

Mathematics for AI

Lecture 19

Second Derivatives, Multilinear maps and Tensors, the Hessian Matrix,
Quadratic Functions, Quadratic Approximation, Taylor Series



Second derivative in multivariable functions



MA19 (I)

$f: \mathbb{R} \rightarrow \mathbb{R}$
 $f: \mathbb{R}^n \rightarrow \mathbb{R}$
 $u: \text{fixed}$
 $D[u]f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$D[u]f(x) = D[u]f \Big|_x = (D[u]f)(x)$$

$$= \frac{d}{d\alpha} f(x + \alpha u) = \nabla_x^T u$$

differentiable

$$(D[u]f)(x) = \frac{d}{d\alpha} f(x + \alpha u)$$

Take a second directional derivative, this time in direction \vec{v} .

$g(x) = (D[u]f)(x)$
 $h(x) = D[v]g(x)$

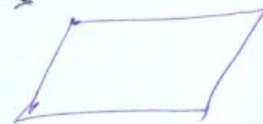
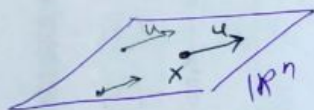
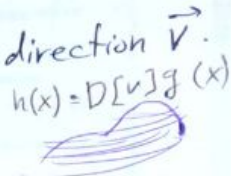
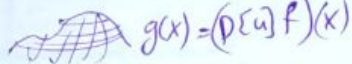
Second derivative in multivariable functions



$$D[u]f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$(D[u]f)(x) = \frac{d}{d\alpha} f(x + \alpha u)$$

Take a second directional derivative, this time in direction \vec{v} .
 $h(x) = D[v]g(x)$



$$(D[v]g)(x) = D[v](D[u]f)(x) \doteq D^2[\vec{v}, u]$$

if f is twice differentiable, $D^2[\vec{v}, u]$ is linear in both u, v

$$D^2[\vec{v}, u] \doteq \text{bilinear in } (v, u)$$

Bilinear maps



Let $l: \mathbb{R}^m \times \mathbb{R}^n \rightarrow \mathbb{R}$ be bilinear

$$l(x, y) \quad x \in \mathbb{R}^m, y \in \mathbb{R}^n$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} + \dots + x_m \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

\downarrow
 e_m

$$x = \sum x_i \vec{e}_i$$

$$\begin{cases} l(\alpha x + \beta x', y) = \alpha l(x, y) + \beta l(x', y) \\ l(x, \alpha y + \beta y') = \alpha l(x, y) + \beta l(x, y') \end{cases}$$

$$l\left(\sum_{i=1}^m x_i e_i, \sum_{j=1}^n y_j e'_j\right)$$

$$= \sum_{i=1}^m x_i l\left(e_i, \sum_{j=1}^n y_j e'_j\right)$$

$$= \sum_{i=1}^m \sum_{j=1}^n y_j x_i \underbrace{l(e_i, e'_j)}_{a_{ij}} = \sum_{i=1}^m \sum_{j=1}^n x_i y_j a_{ij} = x^T A y$$

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

Tensors of order 1 and 2



$$f(x) \quad f: \mathbb{R}^n \rightarrow \mathbb{R}, \quad f \text{ linear} \Rightarrow \exists a \in \mathbb{R}^n \quad f(x) = a^T x$$

f : is a tensor of degree 1
(rank) order $a \in \mathbb{R}^n$
or
 a 1D array $a[i]$

$$f(x) = a^T x = \sum_{i=1}^n a_i x_i$$

$$f(x, y): \mathbb{R}^m \times \mathbb{R}^n \rightarrow \mathbb{R} \quad \text{bilinear}$$

$$\Rightarrow \exists A \in \mathbb{R}^{m \times n} \quad f(x, y) = x^T A y$$

f : is a degree 2 tensor
 A

$$A_{ij} = a_{ij} = f(e_i, e_j)$$

A : 2D array $A[i, j]$

$$f(x, y) = \cancel{a} x^T A y = \sum_{i=1}^m \sum_{j=1}^n a_{ij} x_i y_j$$

Trilinear functions, tensors of order 3



K. N. Toosi
University of Technology

$f(x, y, z): \mathbb{R}^m \times \mathbb{R}^n \times \mathbb{R}^p$ trilinear

f is a tensor of rank 3
degree

A : 3D array

$$a_{ijk} = A[i, j, k]$$

$$f(x, y, z) = \sum_{i,j,k} x_i y_j z_k a_{ijk}$$

Multilinear functions, tensors of order p



K. N. Toosi
University of Technology

$$f(x_1, x_2, \dots, x_p): \quad f: \mathbb{R}^{n_1} \times \mathbb{R}^{n_2} \times \dots \times \mathbb{R}^{n_p} \rightarrow \mathbb{R}$$

