

Mathematics for AI

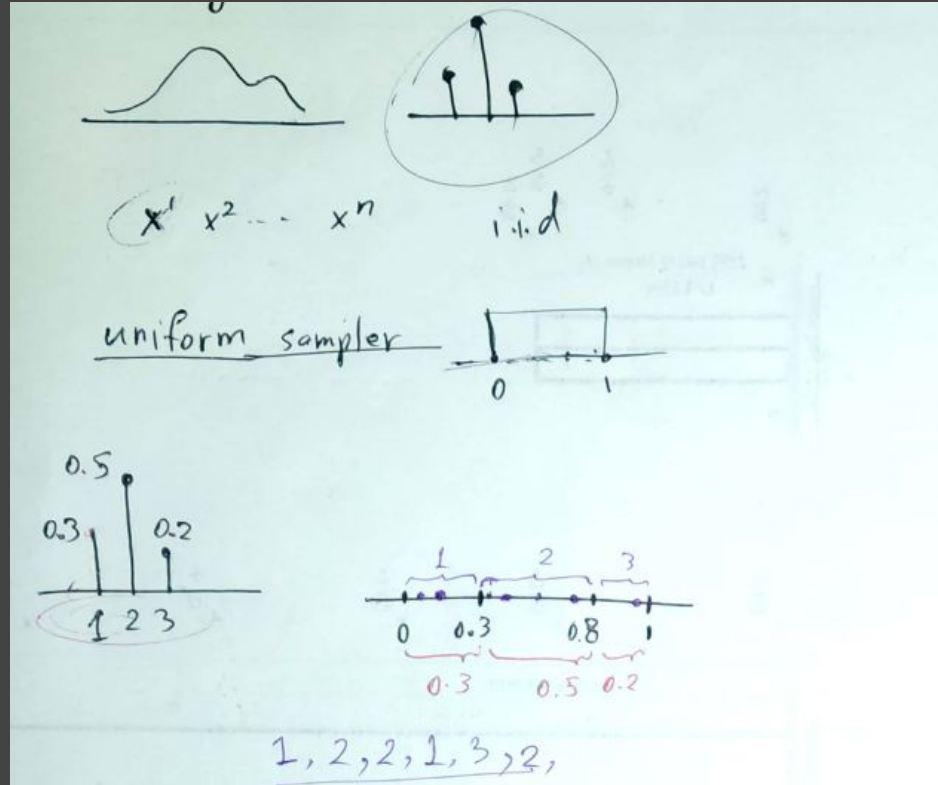
Lecture 26

Sampling (Cont.)

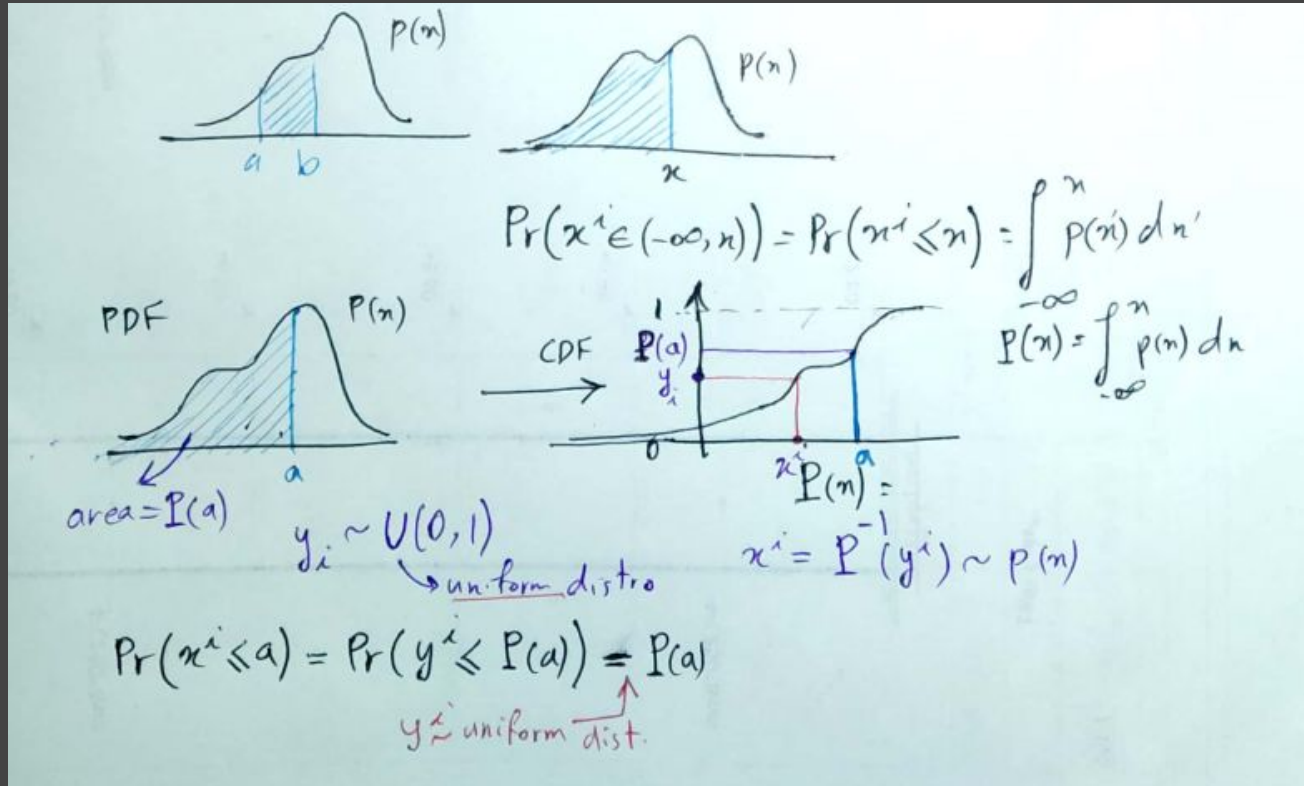
Sampling (Review)



