

Linear Algebra for Computer Science

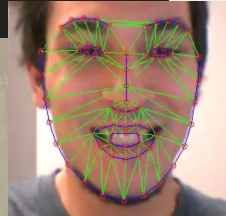
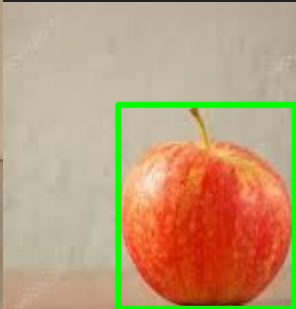
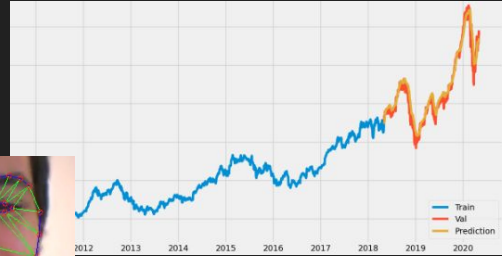
Lecture 30

Introduction to Machine Learning
and learning from data

Machine Learning



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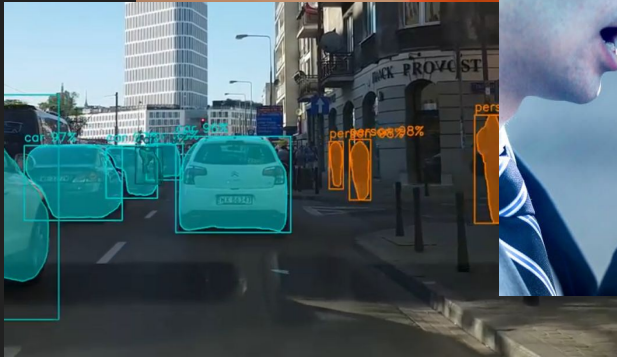


input



Model

output



Classification



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Classification



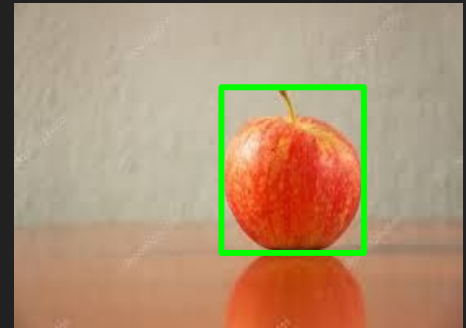
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Object detection



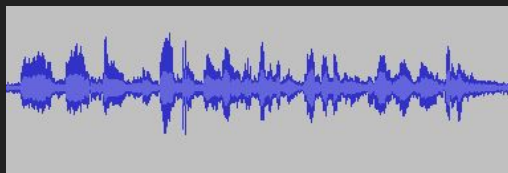
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Speech Recognition



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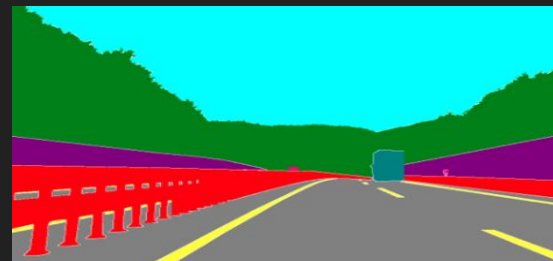
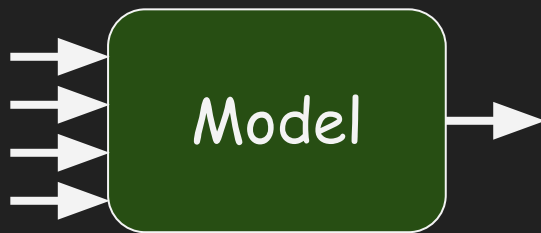


