. By applying the optimum values of $q_i, i = 1, \ldots, L$, the number of contending MTCDs can be balanced between different power levels to maximize the RA throughput. Therefore, the optimum values of barring factors can be obtained through finding the desired number of contending MTCDs in each power level.

Let $S_i$ denote the RA throughput of the system with given $i$ power levels. The RA throughput of the system with the single power level is determined by the success probability of $n_1$ given MTCDs multiplied by the number of preamble, $M$. In this case, the success probability of MTCDs is the probability that only one out of $n_1$ contending MTCDs selects each preamble, named $m$, and others do not. That is $\binom{n_1}{1}(\frac{1}{M})(1 - \frac{1}{M})^{n_1 - 1}$. Then, $S_1$ simplifies to (2).

$$S_1 = n_1(1 - \frac{1}{M})^{n_1 - 1}.$$  \hfill (2)

For a system with two power levels where $p_2 > p_1$, the RA throughput is the sum of the throughput of the first power level provided that there is not any interference from the second power level, and the throughput of the second power level, as:

$$S_2 = S_1(1 - \frac{1}{M})^{p_2} + n_2(1 - \frac{1}{M})^{n_2 - 1}$$  \hfill (3)

This process can be continued to find $S_i$. In summary, for a system with given $L$ power levels, $S_L$ is given by:

$$S_L = S_{L-1}(1 - \frac{1}{M})^{p_L} + n_L(1 - \frac{1}{M})^{n_L - 1}$$  \hfill (4)

Assume that $n_i$ MTCDs select power level $i$. We can find $S_L$ as a function of $n_i, i = 1, \ldots, L$, in a recursive manner as in (5).

$$S_L = (1 - \frac{1}{M})^{(p_L - 1)} \rho_L$$  \hfill (5)

where $\rho_L = \sum_{j=1}^{L} n_j (1 - \frac{1}{M})^{\sum_{j=1}^{L} n_j}$. The objective is to find the optimal number of MTCDs which select power level $i, n_i^*$, such that $S_L$ is maximized. The $\frac{\partial}{\partial n_i}$ component of the gradient of $S_L$ with respect to $n_i$ is given by (6).

$$\frac{\partial S_L}{\partial n_i} = (1 - \frac{1}{M})^{\sum_{j=1}^{L} n_j - 1}(1 - \ln(\frac{M}{M - 1})\rho_L)$$  \hfill (6)

Now, by setting (6) to zero, we can find $n_i^*$ in a recursive manner as in (7).

$$n_i^* = \rho_i^* \left(1 - (1 - \frac{1}{M})^{n_i^* - 1}\right), \quad \rho_i^* = \frac{1}{\ln(\frac{M}{M - 1})}$$  \hfill (7)

where $n_i^* = \frac{1}{\ln(\frac{M}{M - 1})}$.

Lemma 4.1

$n_i^*, i = 1, \ldots, L$ is the unique global optimal point of $S_L$ in the perfect capture model.

Proof

See Appendix A. \hfill \Box

Also, the maximum RA throughput of a system with $L$ power levels, $S_L^*$, can be obtained by replacing the optimal values of $n_i^*$ and $\rho_i$, i.e. $n_i^*$ and $\rho_i^*$, in (5).

According to (7), $1 - \frac{1}{M}^{n_i^* - 1}$ is a decreasing term of $n_i^*$ and $n_i^* < n_i^* - 1$. Therefore, for high enough values of $i$ we will have $n_i \rightarrow 0$. That is $S_L^*$ reaches to $\frac{M}{\ln(\frac{M}{M - 1})} \approx M$, which can be considered as the upper bound for $S_L$.

Let $n_{act}$ be random variable denoting the total number of active MTCDs in each RA procedure. Assuming the traffic model of Fig. 2, the probability that each MTCD be in active state, $\Pi_{act}$, is given by (8). Also, the eNB can compute the expected value of the number of active MTCDs, $E[n_{act}]$, in each RA opportunity.

$$\Pi_{act} = \frac{\alpha N_T - S_L}{\alpha N_T}$$  \hfill (8)

Now, by using (8), $E[n_{act}]$ can be computed as in (9).

$$E[n_{act}] = N_T \Pi_{act}$$  \hfill (9)

In an overload condition, the expected number of active MTCDs is greater than the sum of the desired number
of contending MTCDs at all power levels, i.e., \( E[n_{act}] > \sum_{i=1}^{L} n_i^* \). In this case, \( q_{ACB} \) is used to block the excessive active MTCDs. Then, by obtaining the values of \( n_i^* \) and \( E[n_{act}] \) using (7) and (9), \( q_{ACB} \) and \( q_1 \) can be computed from (10) and (11) respectively to sustain \( n_i \) in each power level near to its optimum value.

\[
q_{ACB} = \min \left\{ 1, \frac{\sum_{i=1}^{L} n_i^*}{E[n_{act}]} \right\} \tag{10}
\]

\[
q_1 = \frac{n_i^*}{\sum_{i=1}^{L} n_i^*} \tag{11}
\]

As a special case, it should be noted that if \( L = 1 \), using (10) and (11) we have \( q_{ACB} = \frac{n_1^*}{E[n_{act}]} \), and \( q_1 = 1 \), which is the traditional single power level ACB scheme. In a lightly loaded condition where \( q_0 N_T < S_L^* \), we have \( q_{ACB} = 1 \). In this condition, by replacing \( n_i \) in (5) with \( q_i E[n_{act}] \), \( S_L \) can be found through solving (5), (8), and (9) numerically.

