

$A \in \mathbb{R}^{n \times n}$

$Ax = b$

$x \in \mathbb{R}^n$
 $b \in \mathbb{R}^n$

$\text{rank}(A) = n$

$f(x) = Ax$ $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is f linear?

$f(x_1) = f(x_2) \Rightarrow Ax_1 = Ax_2 \Rightarrow Ax_1 - Ax_2 = \vec{0}$
 $A(x_1 - x_2) = \vec{0} \Rightarrow Az = \vec{0} \Rightarrow \begin{bmatrix} \vec{a}_1 & \vec{a}_2 & \dots & \vec{a}_n \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{bmatrix} = \vec{0}$

$z_1 \vec{a}_1 + z_2 \vec{a}_2 + \dots + z_n \vec{a}_n = \vec{0} \Rightarrow z_1 = z_2 = \dots = z_n = 0 \Rightarrow \vec{z} = \vec{0}$

$x_1 - x_2 = \vec{0} \Rightarrow x_1 = x_2 \Rightarrow f$ is one-to-one

is f onto?

Let $y \in \mathbb{R}^n$ ~~is there~~ is there an $x \in \mathbb{R}^n$ such that $f(x) = y$?

$f(x) = y \Rightarrow Ax = y = \begin{bmatrix} \vec{a}_1 & \vec{a}_2 & \dots & \vec{a}_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = y$

$x_1 \vec{a}_1 + x_2 \vec{a}_2 + \dots + x_n \vec{a}_n = y$ span
 $\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n \in \mathbb{R}^n$ ~~form a basis for~~ \mathbb{R}^n

$\Leftarrow \exists n_1, n_2, \dots, n_n$ such that $n_1 \vec{a}_1 + \dots + n_n \vec{a}_n = y$

$\Rightarrow \exists x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \in \mathbb{R}^n$ $Ax = y$

$f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ $f(x) = Ax$ } $\Rightarrow f$ is one to one & onto
 $A \in \mathbb{R}^{n \times n}$ nonsingular

$\Rightarrow \exists f^{-1}: \mathbb{R}^n \rightarrow \mathbb{R}^n$ such that $f(f^{-1}(x)) = f^{-1}(f(x)) = x$ for all x

$f: U \rightarrow U$ is linear & invertible LAG (II)

$$(\exists f^{-1} \forall x \quad f^{-1}(f(x)) = f(f^{-1}(x)) = x)$$

is f^{-1} linear?

$$\begin{aligned}
 f^{-1}(\alpha \vec{y}_1 + \beta \vec{y}_2) &\stackrel{?}{=} \alpha f^{-1}(y_1) + \beta f^{-1}(y_2) \\
 f(f^{-1}(\alpha \vec{y}_1 + \beta \vec{y}_2)) &\stackrel{?}{=} f(\alpha f^{-1}(y_1) + \beta f^{-1}(y_2)) \\
 \alpha \vec{y}_1 + \beta \vec{y}_2 &\stackrel{?}{=} \alpha f(f^{-1}(y_1)) + \beta f(f^{-1}(y_2)) \\
 \alpha \vec{y}_1 + \beta \vec{y}_2 &= \alpha y_1 + \beta y_2
 \end{aligned}$$

$$\left. \begin{aligned}
 f(x) &= \underline{A}x \\
 \text{rank}(A) &= n \\
 A &\in \mathbb{R}^{n \times n} \\
 f: \mathbb{R}^n &\rightarrow \mathbb{R}^n
 \end{aligned} \right\}$$

$$\left. \begin{aligned}
 f: \mathbb{R}^n &\rightarrow \mathbb{R}^n \text{ is linear} \\
 \Rightarrow \exists B \in \mathbb{R}^{n \times n} \\
 f^{-1}(y) &= \underline{B}y \quad \forall y
 \end{aligned} \right\}$$

$$\Rightarrow \underline{A} \in \mathbb{R}^n \quad f(f^{-1}(x)) = f^{-1}(f(x)) = x$$

$$A(Bx) = B(Ax) = x \quad \forall x$$

$$(AB)x = (BA)x = x \quad \forall x$$

$$\forall x \quad (AB)x = x \Rightarrow \begin{aligned}
 AB e_1 &= e_1 \\
 AB e_2 &= e_2 \\
 &\vdots \\
 AB e_n &= e_n
 \end{aligned}$$

$$\begin{aligned}
 e_1 &= \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad e_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} \in \mathbb{R}^3 \\
 AB &= \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}
 \end{aligned}$$

$$(A \cdot B) [e_1 \ e_2 \ \dots \ e_n] = [e_1 \ e_2 \ \dots \ e_n]$$

$$ABI = I \Rightarrow AB = I \quad BA = I$$

$\forall A \in \mathbb{R}^{n \times n}$ non singular $\exists B \quad AB = BA = I$

B^{-1} is called the inverse of A
 & is denoted by A^{-1}

$Ax = b$ $A \in \mathbb{R}^{n \times n}$ nonsingular

$A^{-1}Ax = A^{-1}b \Rightarrow x = A^{-1}b$
 $n \times n$ $n \times 1$
 $n \times 1$

there exist a unique solution $x = A^{-1}b$.

rotation

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}^{-1} = \begin{bmatrix} \cos(-\theta) & -\sin(-\theta) \\ \sin(-\theta) & \cos(-\theta) \end{bmatrix}$$

$$= \begin{bmatrix} \cos(\theta) & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

~~$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$~~ $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$
 reflection

scale

$$\begin{bmatrix} (s) & 0 \\ 0 & (s) \end{bmatrix} \begin{bmatrix} (1/s) & 0 \\ 0 & (1/s) \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$A \in \mathbb{R}^{n \times n}$ singular

null vector of A

$A \in \mathbb{R}^{m \times n}$ ~~A~~ $v \in \mathbb{R}^n$ $Av = 0$

v is a null vector of A

$\vec{0} \in \mathbb{R}^n$ is a null vector of any $A \in \mathbb{R}^{n \times n}$

Does A have a nonzero null vector?
non-trivial

~~A~~ non-singular $\iff Av = 0 \implies v = \vec{0}$

A singular $\implies \begin{bmatrix} \vec{a}_1 & \vec{a}_2 & \dots & \vec{a}_n \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{bmatrix} = \vec{0}$

$\exists x \neq 0$ $Ax = 0$

$\vec{a}_i = z_1 \vec{a}_1 + z_2 \vec{a}_2 + \dots + z_{i-1} \vec{a}_{i-1} + z_{i+1} \vec{a}_{i+1} + \dots + z_n \vec{a}_n$

$\vec{a}_1 = z_2 \vec{a}_2 + \dots + z_n \vec{a}_n$

$0 = -1 \vec{a}_1 + z_2 \vec{a}_2 + \dots + z_n \vec{a}_n$

$\begin{bmatrix} \vec{a}_1 & \vec{a}_2 & \dots & \vec{a}_n \end{bmatrix} \begin{bmatrix} -1 \\ z_2 \\ \vdots \\ z_n \end{bmatrix} = 0$

A singular $\exists x \neq 0$ $Ax = 0$

Assume A is singular & has an inverse A^{-1} .

$\implies \exists x \neq 0, Ax = 0$

$x = Ax = A^{-1}Ax = A^{-1}0 = 0$ ~~$x \neq 0$~~