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Segmentation



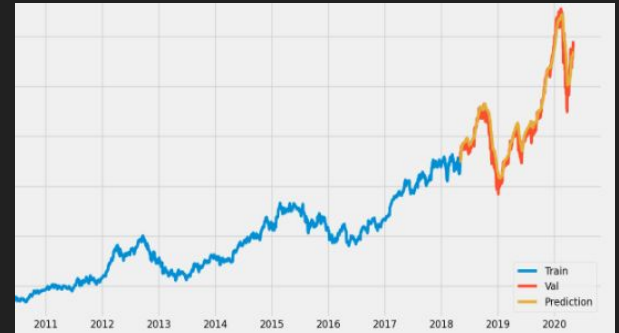
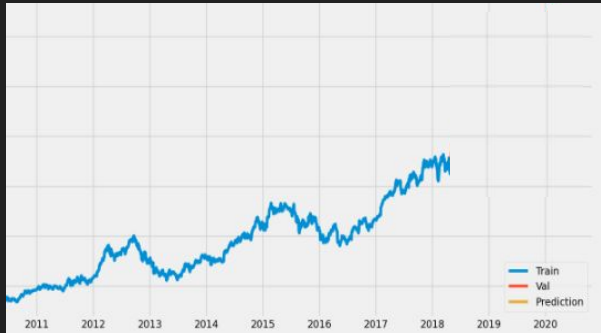
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Stock Market Prediction



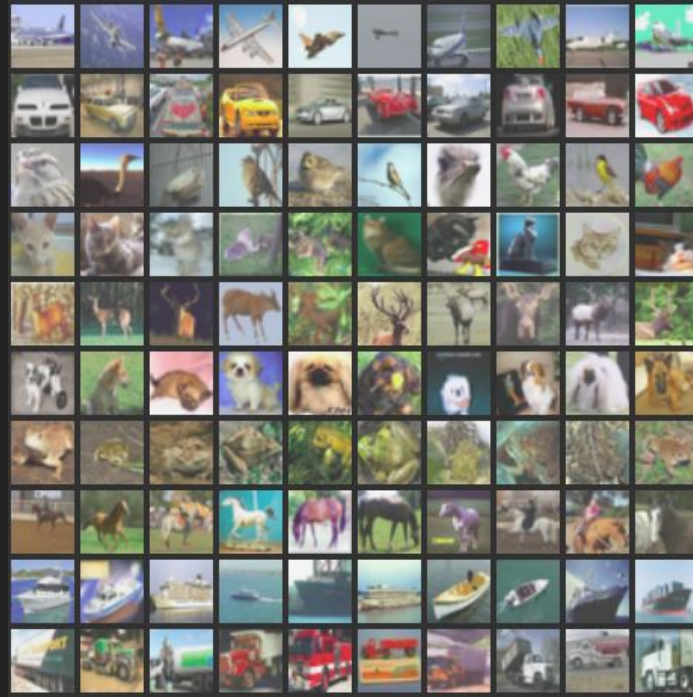
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Learning from data