In the next step, we compute the average access delay of MTCDs using the obtained values for \( S_L \) and \( E[n_{act}] \) according to (5) and (9), respectively. In a system with \( L \) power levels, the access delay, \( d_L \), for the MTCD accounts for the time duration between the first transmission attempt and the final successfully reception by the eNB. It is noted that each active MTCD continues the RA procedure to successfully transmit its data/scheduled-request in the next RA opportunities. Also, the probability of successful transmission, \( q_{Sl} \), in each PRACH opportunity is the same and independent of previous attempts. Therefore, the number of retransmission attempts until the successful transmission is a random variable with geometric probability mass function that its expected value is given by \( \frac{1}{\bar{q}_L} \). Now, if \( T \) denotes the time interval between two consecutive PRACH opportunities, the average access delay, \( E[d_L] \), is given by the multiplication of \( T \) and \( \frac{1}{\bar{q}_L} \) as given in (12).

\[
E[d_L] = \frac{T}{\bar{q}_L} \tag{12}
\]

where the probability of successful transmission of the MTCD could be written as:

\[
q_{Sl} = \frac{S_L}{E[n_{act}]} \tag{13}
\]

According to (12), it can be found that the average access delay can be decreased through enhancing the probability of successful transmission of MTCD in each RA procedure. The perfect capture model describes the effectiveness of the proposed multiple power level RA procedure in a scenario in which the effects of MTCDs’ energy budget on the successful transmission and access delay have not been considered. To consider the MTCDs’ energy budget, the performance of the proposed method has been investigated for the SIR-based model in the next subsection.

\[\text{4.2. Model 2: SIR-based Model}\]

In this subsection, the RA throughput of the SIR-based capture model with \( L \) available power levels is computed. As mentioned earlier, a contending MTCD can transmit its data/scheduled-request successfully, if it can capture the channel among all other co-tagged MTCDs. In the SIR-based model, the channel is successfully captured by the MTCD with power level \( p_i \) if the following condition is satisfied.

\[
p_i > \beta \left( \sum_{j=1}^{i-1} n_j p_j + (n_i - 1)p_i + \sum_{j=i+1}^{L} n_j p_j \right) \tag{14}\]

The first, second, and third terms in the right hand side of (14) are the interferences caused by the transmissions of lower, the same, and higher power levels of co-tagged MTCDs, respectively. Notice that when one or more co-tagged MTCDs with power level \( j > i \) transmit the data/scheduled-request, transmissions of other co-tagged MTCDs with power level \( i \) will not be detected by the eNB as in the perfect capture model. The same also happens when \( j = i \) but the number of MTCDs with power level \( i \) is greater than one, i.e., \( n_i > 1 \). However, for \( j < i \), the number of co-tagged MTCDs determines the amount of incurred interference. This interference causes the probability of successfully decoding the transmitted data/scheduled-request from \( MTCD_i \) at the eNB to be decreased. For a system with \( L \) power levels, in order to compute the probability of failure in the decoding of \( MTCD_L \)’s data/scheduled-request at the eNB, denoted by \( q_{K_L} \), we continue as follows. Define \( K_L \) as a set of all vectors satisfying condition (15) \[\text{(21)}\]:

\[
K_L = \left\{ \mathbf{k} = [k_1 k_2 ... k_{L-1}] \mid \beta \sum_{j=1}^{L-1} k_j p_j > p_L \right\} \tag{15}\]

where \( \mathbf{k} = [k_1, k_2, ..., k_{L-1}] \) and \( k_i \) denote a specific vector of \( K_L \) and the number of MTCDs which use power level \( p_i \) respectively. It is noted that all MTCDs of \( \mathbf{k} \) select the same preamble in the first step of RA procedure. The occurrence probability of a specific \( \mathbf{k} \), \( q_{K_L} \), can be obtained from (16).

\[
q_K = \prod_{j=1}^{L-1} f(k_j; n_j, \frac{1}{M}) \tag{16}\]

where \( f(k_j; n_j, \frac{1}{M}) = \binom{n_j}{k_j} \left(\frac{1}{M}\right)^{k_j} \left(1 - \frac{1}{M}\right)^{n_j - k_j} \) is the binomial probability mass function. Since \( q_{K_L} \) is the probability of all vectors like \( \mathbf{k} \) which satisfying condition (15), this probability is equivalent to the sum of \( q_K \) as:

\[
q_{K_L} = \sum_{\mathbf{k} \in K_L} q_K \tag{17}\]
Now, by applying (17), the throughput in (4) can be found for the SIR-based model as given by (18).

\[ S_L = S_{L-1}(1 - \frac{1}{M})^{n_L} + n_L(1 - \frac{1}{M})^{n_L-1}(1 - q_{K_L}) \]  

(18)

\( 1 - q_{K_L} \) in (18) determines the probability of successfully decoding the transmitted data/scheduled-request from MTCD with power \( L \) at the eNB. According to (18), the first term is the throughput from transmissions of all co-tagged \( MTCD_i \) for \( i < L \). The second term indicates the throughput of \( MTCD_i \)'s transmission while the imposed interference from other co-tagged \( MTCD_i \), that \( i < L \) is \( \beta \) times lower than the transmission power of \( MTCD_L \).

According to (18), \( S_L \) can be found as the function of \( n_i,i = 1, \ldots, L, \) and \( q_{K_L} \) in a recursive manner as in (19).

\[ S_L = \sum_{i=1}^{L} n_i(1 - \frac{1}{M})^{\sum_{j=0}^{i-1}}(1 - q_{K_i}) \]  

(19)

Since \( S_L \) is a function of both \( p_i \) and \( n_i \), we need to find the optimum values of \( p_i \) and \( n_i \) to maximize \( S_L \).