$x_i \in \mathbb{R}^{n_i}$ Multilinear

$\Rightarrow f$ is a tensor of rank p

f : can be represented by a p -dimensional array

The Hessian Matrix



K. N. Toosi
University of Technology

$D^2[u, v]f = D[v]D[u]f$ is a bilinear function $(\mathbb{R}^n \times \mathbb{R}^n) \rightarrow \mathbb{R}$

$$\Rightarrow D^2[u, v] \Big|_x = D[v](D[u]f) \Big|_x = v^T H u \quad \begin{array}{l} H = H(x) \\ \in \mathbb{R}^{n \times n} \end{array}$$

Hessian Matrix

The Hessian Matrix



K. N. Toosi
University of Technology

$D^2[u, v]f = D[v]D[u]f$ is a bilinear function $(\mathbb{R}^n \times \mathbb{R}^n) \rightarrow \mathbb{R}$

$$\Rightarrow D^2[u, v] \Big|_x = D[v](D[u]f) \Big|_x = v^T H u \quad \begin{array}{l} H = H(x) \\ \in \mathbb{R}^{n \times n} \end{array}$$

Hessian Matrix

The Hessian Matrix



$$\begin{aligned}
 (D[u]f)(x) &= \nabla_f^T u = \left[\frac{\partial f}{\partial x_1} \quad \frac{\partial f}{\partial x_2} \quad \dots \quad \frac{\partial f}{\partial x_n} \right]^T u = \sum \frac{\partial f}{\partial x_i} u_i \\
 D[v](D[u]f) &= \nabla_{D[u]f}^T v = \sum_{i=1}^m \left(\nabla_{\frac{\partial f}{\partial x_i}} u_i \right)^T v \quad \text{MA 19 (III)} \\
 &= \sum_{i=1}^n \sum_{j=1}^n u_i \cdot \nabla_{\frac{\partial f}{\partial x_i}}^T v = \sum_{i=1}^n \sum_{j=1}^n u_i \cdot \left(\frac{\partial f}{\partial x_j} \left(\frac{\partial f}{\partial x_i} \right) v_j \right) \\
 &= \sum_{i=1}^n \sum_{j=1}^n u_i \cdot v_j \cdot \frac{\partial^2 f}{\partial x_i \partial x_j} \\
 &= \sum \sum u_i \cdot v_j \quad \text{Hessian Matrix} \\
 &= v^T H u
 \end{aligned}$$

The Hessian Matrix



K. N. Toosi
University of Technology

$$\mathbf{H}_f = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix}$$

https://en.wikipedia.org/wiki/Hessian_matrix

The Hessian Matrix



$H =$
 $H =$

$$\begin{bmatrix}
 \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \dots \\
 \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \dots \\
 \vdots & \vdots & \ddots
 \end{bmatrix}$$

$C^0 \supseteq C^1 \supseteq C^2 \dots \supseteq C^\infty$

symmetric

$f \in C^2 \Rightarrow H^T = H$

\hookrightarrow twice continuously differentiable

$$\frac{\partial^2 f}{\partial x_i \partial x_j} = \frac{\partial f}{\partial x_j \partial x_i}$$

Directional Curvature



K. N. Toosi
University of Technology

Directional curvature

$C[u] = D[u]D[u]f(x) = u^T H u$

$H = H(x) \in \mathbb{R}^{n \times n}$

The image contains two hand-drawn diagrams. The top diagram shows a simple 2D parabolic curve opening upwards, representing a cross-section of a surface. The bottom diagram shows a 3D perspective of a surface. A point x is marked on the surface, and a vector u originates from x , pointing in a direction along the surface. A small curve is drawn on the surface, following the direction of u . The text $H = H(x) \in \mathbb{R}^{n \times n}$ is written next to the diagram, indicating that H is the Hessian matrix at point x .