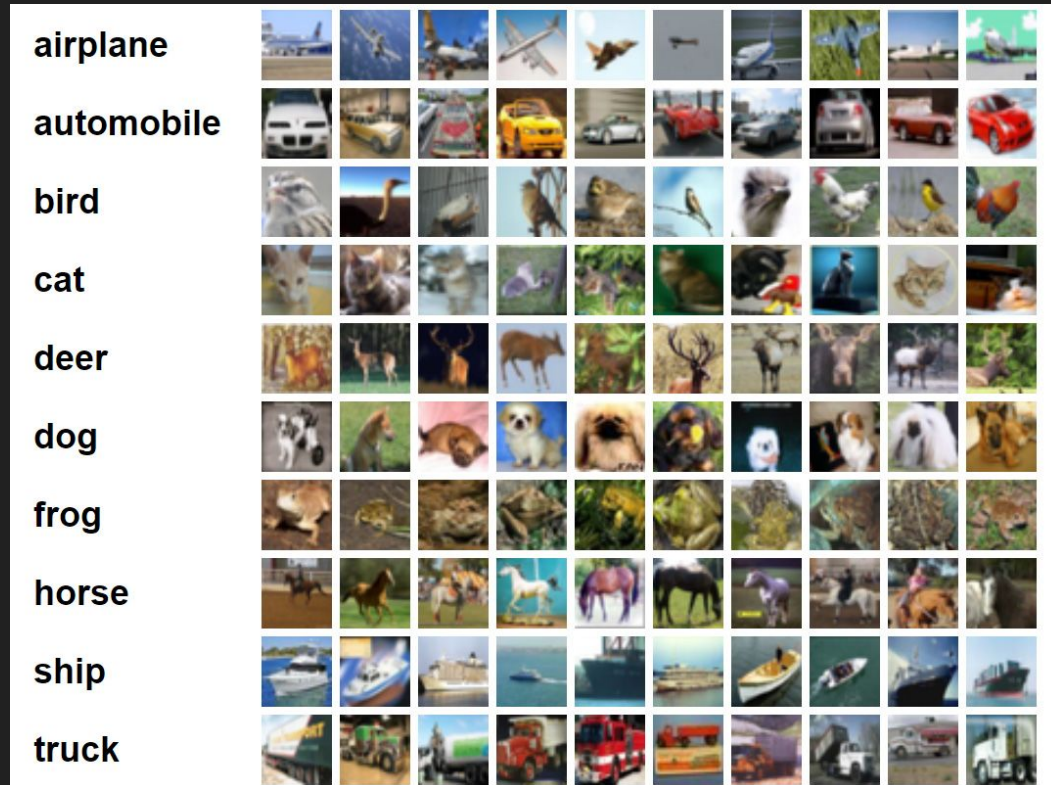
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Supervised Learning



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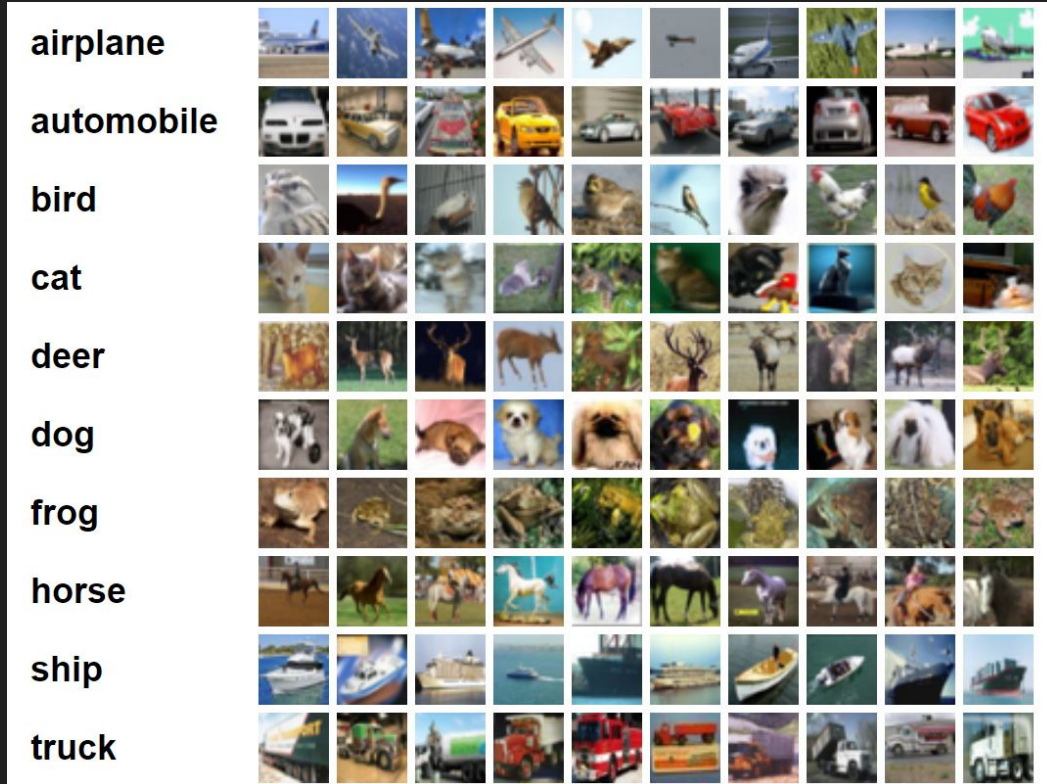