High transmission power or greater number of contending MTCDs in each power level leads to more energy consumption of MTCDs. To consider the energy efficiency issue, the MTCD’s energy budget in each RA procedure can be bounded. Let \( \mathcal{E} \) be the random variable denoting the energy consumption of the MTCD in each RA procedure.

We define \( \mathbb{E}[\mathcal{E}] \) as the expected energy consumption in each RA procedure as given by (20).

\[ \mathbb{E}[\mathcal{E}] = \sum_{i=1}^{L} n_i \mathcal{E}_i \]  

(20)

where \( \mathcal{E}_i \) is the energy consumption of the MTCD with power level \( p_i \) and is obtained through the multiplication of \( p_i \) and the duration of one PRACH opportunity, \( T_i \), i.e., \( \mathcal{E}_i = p_i T_i \). Since the preamble transmission power is considered to be constant for all MTCDs and for all RA opportunities, we just consider the energy consumption of transmitting message 3 in (20) and ignore the energy usage of the first step of RA procedure.

Now, the problem of maximizing \( S_L \) subject to the expected energy consumption constraint can be formulated as follows:

\[ \max_{n_1, \ldots, n_L, p_1, \ldots, p_L} S_L \]  

subject to \( p_{i-1} \leq p_i, \quad i = 2, 3, \ldots, L, \)  

\[ \mathbb{E}[\mathcal{E}] \leq \mathcal{E}_0 \]  

(23)

where (22) states that the amount of transmission power is increased by increasing the power level index. Constraint (23) ensures that the expected value of MTCDs’ energy consumption is not greater than the determined threshold, \( \mathcal{E}_0 \). By increasing \( \mathcal{E}_0 \), the differences between power levels are increased. This causes \( q_{K_L} \) to be decreased and hence, \( S_L \) to be increased. For a high enough value of \( \mathcal{E}_0 \), there are not any interference from the transmissions of lower power levels, i.e., \( q_{K_L} = 0,i = 2, \ldots, L \). In this case, \( n_i \) is equal to what has been obtained in (7), and the RA throughput of the system is reached to the throughput of the perfect capture model. For the minimum value of \( \mathcal{E}_0 \), i.e., \( \mathcal{E}_0 = p_1 T_1 \), by replacing (20) in constraint (23), we have \( n_i = 0 \) for \( i > 1 \); which concludes the single power level RA procedure.

For other values of \( \mathcal{E}_0 \), variables that should be determined in (21)-(23) are \( n_1 \ldots n_L \) and \( p_2 \ldots p_L \), as the desired integer and real positive numbers respectively. The value of \( p_1 \) is considered to be as the same as the preamble transmission power. Since the formulated problem in (21)-(23) is a nonlinear problem with mixed discrete and continuous variables, we use Genetic algorithm to solve it in an intelligent exhaustive search manner.

In the following, the relationship between \( n_i,i = 1, \ldots, L \) and \( p_i,i = 1, \ldots, L \), is illustrated for the special case of \( L = 2 \) in (21)-(23). In this case, from (15) and (16) we have \( k_1 \geq \frac{p_1}{p_2} \) and \( q_{K} = f(k_1; n_1, \frac{1}{M}) \), respectively. Hence, using (17), the probability of failure in the decoding of \( MTCD_i \)'s data/scheduled-request at the eNB can be computed as given in (24).

\[ q_{K_i} = \sum_{k_1=0}^{n_1} f(k_1; n_1, \frac{1}{M}) \]  

(24)

Notice that \( k_1 \) in (24) is an integer number and hence \( p_2 \) can be represented by \( p_2 = \beta p_1 \) where \( c \) is an integer. If \( p_2 \) has been replaced by \( \beta p_1 \) in (24), it can be found that \( 1 - q_{K_i} \) is equivalent to \( Pr(k_1 \leq c) \); which is the Cumulative Distribution Function (CDF) of binomial distribution. The CDF of binomial distribution, \( F(c; n_1, \frac{1}{M}) \), can be substituted with the regularized incomplete beta function, \( I_{w_1}(n_1 - c, c + 1) \), where \( I_{w_1}(a,b) \) is defined as \( \frac{B(x;a,b)}{B(a,b)} \) and \( B(x;a,b) \) and \( B(a,b) \) are incomplete and complete beta functions respectively. Therefore, the problem in (21)-(23) can be represented for \( L = 2 \) by substituting \( p_2 \) and \( 1 - q_{K_i} \) with \( c \beta p_1 \) and \( I_{w_1}(n_1 - c, c + 1) \) respectively, as follows:

\[ \max_{n_1, n_2, c} S_2 = n_1(1 - \frac{1}{M})^{n_1+n_2-1} + n_2(1 - \frac{1}{M})^{n_2-1}I_{w_1}(n_1 - c, 1 + c) \]  

