

# Linear Algebra for Computer Science

## Homework 1

### Read these first:

- i You may write your solutions on paper, under a word processing software (MS-word, Libre Office, etc.), or under L<sup>A</sup>T<sub>E</sub>X.
- ii If writing on paper, you must use a scanner device or a Camera Scanner (CamScanner) software to scan the document and submit a *single* PDF file.
- iii Up to 15% extra score will be given to solutions written under L<sup>A</sup>T<sub>E</sub>X, provided that you follow either of the following conventions:
  - (a) Represent scalars with normal (italic) letters ( $a, A$ ), vectors with bold lower-case letters ( $\mathbf{a}$ , using `\mathbf{a}`), and matrices with bold upper-case letters ( $\mathbf{A}$ , using `\mathbf{A}`), or
  - (b) represent scalars with normal (italic) letters ( $a, A$ ), vectors with bold letters ( $\mathbf{a}, \mathbf{A}$ ), and matrices with typewriter upper-case letters ( $\mathbf{A}$ , using `\mathtt{A}`).
  - (c) Your latex document must contain a *title*, a *date*, and your name as the author.
  - (d) In all cases, you must submit a *single* PDF file.
  - (e) If writing under L<sup>A</sup>T<sub>E</sub>X, you must submit the *.tex* source (and other necessary source files if there are any) in addition to the PDF file.

Here is a short tutorial on L<sup>A</sup>T<sub>E</sub>X: [https://www.overleaf.com/learn/latex/Learn\\_LaTeX\\_in\\_30\\_minutes](https://www.overleaf.com/learn/latex/Learn_LaTeX_in_30_minutes)

### Questions

1. A vector space defined on the field of the real numbers  $\mathbb{R}$  is a set  $V$ , equipped with a vector addition operator (vector + vector) and a scalar multiplication (scalar times vector) with the following properties
  - (1) *Commutativity*:  $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$  for  $\mathbf{u}, \mathbf{v} \in V$ .
  - (2) *Associativity*:  $\mathbf{u} + (\mathbf{v} + \mathbf{w}) = (\mathbf{v} + \mathbf{u}) + \mathbf{w}$  for all  $\mathbf{u}, \mathbf{v}, \mathbf{w} \in V$ .

- (3) *Identity element:* There exists an element  $\mathbf{z} \in V$  such that for every  $\mathbf{u} \in V$  we have  $\mathbf{u} + \mathbf{z} = \mathbf{u}$ . ( $\mathbf{z}$  is called the identity element and is often denoted by  $\mathbf{0}$ ).
- (4) *Inverse:* for every  $\mathbf{u} \in V$  there exist  $\mathbf{u}' \in V$  such that  $\mathbf{u} + \mathbf{u}' = \mathbf{z}$  (where the identity element  $\mathbf{z}$  was defined above. The vector  $\mathbf{u}'$  is called the (additive) inverse of  $\mathbf{u}$  and is usually denoted by  $\mathbf{u}^{-1}$  or  $-\mathbf{u}$ .)
- (5)  $1\mathbf{u} = \mathbf{u}$ . (notice that  $1 \in \mathbb{R}$ .)
- (6)  $a(b\mathbf{u}) = (ab)\mathbf{u}$  for all  $a, b \in \mathbb{R}$  and  $\mathbf{u} \in V$ .
- (7)  $a(\mathbf{u} + \mathbf{v}) = a\mathbf{u} + a\mathbf{v}$  for all  $a \in \mathbb{R}$  and  $\mathbf{u}, \mathbf{v} \in V$ .
- (8)  $(a + b)\mathbf{u} = a\mathbf{u} + b\mathbf{u}$  for all  $a, b \in \mathbb{R}$  and  $\mathbf{u} \in V$ .

Prove the following. In each step state which of the above axioms (1-8) you are using. You might also use the previous results, i.e. to prove d you may use parts a,b,c. Notice that there is no notion of subtraction ( $-$ ) here.

- (a) If  $\mathbf{z}$  is an identity element, then  $\mathbf{z} + \mathbf{u} = \mathbf{u}$  for all  $\mathbf{u} \in V$ . (notice that (3) states  $\mathbf{u} + \mathbf{z} = \mathbf{u}$ .)
  - (b) The identity element  $\mathbf{z}$  is unique.
  - (c) The inverse of the identity element is itself.
  - (d) The inverse of any vector is unique.
  - (e)  $0\mathbf{u} = \mathbf{z}$  for the scalar  $0 \in \mathbb{R}$ .
  - (f)  $a\mathbf{z} = \mathbf{z}$  for any scalar  $a \in \mathbb{R}$ .
  - (g)  $(-1)\mathbf{u} = \mathbf{u}'$  where  $\mathbf{u}'$  is the inverse element of  $\mathbf{u}$ .
2. Consider a matrix  $\mathbf{A} \in \mathbb{R}^{m \times n}$ , such that  $\mathbf{A}\mathbf{x} = \mathbf{0}$  for all  $\mathbf{x} \in \mathbb{R}^n$ . Prove that  $\mathbf{A} = \mathbf{0}_{m \times n}$ , that is all the entries of  $\mathbf{A}$  are zero.
  3. Consider a matrix  $\mathbf{A} \in \mathbb{R}^{m \times n}$ , such that  $\mathbf{A}\mathbf{x}_i = \mathbf{0}$  for  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n \in \mathbb{R}^n$ , where  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  form a basis for  $\mathbb{R}^n$ . Prove that  $\mathbf{A} = \mathbf{0}_{m \times n}$ .
  4. Consider a square matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$  for which  $\mathbf{A}\mathbf{x} = \mathbf{x}$  for all  $\mathbf{x} \in \mathbb{R}^n$ . Prove that  $\mathbf{A} = \mathbf{I}_n$ , the  $n$  by  $n$  identity matrix.
  5. Give an example of a matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$ , such that  $\mathbf{A}\mathbf{x} = \mathbf{x}$  for some nonzero vector  $\mathbf{x} \in \mathbb{R}^n$ ,  $\mathbf{A}$  is not the identity matrix.
  6. Assume that the vectors  $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n$  are linearly independent. Prove that the set of vectors  $\mathbf{a}'_1, \mathbf{a}_2, \dots, \mathbf{a}_n$  are also linearly independent where  $\mathbf{a}'_1 = \mathbf{a}_1 + \beta\mathbf{a}_2$  for some scalar  $\beta$ .
  7. The dot product can also be defined on matrices. Consider two matrices  $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{m \times n}$ . Their dot product can be defined as  $\langle \mathbf{A}, \mathbf{B} \rangle = \sum_{i=1}^m \sum_{j=1}^n A_{ij}B_{ij}$ .

- (a) Prove that  $\langle \mathbf{A}, \mathbf{B} \rangle = \text{trace}(\mathbf{A}^T \mathbf{B}) = \text{trace}(\mathbf{B}^T \mathbf{A}) = \text{trace}(\mathbf{A} \mathbf{B}^T)$ , where  $\text{trace}(\mathbf{S}) = \sum_i S_{ii}$  gives the sum of the diagonal elements of a square matrix  $\mathbf{S}$ .
- (b) Prove that  $\langle \mathbf{A} \mathbf{B}, \mathbf{C} \rangle = \langle \mathbf{B}, \mathbf{A}^T \mathbf{C} \rangle = \langle \mathbf{A}, \mathbf{C} \mathbf{B}^T \rangle$  Hint:  $(\mathbf{A} \mathbf{B})^T = \mathbf{B}^T \mathbf{A}^T$ .
8. Prove that a triangular matrix with at least one zero diagonal element is singular.