Calculating Hessian



How to derive the Hessian matrix

1- find $\frac{\partial^2 f}{\partial x_j \partial x_i}$ for $i=1-n$ and $j=1-n$ and arrange in a matrix

2- (a) find $D[u]f = g(x, u)$

(b) find $D[v]g = D[v]D[u]f(x)$

(c) write in the form $v^T H u$

Quadratic forms and Quadratic functions



K. N. Toosi
University of Technology

Quadratic form

$$f(x, y) = f\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = ax^2 + by^2 + cxy$$

$$x = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & c/2 \\ c/2 & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$x^T A x$$

Quadratic function

$$f(x, y) = ax^2 + by^2 + cxy + dx + ey + g$$

$$= \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & c/2 \\ c/2 & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} d & e \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + g$$

$$x^T A x + h^T x + g$$

A symmetric

Quadratic forms and Quadratic functions



K. N. Toosi
University of Technology

Quadratic form $f(x)$ $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$f(x) = x^T A x \quad A \text{ symmetric}$$

Quadratic function $f(x) = x^T A x + b^T x + c$

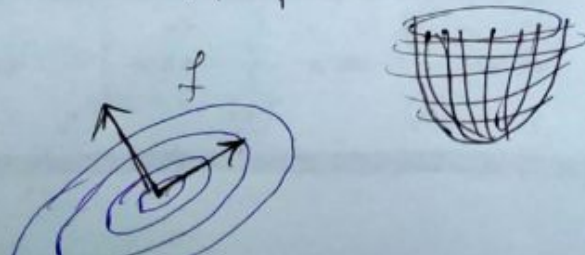
$$A \in \mathbb{R}^{n \times n}, \quad b \in \mathbb{R}^n, \quad c \in \mathbb{R}$$

symmetric

$$\nabla_f = 2Ax + \vec{b} \in \mathbb{R}^n$$

$$H_f = 2A \in \mathbb{R}^{n \times n}$$

A positive definite



Linear vs Quadratic Approximation



$$f(x) = \underline{x^T A x} + \underline{b^T x + c}$$

MA19 (V)

$$A = 0_{n \times n} \Rightarrow f: \text{affine}$$



Approximate f around x_0

1: linearization $f(x) = f(x_0) + \nabla_{|x_0}^T (x - x_0)$

2: *pr* approximate with a quadratic (better)

$$f(x) = f(x_0) + \nabla_{|x_0}^T (x - x_0) + \frac{1}{2} (x - x_0)^T H_{|x_0} (x - x_0)$$

$$f(x) = f(x_0) + \sum_{i=1}^n \frac{\partial f}{\partial x_i} (x_i - x_{0i}) + \frac{1}{2} \sum_i \sum_j (x_i - x_{0i})(x_j - x_{0j})$$

Taylor Series



K. N. Toosi
University of Technology

$$\begin{aligned} f(x) &= f(x_0) + \sum \frac{\partial f}{\partial x_i} (x_i - x_{0i}) + \frac{1}{2} \sum \sum (x_i - x_{0i}) (x_j - x_{0j}) \frac{\partial^2 f}{\partial x_i \partial x_j} \\ &+ \frac{1}{3!} \sum_i \sum_j \sum_{k=1}^n (x_i - x_{0i}) (x_j - x_{0j}) (x_k - x_{0k}) \frac{\partial^3 f}{\partial x_k \partial x_j \partial x_i} \\ &+ \frac{1}{4!} \sum \sum \sum \sum \\ &\vdots \end{aligned}$$

Exercise: Calculate Hessian



K. N. Toosi
University of Technology

$$f(x) = x^T A x + \underline{b^T x} + c = \sum_i \sum_j x_i x_j a_{ij} + \sum_i b_i x_i + c$$

A symmetric

$$\frac{\partial^2 f}{\partial x_i \partial x_i} = 2a_{ij}$$

$$D[u]f = 2 u^T A x + b^T u$$

$$\begin{aligned} D[v](D[u]f) &= 2 D[v](u^T A x) + D[v](\cancel{b^T u}^0) \\ &= 2 \frac{d}{d\alpha} u^T A (x + \alpha v) \Big|_{\alpha=0} = 2 u^T A v = 2 v^T A u \\ &= v^T \underbrace{(2A)}_{\text{Hessian}} u \end{aligned}$$

A symmetric

$$f(x) = x^T x x^T A x$$

Exercise: Calculate Hessian

Calculate Hessian for

$$f(x) = x^T x x^T A x$$



K. N. Toosi
University of Technology