(25)

subject to \( T(n_1p_1 + n_2c \beta p_1) \leq \mathcal{E}_0 \),  

(26)

where \( n_1, n_2, \) and \( c \) are integer numbers. According to the property of the regularized incomplete beta function, it can be inferred that \( I_{w_1}(n_1 - c, 1 + c) \) is monotonically increasing function of \( c \) and hence of \( p_2 \) while it is monotonically decreasing of \( n_1 \). This means that the imposed interferences from \( MTCD_1 \)'s transmissions can be mitigated by decreasing the number of contending \( MTCD_1 \) or increasing the transmission power \( p_2 \). Also, according to the objective function in (25), the value of
\( p_2 \) only determines the amount of incurred interference. Therefore, the RA throughput can be enhanced by increasing the transmission power \( p_2 \). In order to increase the transmission power \( p_2 \), we can search for the maximum value of \( c \) satisfying constraint (26) with given values of \( n_1 \) and \( n_2 \). Therefore, the objective function in (25) can be expressed in terms of two variables \( n_1 \) and \( n_2 \); which limit the search space to a small feasible region. Due to the limited search region, the optimization problem in (25)-(26) can be solved by searching all possible values of \( n_1 \) and \( n_2 \). \( n_1, n_2 \in \{1,...,M\} \). After solving the optimization problem, the values of \( q_{ACB}, q_i \), and \( E[d_k] \) can be computed using (10), (11), and (12) respectively.

\[ S_{L,i} = n_i(1 - \frac{1}{M})^{L_{i,n} - 1}(1 - q_{K_i}) \quad (27) \]

According to (27) for \( q_{K_i} = 0 \) and \( n_i = n_i^* \), \( S_{L,i} \) would be equal to the number of successfully transmitted requests from the \( i^{th} \) power level in the perfect capture model at the optimal RA throughput. In this case, \( S_{L,i} \) is denoted by \( S_{L,i}^* \).

Due to the various obtained throughput for different power levels in (27), the proposed RA procedure can be used to discriminate among MTCDs with different priorities. Since MTCDs with higher power levels consume more energy in comparison to MTCDs with lower power levels, in what follows we find the required condition to guarantee the priority of these MTCDs in the RA procedure. We continue this study for a system with two power levels, however, it can be extended to deal with multiple power level system. In order to guarantee the number of successfully transmitted requests of the second power level to be more than a predefined threshold \( \Gamma_0 \), the optimization problem in (25)-(26) can be revised by considering the condition of \( S_{L,2} \geq \Gamma_0 \) as follows:

\[ \max_{n_1,n_2,c} S_2 = n_1(1 - \frac{1}{M})^{n_1+n_2-1} \]

\[ n_2(1 - \frac{1}{M})^{n_2-1}I_{n_2,1}(n_1 - c, 1 + c) \quad (28) \]

\[ \text{s.t.} \quad \frac{T(n_1 p_1 + n_2 c \Omega_0 p_1)}{n_1 + n_2} \leq \Gamma_0, \quad (29) \]

\[ n_2(1 - \frac{1}{M})^{n_2-1}I_{n_2,1}(n_1 - c, 1 + c) \geq \Gamma_0, \quad (30) \]

where \( S_{2,1} \) and \( S_{2,2} \) are \( n_1(1 - \frac{1}{M})^{n_1+n_2-1} \) and \( n_2(1 - \frac{1}{M})^{n_2-1}I_{n_2,1}(n_1 - n_1, 1 + n_1) \) respectively. The optimization problem in (28)-(30) can be solved numerically to find the optimum values of \( n_1 \) and \( n_2 \) at feasible points. Notice that the optimum value of \( c \) is obtained by replacing different values of \( n_1 \) and \( n_2 \) in (29) to find the maximum value of \( \Gamma_0 \) which satisfy this inequality. This optimization problem can be simplified to the perfect capture model when \( \delta_0 \) is high enough. Since in this case \( S_2 \) has a single global maximum, see Lemma 1, the RA throughput of the system for \( \Gamma_0 < S_{2,2} \) reaches to \( S_{2,2} \) and the optimum values of \( n_1 \) and \( n_2 \) are computed using (7). If \( \Gamma_0 > S_{2,2} \), the optimum value of \( n_2 \) is computed through solving \( n_2(1 - \frac{1}{M})^{n_2-1} = \Gamma_0 \), numerically. Then, the optimum value of \( n_1 \) can be found by substituting the optimum value of \( n_2 \) into the objective function in (28) and searching for all possible values of \( n_1 \) which maximize (28). It is noted that the maximum value of \( \Gamma_0 \) equals to the RA throughput of the single power level system which is \( S_1^* \).

Notice that considering the priority of MTCDs with higher power levels may lead to the decrease in the number of total successfully transmitted requests in the system as expected at the optimal point. This happens when the number of transmitted requests from the higher power levels is greater than its optimum value.

### 5. PERFORMANCE EVALUATION

In this section, the performance of the proposed multiple power level RA procedure has been compared with the single power level RA or the traditional ACB scheme by simulation and analysis. The results discussed in four subsections including: the perfect capture model, the SIR-based capture model, the priority point of view, and the implementation issues. We consider a scenario in which the eNB broadcasts the required parameters for the RA procedure, i.e., \( q_{ACB} \) and \( q_i \). Then, each active MTCD initiates the RA procedure with probability \( q_{ACB} \). In the considered RA procedure, each contending MTCD selects the \( n_i^{th} \) preamble in the first step and the \( n_2^{th} \) power level in the third step of RA procedure with probability \( \frac{1}{M} \) and \( q_i \) respectively, to transmit the request to the eNB. Values of \( q_{ACB} \) and \( q_i \) are computed according to what has been discussed for the perfect capture model and the SIR-based capture model in subsections 4.1 and 4.2, respectively.