<http://seansoleyman.com/effect-of-dataset-size-on-image-classification-accuracy/>

Supervised Learning



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Training data:

X_1, y_1

X_2, y_2

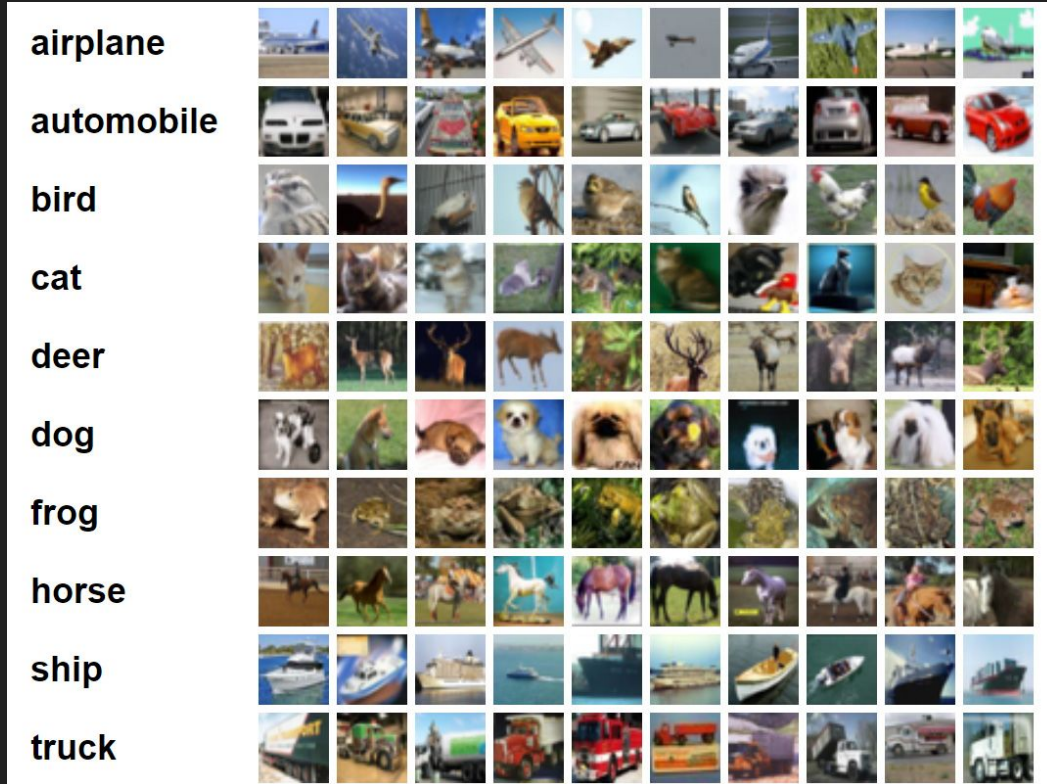
X_3, y_3

\vdots
 X_n, y_n

Supervised Learning



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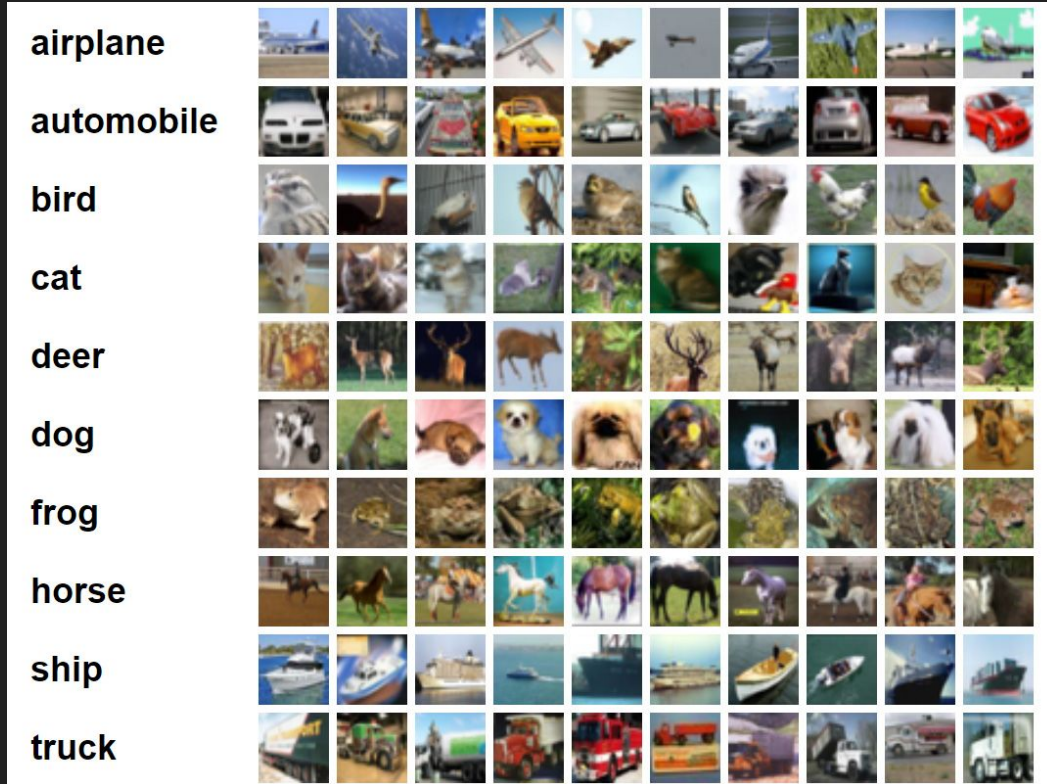