K. N. Toosi
University of Technology



Sampling Continuous Distributions



Sampling Multivariable Distributions



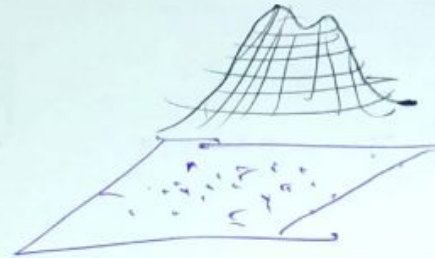
What About 2D & NP distributions?

$P(x, y) \longrightarrow$ sample $(x^1, y^1), (x^2, y^2) \dots, (x^m, y^m)$
 $P\left(\begin{bmatrix} x \\ y \end{bmatrix}\right)$

$$P(X) = P\left(\begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}\right) = P(X_1, X_2, \dots, X_n)$$

sample X^1, X^2, \dots, X^m

$$\begin{bmatrix} X_1^1 \\ X_2^1 \\ \vdots \\ X_n^1 \end{bmatrix}, \begin{bmatrix} X_1^2 \\ X_2^2 \\ \vdots \\ X_n^2 \end{bmatrix}, \dots, \begin{bmatrix} X_1^m \\ X_2^m \\ \vdots \\ X_n^m \end{bmatrix}$$



Sampling Multivariable Distributions - Independent Case



$$P(X) = P(X_1, \dots, X_n) = \underbrace{p_1(X_1)} \underbrace{p_2(X_2)} \dots \underbrace{p_n(X_n)}$$

$$\left. \begin{array}{l} X_1^i \sim p_1 \\ X_2^i \sim p_2 \\ \vdots \\ X_n^i \sim p_n \end{array} \right\} \Rightarrow (X_1^i, X_2^i, \dots, X_n^i) \sim P$$

Sampling Multivariable Distributions - Using Chain Rule



what if variables are not independent?

$p(n, y)$, x, y are not independent.

$$p(n, y) = p(y|x) p(n) \quad \begin{array}{l} \longrightarrow p(n) = \sum_y p(n, y) \\ \longrightarrow p(y|x) = \frac{p(n, y)}{\sum_{y'} p(n, y')} = \frac{p(n, y)}{\sum_{y'} p(n, y')} \end{array}$$

x^i = take a sample from $p(n)$

y^i = take a sample from $p(y|x^i)$

$\Rightarrow (x^i, y^i)$ is a sample from $p(n, y)$

$$\begin{aligned} \Pr(X=x^i, Y=y^i) &= \Pr(X=x^i) \Pr(Y=y^i | X=x^i) \\ &= p(n^i) p(y^i | n^i) = p(n^i, y^i) \end{aligned}$$