In the simulated scenario, we assume that the arrival probability of MTCDs is 0.003 and the eNB is able to estimate the number of active MTCDs in each RA procedure. We should note that since each MTCD continues its access attempts until it could successfully transmit its request, the number of access attempting requests in each RA procedure is much greater than the expected new access attempts. The simulation results are averaged over 5000 RA runs. The values of the simulation parameters are summarized in Table 1.
Table I. System parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Details</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$M$</td>
<td>Number of preambles</td>
<td>54</td>
</tr>
<tr>
<td>$P_1$</td>
<td>Reference Power level for $L_1$</td>
<td>23dBm</td>
</tr>
<tr>
<td>$\alpha$</td>
<td>The arrival probability of MTCDs</td>
<td>0.003</td>
</tr>
<tr>
<td>$T$</td>
<td>time interval between two PRACH opportunities</td>
<td>5ms</td>
</tr>
<tr>
<td>$T_1$</td>
<td>Duration of one RA procedure</td>
<td>1ms</td>
</tr>
</tbody>
</table>

In what follows, the performance of the proposed multiple power level RA method is evaluated in terms of the RA throughput and the average access delay of MTCDs. It is shown that the performance metrics can be improved at the cost of slightly increasing the energy consumption of MTCDs.

5.1. Performance results of the perfect capture model

In this subsection, the performance of the proposed RA procedure has been investigated for the perfect capture model. In Fig. 4 and its corresponding contour curves in Fig. 5, the RA throughput of the system with two power levels for different number of contending MTCDs at each power level are depicted. For analytical results, the RA throughput is obtained by substituting values of $n_1$ and $n_2$, $n_1,n_2 \in \{5,10,\ldots,M\}$, in (5). The maximum value of RA throughput happens at the values which are expected by (7).

In Fig. 6, the performance of the proposed RA procedure in the perfect capture model against different number of MTCDs is shown for $L = 1,2,3,4$. For the analytical results, the RA throughput for different values of $L$ can be found according to what has been discussed in section 4.1. We find from Fig. 6 that $S_L$ is greater than $S_{L-1}$, emphasizes that the achievable RA throughput is increased with the number of power levels. In addition, $S_L$ in each power level has been increased by increasing the number of MTCDs until it reaches to its maximum value for each power level. As previously mentioned, the maximum RA throughput of each power level happens in an overload condition where $N_T > \frac{S_L}{\alpha}$. If $N_T < \frac{S_L}{\alpha}$, $S_L$ has a value between $S_{L-1}$ and $S_L$ as shown in Fig. 6. The circle markers in Fig. 6 show the values of $N_T$ where $N_T = \frac{S_L}{\alpha}$ for $L = 2,3,4$. These values of $N_T$ can be used by the eNB to determine the number of power levels in accordance with the total number of MTCDs. This means that in a lightly loaded condition, the proposed RA procedure can be switched to the lower power levels in order to decrease the MTCDs’ energy consumption. From the resource efficiency point of view, we can notice to the ratio of the RA throughput values to the total number of possible accommodated requests using $M = 54$ preambles. According to Fig. 6, the resource efficiency is equal to 0.37 for $L = 1$, 0.54 for $L = 2$, 0.63 for $L = 3$, and 0.69 for $L = 4$.

Fig. 7 compares the average access delay of MTCDs in the perfect capture model for different values of $L, 1 \sim 4$. In this figure, the value of $E[d_L]$ is derived using (12). We find from Fig. 7 that $E[d_L]$ increases linearly when the total number of MTCDs is increased. However, the rate of increasing for $L = 1$ is greater than that for $L = 2,3,4$. This indicates that by applying more power levels in an overload condition, the RA delay can be mitigated compared to the traditional single power level RA scheme.

5.2. Performance results of the SIR-based capture model

Here, the performance of the proposed method while bounding the energy budget of MTCDs is investigated for the SIR-based capture model. In the following results, the optimum values of RA parameters, i.e., $n_1,\ldots,n_L$ and $p_2,\ldots,p_L$, are computed by solving (21)-(23). We use
The average access delay of the MTCD in the SIR-based capture model against different values of $N_T$ for $L = 1, 2, 3, 4$ is shown in Fig. 9. According to this figure, $E[d_L]$, the average access delay for this model is computed using (12).

The throughput of the RA procedure in the perfect capture model against different values of $E_0$ for $N_T = 15000$, $\beta = 1.2$, and $L = 1, 2, 3, 4$ is shown in Fig. 8. This figure shows that for the minimum value of $\delta_0$, i.e., $T_1p_1 = 0.19mJ$, the RA throughput of the system with 2, 3, and 4 power levels is the same with a single power level scheme. Also, this situation happens for $\delta_0 = 0.25mJ$ where the RA throughput of the system with 4 power levels is equal to the system with 3 power levels. On the other side, the RA throughput can be increased up to its maximum value through more energy consumption. The maximum value of $S_2$ in the SIR-based capture model has the same value for the perfect capture model which is demonstrated by the dashed lines in Fig. 8. The average access delay of MTCDs against different values of $\delta_0$ for $L = 2, 3, 4, \beta = 1.2$, and $N_T = 15000$ is shown in Fig. 9. According to this figure, $E[d_L]$ is decreased at the cost of more energy consumption. In addition, for a given MTCD’s energy budget, the average access delay is decreased by increasing the number of power levels.
this case the interference caused by the transmissions from the first power level on MTCDs\(_2\) could be overcomed. The maximum and the minimum values of \(E[d_2]\) are shown with circle markers in Fig. 10.