Training data:

	Apple
	Apple
	Orange
	Orange

Supervised Learning



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Training data:

	0
	0
	1
⋮	
	1

Supervised Learning



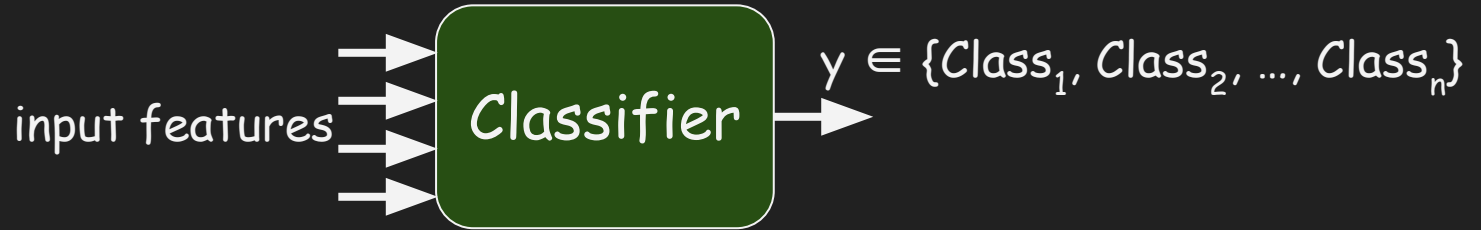
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Classification



