## Mathematics for AI Homework 4

## Read these first:

i You may write your solutions on paper, under a word processing software (MS-word, Libre Office, etc.), or under $\mathrm{EAT}_{\mathrm{E}} \mathrm{X}$.
ii If writing on paper, you must use a scanner device or a Camera Scanner (CamScanner) software to scan the document and submit a single PDF file. Also, write your answers neatly, in an organized and legible manner on paper.
iii Up to $15 \%$ extra score will be given to solutions written under $\mathrm{IA}_{\mathrm{E}} \mathrm{X}$, provided that you follow either of the following conventions:
(a) Represent scalars with normal (italic) letters $(a, A)$, vectors with bold lower-case letters (a, using $\backslash \operatorname{mathbf}\{\mathrm{a}\}$ ), and matrices with bold upper-case letters (A, using \mathbf\{A\}), or
(b) represent scalars with normal (italic) letters $(a, A)$, vectors with bold letters ( $\mathbf{a}, \mathbf{A}$ ), and matrices with typewriter upper-case letters (A, using \mathtt\{A\}).
(c) You latex document must contain a title, a date, and your name as the author.
(d) In all cases, you must submit a single PDF file.
(e) If writing under $\mathrm{IA}_{\mathrm{E}} \mathrm{X}$, you must submit the .tex source (and other necessary source files if there are any) in addition to the PDF file.

Here is a short tutorial on $\mathrm{AAT}_{\mathrm{E}} \mathrm{X}$ : https://www.overleaf.com/ learn/latex/Learn_LaTeX_in_30_minutes

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## Questions

For each questions, you may use the results of the previous questions (but not the following ones). Throughout this document, the operations diag() and Diag(•) are defined as follows:

- $\operatorname{diag}(\mathrm{A})$ creates a vector $\in \mathbb{R}^{n}$ from the diagonal elements of the matrix $\mathrm{A} \in \mathbb{R}^{m \times n}$, and
- $\operatorname{Diag}(\mathbf{x})$ creates an $n \times n$ diagonal matrix whose diagonal elements are the entries of $\mathbf{x} \in \mathbb{R}^{n}$.

Notice that both these operations are linear.

## Adjoint

Consider two inner product spaces $\mathcal{U}$ and $\mathcal{V}$. A mapping $f^{*}: \mathcal{V} \rightarrow \mathcal{U}$ is called the adjoint of the linear map $f: \mathcal{U} \rightarrow \mathcal{V}$ if

$$
\langle\mathbf{y}, f(\mathbf{x})\rangle=\left\langle f^{*}(\mathbf{y}), \mathbf{x}\right\rangle,
$$

for all $\mathbf{x} \in \mathcal{U}$ and $\mathbf{y} \in \mathcal{V}$.

1. Show that for the linear map $\mathbf{f}: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$ defined by $f(\mathbf{x})=\mathrm{Ax}$ with $\mathrm{A} \in \mathbb{R}^{m \times n}$ the adjoint is defined by $f^{*}(\mathbf{y})=\mathrm{A}^{T} \mathbf{y}$.
2. Show that the $\operatorname{diag}(\cdot)$ and $\operatorname{Diag}(\cdot)$ operations defined above are adjoints of each other (with respect to the ordinary dot product defined in previous assignments).

## Jacobian

3. Derive the Jacobian matrix for the following with respect to $\mathbf{x} \in \mathbb{R}^{n}$ using the directional derivative method.
(a) $\operatorname{Diag}(\mathbf{x}) \mathbf{x}$,
(b) $\operatorname{Diag}(\mathbf{x}) \mathbf{\mathbf { a } ^ { T }} \mathbf{x}$ where $\mathbf{a} \in \mathbb{R}^{n}$,
(c) $\mathrm{A} \operatorname{Diag}(\mathbf{x}) \mathrm{x}$ where $\mathrm{A} \in \mathbb{R}^{n \times n}$,
(d) $\left(\mathbf{x}^{T} \mathrm{Ax}\right)^{2} \mathrm{~A} \mathbf{x}$ where $\mathrm{A} \in \mathbb{R}^{n \times n}$,

## Quadratic Forms

4. Consider the quadratic form $f: \mathbb{R}^{2} \rightarrow \mathbb{R}$ defined as $f(\mathbf{x})=\mathbf{x}^{T} \tilde{A} \mathbf{x}$, where

$$
\tilde{A}=\left[\begin{array}{cc}
1 & 2 \\
4 & -1
\end{array}\right]
$$

Find a symmetric matrix A such that $f(\mathbf{x})=\mathbf{x}^{T} \mathbf{A} \mathbf{x}$.
5. Show that for every function $f: \mathbb{R}^{2} \rightarrow \mathbb{R}$ defined as $f(\mathbf{x})=\mathbf{x}^{T} \tilde{A} \mathbf{x}$, there exist a symmetric matrix A such that $f(\mathbf{x})=\mathbf{x}^{T} \mathbf{A} \mathbf{x}$.

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## Hessian

6. Find the Gradient and the Hessian for the following with respect to $\mathrm{x} \in \mathbb{R}^{n}$
(a) $\operatorname{diag}\left(\mathbf{x A} \mathbf{x}^{T}\right)$,
(b) $\mathbf{x}^{T} \operatorname{Diag}(\mathbf{x}) \mathbf{x}$,
(c) $\left(\mathbf{x}^{T} \mathrm{~A} \mathbf{x}\right)^{2}$ where $\mathrm{A} \in \mathbb{R}^{n \times n}$ is a symmetric matrix,
(d) $\left(\mathbf{x}^{T} \mathbf{A x}\right) /\left(\mathbf{x}^{T} \mathbf{B x}\right)$ where $\mathrm{A}, \mathrm{B} \in \mathbb{R}^{n \times n}$ are symmetric,
(e) $\sum_{i=1}^{n} \sqrt{\mathbf{x}^{T} \mathrm{~A}_{i} \mathbf{x}}$ where $\mathrm{A}_{1}, \mathrm{~A}_{2}, \ldots, \mathrm{~A}_{n} \in \mathbb{R}^{n \times n}$ are (symmetric) positive definite.