![Figure 10. The average access delay of the MTCD in the SIR-based capture model against different values of \(\beta_0\) for \(N_T = 15000\) and \(\beta = 1.2, 2.2, 3.2\).](image)

### 5.3. Performance results of the priority based multiple power level RA method

In this section, it is shown that the proposed method can be used to provide different priorities for MTCDs with distinct two power levels. In this simulation, the optimum values of \(n_1\) and \(n_2\) have been obtained by solving (28)-(30) numerically. Also, for the analytical results, the number of successfully transmitted requests of each power level is computed using (27).

The average number of successfully transmitted data/scheduled-requests of each power level in the SIR-based capture model is shown in Fig. 11 for \(L = 2\) against different values of \(\beta_0\). In this figure, the value of \(\Gamma_0\) is considered to be 16. According to this figure, we find that \(S_2\) is an increasing function of \(\beta_0\) as it is expected. Also, we note that the values of \(S_{2,1}\) and \(S_{2,2}\) are not necessarily an increasing function of \(\beta_0\) at the optimum RA throughput. Furthermore, we note that \(S_{2,2}\) is greater than the determined threshold which indicates the priority of MTCDs of the second power level against MTCDs of the first power level in the RA. In addition, for the high enough values of \(\beta_0\), \(S_{2,1}\) and \(S_{2,2}\) are reached to their optimal values in the perfect capture model, \(S_{2,1}^0\) and \(S_{2,2}^0\).

In Fig. 12, we show the effect of \(\Gamma_0\) on the number of successfully decoded requests from the first and second power levels of the system with two power levels. We find that for \(\Gamma_0 < S_{2,2}^0\), i.e., \(\Gamma_0 < 18.32\), the values of \(S_{2,1}^0\) and \(S_{2,2}^0\) are equal to their expected optimal values, \(S_{2,1}^0\) and \(S_{2,2}^0\) respectively, which leads to the maximum RA throughput. In this case, the value of \(\Gamma_0\) does not impose additional constraint on the problem. However, if \(\Gamma_0 > 18.32\), the value of \(S_{2,2}\) is increased linearly by increasing \(\Gamma_0\) to ensure that the number of successfully transmitted requests from the second power level meet the imposed constraint. In this case the number of successfully transmitted requests from the first power level is decreased.

![Figure 11. The average number of successfully transmitted requests of each power level for the system with two power levels against different values of \(\beta_0\) for \(N_T = 15000\), \(\beta = 1.2\), and \(\beta = 3.2\).](image)

![Figure 12. The average number of successfully transmitted requests of each power level for a system with two power levels against different values of \(\Gamma_0\) for \(N_T = 15000\), \(\beta = 1.2\), and \(\beta = 3.2\).](image)

### 5.4. Implementation issues

In the analysis of the proposed multiple power level RA scheme we consider some simplifying assumptions. In this subsection, we provide the simulation results of the multiple power level RA scheme considering some implementation issues. In these simulations, we consider the maximum allowable number of MTCDs’ retransmission attempts, the probability of successful preamble detection, the accuracy of the estimator at the
eNB, and the constraints on connection establishment in the LTE.

A. Maximum number of retransmission attempts

According to the 3GPP specifications, each collided MTCD should reattempt for the RA procedure after a random backoff time if the maximum number of retransmission attempts has not been reached [3]. In our analysis we do not consider a limit on the number of retransmission attempts and the back-off time before each transmission. In what follows, we provide the simulation results of the proposed method against different values of the maximum number of retransmission attempts which is denoted by \( R_{\text{max}} \) as in [26].

We consider a scenario of the perfect capture model in which each collided MTCD will wait for a random number of RA opportunities that selected according to a uniform probability distribution between 0 and \( W_{\text{max}} \). The value of \( W_{\text{max}} \) is set to be 20 RA opportunities. Also, if the maximum number of retransmissions attempts is reached, the collided MTCD will give up the RA procedure and will return to the idle state until new data arrival. Notice that each collided MTCD will become active after a backoff duration and perform the ACB check to participate in the RA procedure according to what has been discussed in section 3.

The average access delay of MTCDs against different values of \( R_{\text{max}} \) for \( L = 1 \) and \( L = 2 \) is shown in Fig. 13. As it is expected, by increasing \( R_{\text{max}} \), most of the MTCDs remain backlogged and hence experience more access delay as it is shown for \( E[d_1] \) and \( E[d_2] \) in Fig. 13. The maximum MTCDs’ access delay happens in the case where there is no limit for retransmission attempts, i.e., \( R_{\text{max}} = \infty \). In this case, the values of \( E[d_1] \) and \( E[d_2] \) can be computed using (12) as 2.07 and 0.92 respectively; which are demonstrated by the dashed lines in Fig. 13. When \( R_{\text{max}} = 0 \), the collided MTCDs do not retry to transmit their data/scheduled-requests. This causes the contending MTCDs remain active with probability \( 1 - P_{\text{ACB}} \) and return to the idle state with probability \( P_{\text{ACB}} \). Hence, by replacing \( q_{\text{ACB}} \) with \( q_{\text{ACB}} \), the probability that each MTCD be in active state, \( P_{\text{act}} \), would be equal to \( \frac{\alpha}{\alpha + q_{\text{ACB}}} \). Then, by substituting the value of \( P_{\text{act}} \) in (9) and by solving (9) and (10), we can find the values of \( q_{\text{ACB}} \) and \( E[n_{\text{act}}] \) as 1 and 44.86 for both scenarios of \( L = 1 \) and \( L = 2 \). In this case, the expected number of contending MTCDs is equal to \( E[n_{\text{act}}] \) for \( L = 1 \) and \( L = 2 \) because of \( q_{\text{ACB}} = 1 \). Since \( q_{\text{ACB}} = 1 \) and \( R_{\text{max}} = 0 \), there is no backlogged MTCDs and the average access delay is equal to the time period of one PRACH subframe, i.e., \( E[d_1] = 5\text{ms}, L = 1, 2 \). Also, it is worth to mention that the average access delay in a system with two power levels is less than the single power level scheme.