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Classification



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Classification



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Regression



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Regression



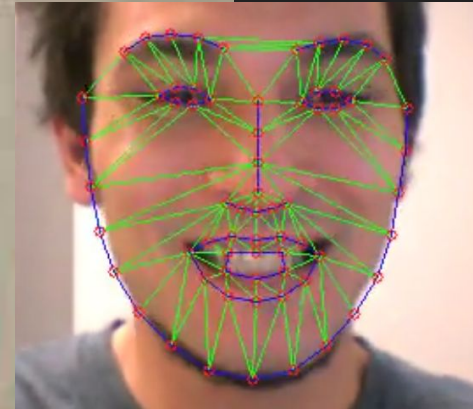
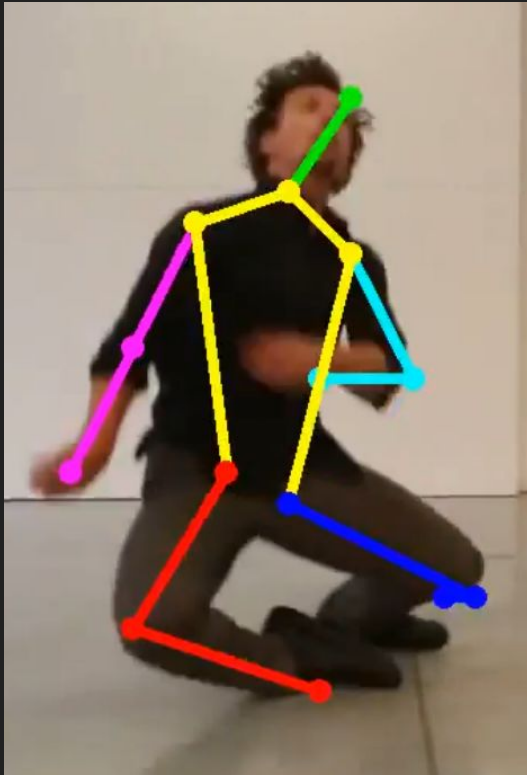
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Regression



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Learnable Models



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Learnable Models: Example



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Learnable Models: Example



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Learnable Models: Input-output map



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$$y = f(x)$$

$$f: \mathbb{R}^m \rightarrow \mathbb{R}^n$$

Learnable Models: Example

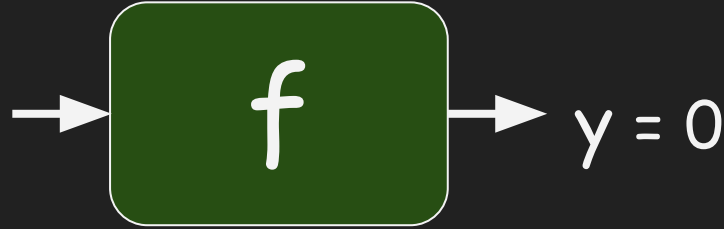


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I

$x =$
I.flatten()



$$y = f(x)$$

$$f: \mathbb{R}^m \rightarrow \mathbb{R}^n$$

Learnable Models: Example

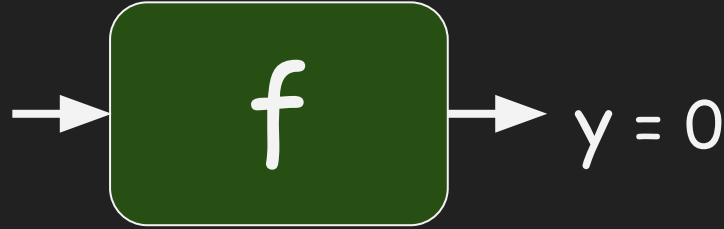


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I

$x =$
 $\text{features}(I)$



$$y = f(x)$$

$$f: \mathbb{R}^m \rightarrow \mathbb{R}^n$$

Learnable Models: parameters



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$$y = f(\theta, \mathbf{x})$$