Sampling Multivariable Distributions - Using Chain Rule



$$\begin{aligned} P(X_1, X_2, \dots, X_n) &= P(X_n | X_1 - X_{n-1}) P(X_1, X_2, \dots, X_{n-1}) \quad \text{MA24 III} \\ &= P(X_n | X_1 - X_{n-1}) P(X_{n-1} | X_1 - X_{n-2}) P(X_1 - X_{n-2}) \\ &\quad \vdots \end{aligned}$$

$$\begin{aligned} P(X_1, X_2, \dots, X_n) &= P(\underline{X_n} | X_1 - X_{n-1}) P(\underline{X_{n-1}} | X_1 - X_{n-2}) \\ &\quad P(\underline{X_{n-2}} | X_1 - X_{n-3}) \dots P(\underline{X_3} | X_1, X_2) P(\underline{X_2} | X_1) P(\underline{X_1}) \end{aligned}$$

$$X_1^i \sim P(X_1)$$

$$X_2^i \sim P(X_2 | X_1^i)$$

$$X_3^i \sim P(X_3 | X_2^i, X_1^i)$$

\vdots

$$X_{n-1}^i \sim P(X_{n-1} | X_1^i, X_2^i, \dots, X_{n-2}^i)$$

$$X_n^i \sim P(X_n | X_1^i, X_2^i, \dots, X_{n-1}^i)$$

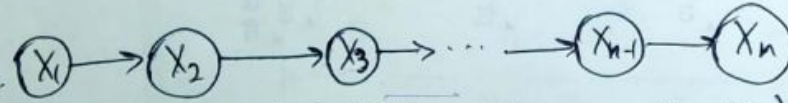
might be
hard/impossible
to compute.

$$\Rightarrow (X_1^i, X_2^i, \dots, X_n^i) \sim P(X_1, X_2, \dots, X_n)$$

Example: Sampling from a Markov Chain



$X_1, X_2, \dots, X_n, \dots$



$$\forall t \quad P(X_t | X_{t-1}, X_{t-2}, \dots, X_2, X_1) = P(X_t | X_{t-1})$$

Markov Property (for Markov chains)

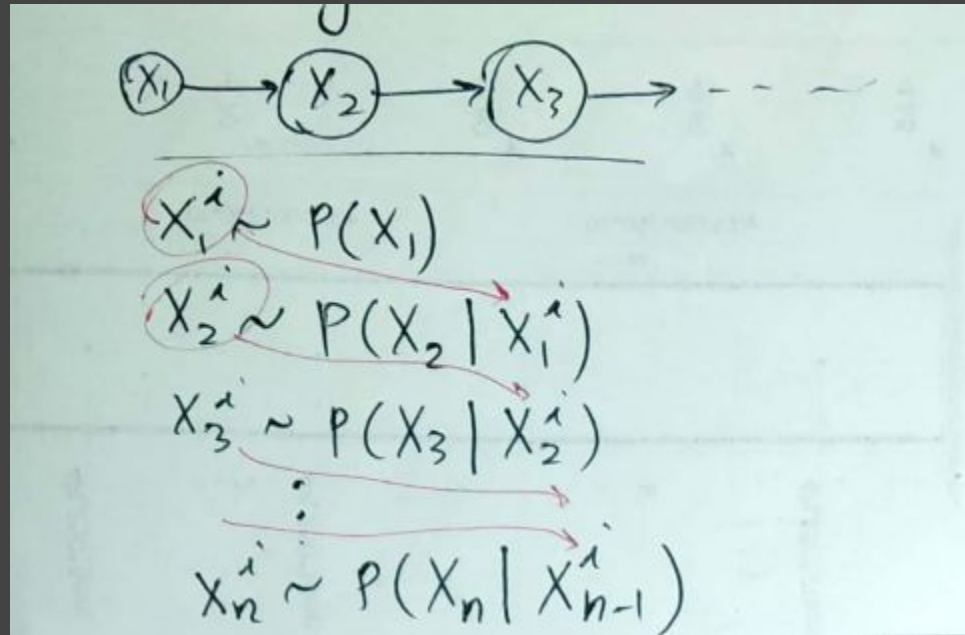
X_t is conditionally independent of $X_{t-2}, X_{t-3}, \dots, X_2, X_1$ given X_{t-1} .