B. The effect of estimation and unsuccessful preamble detection at the eNB

So far, it is assumed that the eNB knows the number of active MTCDs in each PRACH opportunity and there is no error in detecting the received preambles by the eNB at the first step of the RA procedure. However, in a practical scenario of M2M communications over LTE network, the eNB may not be able to detect all transmitted preambles by the MTCDs and should estimate the number of active MTCDs in each PRACH opportunity. Regarding these implementation issues, we have simulated and compared the RA throughput of the single power level and two power level schemes for three different scenarios: the RA with the perfect estimator and detector (ideal scenario), the RA with the imperfect detector, and the RA with the imperfect estimator. Simulation results have been shown in Fig. 14 for \( R_{\text{max}} = \infty, W_{\text{max}} = 0 \).

In the imperfect detection scenario, we assume that the eNB cannot detect the transmitted preambles by the MTCDs with probability \( q_e \). Fig. 14 shows that at the detection error of \( q_e = 0.2 \), the achieved throughput of both single power level and two power level schemes are almost %20 less than their corresponding ideal throughput. We note that in the proposed multiple power level RA method, only one co-tagged MTCDs may accomplish the RA procedure. Hence, each detected preamble by the eNB may imply just one successful transmission at the end of RA procedure. Therefore, for large number of MTCDs, the error in preamble detection leads to the reduction in the RA throughput proportionally. For \( N_T < 5000 \), due to the lower number of selected preambles, there is not a significant difference between the ideal throughput and the other scenarios for \( q_e = 0.2 \).

To investigate the effect of estimating the number of active MTCDs at the eNB, we use the estimation technique of [22] in each RA procedure. In this technique, at the first, the eNB counts the number of idle preambles in the \( i^{th} \) PRACH opportunity and divides it by \( M \) to compute the probability that one preamble remains idle, \( q_{\text{idle}} \). Then, by considering the value of \( q_{\text{idle}} \), the number of contending MTCDs which is denoted by \( C_i \), can be computed as follows [27].

![Figure 13. The average access delay of each MTCD in the perfect capture model against different values of \( R_{\text{max}} \) for \( L = 1, 2 \) and \( N_T = 15000 \).](image)
The RA throughput of the perfect capture model [27]:

\[ C_i = \frac{\ln(q_{ACB,i})}{\ln(M)} \]

Now, the eNB can compute the number of active MTCDs in the \((i + 1)\text{th}\) PRACH opportunity from \(C_i\) and \(q_{ACB,i}\) as follows [27]:

\[ \hat{n}_{act,i+1} = \frac{C_i}{q_{ACB,i}} \]

Also, according to (10) and by using the value of \(\hat{n}_{act,i+1}\), the eNB updates the ACB factor in the \((i + 1)\text{th}\) PRACH opportunity as given by:

\[ q_{ACB,i+1} = \min\left\{1, \frac{\sum_{i=1}^{L} n_i^*}{\hat{n}_{act,i+1}}\right\} \]

The number of contending MTCDs can be controlled by broadcasting the updated value of \(q_{ACB}\) by the eNB in each RA procedure after estimation. As it is shown in Fig. 14, the RA throughput of the single and two power level schemes using this estimation technique follow the corresponding ideal scenario where the proposed multiple power level scheme outperforms the single power one.

![Figure 14. The RA throughput of the perfect capture model against different values of \(N_p\) for three considered scenarios when \(W_{\text{max}} = 0, R_{\text{max}} = \infty\), and \(L = 1, 2\).](image)

C. Constraints on connection establishment

Connection establishment in the LTE suffers from the limited amount of the resources available in downlink and uplink. This causes all contending MTCDs which successfully pass the first step of RA procedure, can not be served by the eNB. That is, there is not sufficient resources in the PUSCH, PDCCH, and Physical Downlink Shared Channel (PDSCH) for the traffic generated from the selected preambles by the MTCDs. To show the performance of the multiple power level RA method when there are constraints on the resources of uplink and downlink, we consider a simple scenario of the perfect capture model in which the number of contending MTCDs in each PRACH opportunity is limited in accordance with the available resources. Let \(\lambda_0\) denote the allowable number of contending MTCDs in each PRACH opportunity that can be served by the eNB. In order to sustain the number of contending MTCDs around \(\lambda_0\), it is assumed that the eNB computes the ACB factor using the value of \(\lambda_0\), and broadcasts it in each PRACH opportunity. Therefore, by considering \(\lambda_0\), \(q_{ACB}\) would be equal to \(\min\{1, \frac{\lambda_0}{\hat{n}_{act}}\}\). We do not consider the available number of preambles for computing the value of \(q_{ACB}\). The parameters of this simulation are as follows: \(N_T = 15000\), \(M = 54\), \(R_{\text{max}} = \infty\), \(W_{\text{max}} = 0\).

Fig. 15 shows the RA throughput of the system with \(L = 1, 2, 3\) power levels against different values of \(\lambda_0\). Notice that the RA throughput of the system with \(L\) power levels can be computed by replacing \(n_i\) in (5) with the multiplication of \(q_i\) and the number of contending MTCDs, i.e., \(q_{ACB}E[n_{act}]\). As it is shown in Fig. 15, the RA throughput of the system with two and three power levels outperform the single power level scheme when \(\lambda_0\) is almost greater than 15. Also, as it is expected, the maximum RA throughput of the system with \(L\) power levels happens at the values that the total number of contending MTCDs is equal to \(\sum_{i=1}^{L} n_i\); which are equal to 53.5, 87.31, and 112.37 for \(L = 1, L = 2, \) and \(L = 3\).