θ : model parameters

Learnable Models: parameters



$$y = f(\underline{x}, \underline{\theta})$$

$$f: \mathbb{R}^m \times \mathbb{R}^p \rightarrow \mathbb{R}^n$$

$$\mathbb{R}^2 \times \mathbb{R}^6 \rightarrow \mathbb{R}^1$$

$$\begin{bmatrix} x \\ y \end{bmatrix} \times \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \end{bmatrix} \mapsto ax^2 + by^2 + cyx + dx + ey + f$$

$$f(x, \theta) \in \mathbb{R}^n$$

training data $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$

$$x_1, x_2, \dots, x_n \in \mathbb{R}^m$$

$$y_1, y_2, \dots, y_n \in \mathbb{R}^n$$

Example
$$C(\theta) = \sum_{i=1}^N \|f(x_i, \theta) - y_i\|^2$$

$$= \sum_{i=1}^N (f(x_i, \theta) - y_i)^T (f(x_i, \theta) - y_i)$$

Learnable Models: parameters



Example

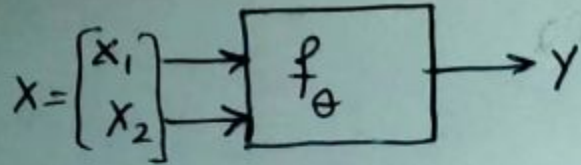
x_1 → g → y
 x_2 →

$$y = ax_1^2 + bx_2^2 + cx_1x_2 + dx_1 + ex_2 + f$$
$$g(x_1, x_2) = \underline{ax_1^2} + \underline{bx_2^2} + \underline{cx_1x_2} + \underline{dx_1} + \underline{ex_2} + \underline{f}$$
$$y = h(x, \theta) = h\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \end{bmatrix}\right) \quad \begin{array}{l} x \in \mathbb{R}^2 \\ \theta \in \mathbb{R}^6 \end{array}$$

x_1 → h_θ → y
 x_2 →

$$h: \mathbb{R}^2 \times \mathbb{R}^6 \rightarrow \mathbb{R}$$

Example: A Quadratic Function



(I)

$$y = f_\theta(x) = f(\theta, x) = ax_1^2 + bx_2^2 + cx_1x_2 + dx_1 + ex_2 + f$$

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$x \in \mathbb{R}^2$$

$$\theta = \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \end{bmatrix} \in \mathbb{R}^6$$

$$f: \begin{matrix} \mathbb{R}^6 & \times & \mathbb{R}^2 \\ \theta & & x \end{matrix} \rightarrow \mathbb{R}$$

Example: A Quadratic Function



$$y = f_{\theta}(x) = f(\theta, x) = ax_1^2 + bx_2^2 + cx_1x_2 + dx_1 + ex_2 + f$$

$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{R}^2$

$\theta = \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \end{bmatrix} \in \mathbb{R}^6$

$f: \mathbb{R}^6 \times \mathbb{R}^2 \rightarrow \mathbb{R}$
 $\theta \quad x$

$$f(\theta, x) = \underbrace{\begin{bmatrix} a & b & c & d & e & f \end{bmatrix}}_{\theta^T} \begin{bmatrix} x_1^2 \\ x_2^2 \\ x_1x_2 \\ x_1 \\ x_2 \\ 1 \end{bmatrix}$$
$$= \theta^T \phi(x) \quad \phi(x) = \phi\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1^2 \\ x_2^2 \\ x_1x_2 \\ x_1 \\ x_2 \\ 1 \end{bmatrix}$$

Quadratic Function: Alternative Parameterization



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$$\begin{aligned} f(\theta, x) &= a_1 x_1^2 + b x_2^2 + c x_1 x_2 + d x_1 + e x_2 + f \\ &= \underbrace{\begin{bmatrix} x_1 & x_2 \end{bmatrix}}_{x^T} \underbrace{\begin{bmatrix} a & c/2 \\ c/2 & b \end{bmatrix}}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}_x + \underbrace{\begin{bmatrix} d & e \end{bmatrix}}_{v^T} \underbrace{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}_x + f \\ &= x^T A x + v^T x + f \quad (A \text{ symmetric}) \\ \theta &= (A, v, f) \\ &\quad \downarrow \quad \downarrow \quad \downarrow \\ &\quad \text{sym} \quad \in \mathbb{R}^2 \quad \in \mathbb{R} \end{aligned}$$

Learnable Models: parameters



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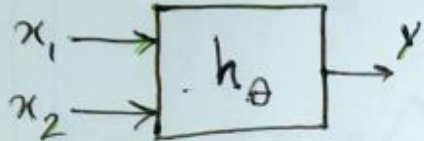
- Parameter Learning:
 - A collection of input-output pairs $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$,
 - choose θ such that $y = f(\theta, x)$ is a reasonable output for any input x .