$$\begin{aligned} P(X_1, X_2, \dots, X_n) &= P(X_n | X_1 - X_{n-1}) P(X_{n-1} | X_1 - X_{n-2}) \dots \\ &\quad \dots P(X_3 | X_2, X_1) P(X_2 | X_1) P(X_1) \\ &= P(X_n | X_{n-1}) P(X_{n-1} | X_{n-2}) \dots P(X_3 | X_2) \\ &\quad P(X_2 | X_1) P(X_1) \end{aligned}$$

Example: Sampling from a Markov Chain



K. N. Toosi
University of Technology



Sampling Using Change of Variables



$$P_X(X) \quad X = (X_1, X_2, \dots, X_n)$$

$$X = f(Y)$$

We can ~~write~~ write the random variable X as

$X = f(Y)$ for some function f , where $Y \sim P_Y(Y)$

& $P_Y(Y)$ is easy to sample from. ~~E.g. $P_Y(Y)$~~

$$Y^i \sim P_Y(Y)$$

$$X^i = f(Y^i)$$

$P_Y(Y)$ is easy to sample from

↳ Example $P_Y(Y) = P_Y(Y_1, Y_2, \dots, Y_n)$ is a Markov chain

↳ Example $P_Y(Y) = P_Y(Y_1, Y_2, \dots, Y_n) = P(Y_1) P(Y_2) \dots P(Y_n)$
 Y_1, Y_2, \dots, Y_n are independent.

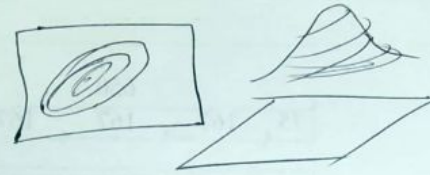
Example: Multivariable Gaussian Distribution



K. N. Toosi
University of Technology

Example:

Draw samples from
a multivariable



Gaussian distribution $N(\mathbf{0}, \Sigma)$

$$Y \sim N\left(0, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = N(0, I)$$

$$X \sim N(0, \Sigma)$$

$Y \sim N(0, I) \rightarrow$ standard normal distribution

$$Y = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix}$$

$N(0, I)$ is easy to sample

from because Y_1, Y_2, \dots, Y_n
are independent.

Example: Multivariable Gaussian Distribution



are independent
Let Y^i be a sample from $N(0, I)$

$$X^i = AY^i \quad AY \text{ is a Gaussian distribution}$$

$\hookrightarrow n \times n$ matrix

$$X = AY \quad \mu_X = E\{AY\} = AE\{Y\} = \vec{0}$$

$$\Sigma_X = \text{Cov}\{AY\} = A \text{Cov}\{Y\} A^T \\ = A I A^T = AA^T$$

Choose A such that $AA^T = \Sigma$.

Σ covariance matrix \Rightarrow Positive (semi) definite.

Decompose Σ into AA^T

there are many choices for A

for any orthogonal H : $AA^T = AH H^{-1} A = AH H^T A^T = AH(AH)^T$

Example: Multivariable Gaussian Distribution



MA26 (VI) K. N. Toosi
University of Technology

⇒ Draw samples from $N(0, \Sigma)$
 X^1, X^2, \dots, X^m

1- Decompose Σ as $\Sigma = AA^T$

for $i = 1 \dots m$:

$$Y^i \sim N(\vec{0}, I)$$

$$X^i = AY^i$$

⇒ X^i are samples from $N(0, \Sigma)$

Using Cholesky Decomposition



$$X^i = AY^i$$

\mathbb{R}^n $\mathbb{R}^{n \times n}$ \mathbb{R}^n

we need N^2 multiplications

$$\Sigma = AA^T$$

Cholesky Decomposition

$$\Sigma = LL^T$$

positive semi-definite lower-triangular

$$X^i = LY^i$$

$\frac{N(N+1)}{2}$ multiplications

Example: Multivariable Gaussian Distribution



K. N. Toosi
University of Technology

Draw Samples from $N(\mu, \Sigma)$:

$$\Sigma = AA^T$$

$$X^i = AY^i + \mu$$

$$L = \text{np.linalg.cholesky}(\Sigma)$$

$$Y_S = [Y^1 - Y^m] = \text{np.random.randn}(n, m)$$

$$X_S = \text{~~A~~ } L @ Y_S + \mu$$

`mu.reshape((-1,1))`

~~NA~~ Markov Chain Monte Carlo
(MCMC)

Markov Chain Monte Carlo methods



K. N. Toosi
University of Technology