![Figure 15. The RA throughput of the perfect capture model against different values of \(\lambda_0\) for \(N_T = 15000\), \(M = 54\), \(R_{\text{max}} = \infty\), \(W_{\text{max}} = 0\), and \(L = 1, 2, 3\).](image)

6. CONCLUSION

We proposed the multiple power level RA method to improve the performance of the RA throughput of M2M communications in the LTE/LTE-A network. At first, the optimum selection probability of each power level is derived based on the perfect capture model. Then, by considering the constrained energy budget of MTCDs, we extend the results for the SIR-based capture model. The proposed method has been evaluated for different numbers of MTCDs and different values of MTCD's...
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Z. Alavikia, and A. Ghasemi

energy budget in the perfect capture model and the SIR-based capture model, by simulation. Moreover, we show that by considering the required condition, the proposed method can be used to prioritize the access of MTCDs. The results show that the multiple power level RA method can enhance the average number of successful transmissions and decrease the average access delay of MTCDs at the cost of more energy consumption of MTCDs and more computations at the eNB. These advantages of the multiple power level RA method makes it suitable for emergency situations such as the power grid blackout. For future work, we will investigate the effects of RA channel properties, i.e., noise and fading effects, on successful transmissions at each power level.

A. THE PROOF OF LEMMA 1

This Lemma is proved by checking whether \(n_i^*, i = 1, \ldots, L\) is, in fact, the global optimum point of function \(S_L\). It is clear from (5) that \(S_L\) is a continuous function of \(n_i\) on the closed and bounded domain \(\text{dom} S_L = \{n_i \mid n_i \in (0, M]\}\). Therefore, according to the extreme value theorem, there is a global maximum and global minimum for \(S_L\) in the interior or the boundary of \(\text{dom} S_L\)\(^{[34]}\).

By setting the gradient of \(S_L\) in (6) to zero, we can find the extremum points of \(S_L\) in the interior of \(\text{dom} S_L\). It is clear from (6) that \(n_i^*, i = 1, \ldots, L\) is the only extremum point of \(S_L\) in the interior of its domain. Now, to show that \(n_i^*, i = 1, \ldots, L\) is actually the global maximum, we check the value of \(S_L\) at the boundary \(\text{dom} S_L\), i.e., \(0\) and \(M\), to be lower than \(S_L^*\).

To this end, it is assumed that \(n_1^*, n_2^*, \ldots, n_L^*\) are the optimal values of \(S_{L-1}\); which means that \(S_{L-1}^* > S_{L-1}\) for \(n_i \in (0, M]\), \(i = 1, \ldots, L - 1\). Now, by substituting \(S_{L-1}^*\) in (4), it is sufficient to check \(S_L\) at \(n_L = 0\) and \(n_L = M\). By setting \(n_L = 0\) in (4), we have \(S_L = S_{L-1}\), and since \(S_L > S_{L-1}\) and \(S_{L-1}^* > S_{L-1}\), it can be inferred that \(S_L^* > S_L\) for \(n_i \in (0, M]\), \(i = 1, \ldots, L - 1\) and \(n_L = 0\). In the case that \(n_L = M\) in (4), we check whether the inequality in (31) is satisfied.

\[
S_L^* > S_{L-1}(1 - \frac{1}{M})^M + M(1 - \frac{1}{M})^{M-1} \tag{31}
\]

using the assumption \(S_{L-1}^* > S_{L-1}\), we can check the following inequality instead of (31).

\[
S_L^* > S_{L-1}(1 - \frac{1}{M})^M + M(1 - \frac{1}{M})^{M-1} \tag{32}
\]

According to (4), \(S_{L-1}^*\) in (32) can be replaced by \(S_L^*(1 - \frac{1}{M})^{-n_i^*} - n_L^*(1 - \frac{1}{M})^{-1}\), which results in (33).

\[
S_L^* \left(1 - (1 - \frac{1}{M})^{M-n_i^*}\right) > (M - n_i^*) (1 - \frac{1}{M})^{M-1} \tag{33}
\]

Now, by substituting the maximum value of \(S_L\) at \(n_i^*\) and \(\rho_L^*\) from (5) in (33), we have:

\[
(1 - \frac{1}{M})^{M-n_i^*} \left(1 + \ln \left(\frac{M}{M - 1}\right) (M - n_i^*)\right) < 1 \tag{34}
\]

where \(n_i^*\) is a value between 0 and \(M\), according to what has been obtained in (7). The first-order derivative of the left term in (34) with respect to \(n_i^*\) is:

\[
\left(\ln \left(\frac{M}{M - 1}\right) \right)^2 (M - n_i^*) (1 - \frac{1}{M})^{M-n_i^*} > 0
\]

which is a positive value for all possible values of \(n_i^*\).

Thus, the left term in (34) is an increasing function of \(n_i^*\) and its maximum value, 1, happens at \(n_i^* = M\). Then, the inequality in (34) is true for \(n_i^* \in (0, M]\).

According to what has been discussed in this lemma, the value of \(S_L^*\) at the boundary of \(\text{dom} S_L\) is less than \(S_L^*\) and hence, \(n_i^*, i = 1, \ldots, L\) is the only global optimal point of the function \(S_L\).

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