Learnable Models: parameters



$$g(x_1, x_2) = \underline{a}x_1^2 + \underline{b}x_2^2 + \underline{c}x_1x_2 + \underline{d}x_1 + \underline{e}x_2 + \underline{f}$$

$$y = h(x, \theta) = h\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \end{bmatrix}\right) \quad \begin{array}{l} x \in \mathbb{R}^2 \\ \theta \in \mathbb{R}^6 \end{array}$$



$$h: \mathbb{R}^2 \times \mathbb{R}^6 \rightarrow \mathbb{R}$$

$$D = \text{training data} = \left\{ \left[(x_1^1, x_2^1), y^1 \right], \left[(x_1^2, x_2^2), y^2 \right], \dots, \left[(x_1^n, x_2^n), y^n \right] \right\}$$

$$D = \left\{ (x^1, y^1), (x^2, y^2), \dots, (x^n, y^n) \right\}$$

Learning from data



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- Parameter Learning:
 - A collection of input-output pairs $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$,
 - choose θ such that $y = f(\theta, x)$ is a reasonable output
 - for training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - for unseen data (generalization)

Learning from data



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- Parameter Learning:
 - A collection of input-output pairs $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$,
 - choose θ such that $y = f(\theta, x)$ is a reasonable output
 - for training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - for unseen data (generalization)

Learning from data



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- Training data $(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \dots, (\mathbf{x}_N, y_N)$
 - choose θ such that $f(\theta, \mathbf{x}_i)$ is close to y_i

Learning from data: Cost function



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- Training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - choose θ such that $f(\theta, x_i)$ is close to y_i

Cost function

Learning from data: Cost function



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- Training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - choose θ such that $f(\theta, x_i)$ is close to y_i
 - cost function:

$$C(\theta) = \sum_{i=1..N} d(f(\theta, x_i), y_i)$$

Learning from data: Cost function



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- Training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - choose θ such that $f(\theta, x_i)$ is close to y_i
 - cost function:

$$C(\theta) = \sum_{i=1..N} d(f(\theta, x_i), y_i)$$

↓
data output

Learning from data: Cost function



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- Training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - choose θ such that $f(\theta, x_i)$ is close to y_i
 - cost function:

$$C(\theta) = \sum_{i=1..N} d(f(\theta, x_i), y_i)$$



model output given x_i

Learning from data: Cost function



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- Training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - choose θ such that $f(\theta, x_i)$ is close to y_i
 - cost function:

$$C(\theta) = \sum_{i=1..n} d(f(\theta, x_i), y_i)$$

↓
distance

Learning from data: Cost function



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- Training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - choose θ such that $f(\theta, x_i)$ is close to y_i
 - cost function:

$$C(\theta) = \sum_{i=1..n} \| f(\theta, x_i) - y_i \|^2$$

distance

Learning from data: Cost function



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- Training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - choose θ such that $f(\theta, x_i)$ is close to y_i
 - cost function:

$$C(\theta) = \sum_{i=1..n} d(f(\theta, x_i), y_i)$$

Learning from data: Cost function



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- Training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - choose θ such that $f(\theta, x_i)$ is close to y_i
 - cost function:

$$C(\theta) = \sum_{i=1..n} d(f(\theta, x_i), y_i)$$

choose θ such that $C(\theta)$ is small

Learning from data: Cost function



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- Training data $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
 - choose θ such that $f(\theta, x_i)$ is close to y_i
 - cost function:

$$C(\theta) = \sum_{i=1..n} d(f(\theta, x_i), y_i)$$

$$\theta^* = \operatorname{argmin}_{\theta} C(\theta)$$