

Mathematics for AI

Lecture 33

Convex Optimization, Duality examples,
Suboptimality Check, KKT conditions

Convex Optimization (Abstract form)



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~~Convex~~ Convex Optimization

$\min f(x)$ subject to $x \in C$ } abstract form
 C is a convex set.

Convex Optimization (Standard form)



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Convex Optimization (standard form)

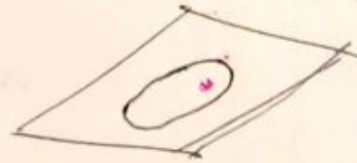
min $f(x)$ subject to $g_i(x) \leq 0$ $i=1,2,\dots,p$

$$Ax = b$$

$$A \in \mathbb{R}^{q \times n}$$
$$b \in \mathbb{R}^q$$

f convex

g_i convex



for most convex optimization problems strong duality holds. (Slater's conditions, etc.)

$$z^* = y^*$$

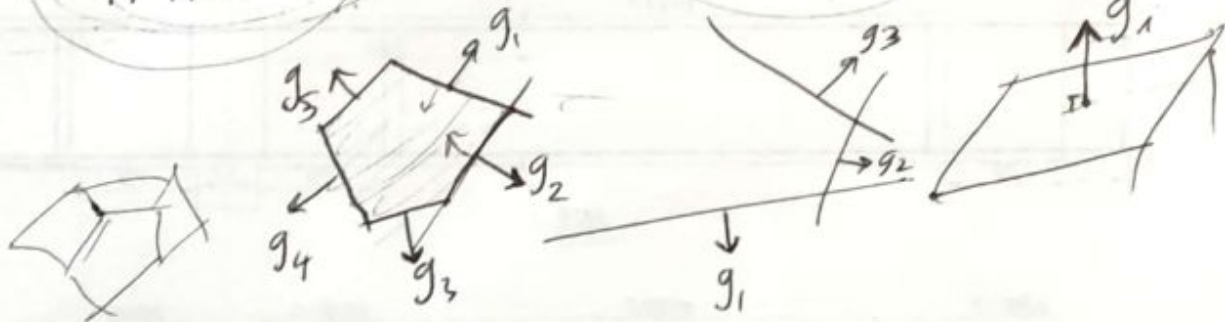
Linear Programming (LP)



Linear Program

$$\begin{aligned} \min_x \quad & a^T x + b \\ \text{s.t.} \quad & Gx \leq \vec{c} \\ & Hx = d \end{aligned}$$

$$\begin{aligned} \min_x \quad & a^T x + b \\ & g_i^T x \leq c_i \quad i=1 \dots q \\ & h_i^T x = d_i \quad i=1 \dots p \end{aligned}$$



Different forms of a Linear Program



$\min_x a^T x + b$ $Gx \leq c$	$Hx = d$	$Hx \leq d$ $Hx \geq d$ <hr/> $Hx \leq d$ $(-H)x \leq -d$
$\min_x a^T x + b$ $Hx = d$ $x \geq 0$	$\min_x a^T x + b$ $Hx = d$ $Gx \leq c$ $x \geq 0$	$\max_x a^T x + b$ $Gx \leq c$ $Hx = d$

Quadratic Programming



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$$\min x^T H x + g^T x + p$$

$$Gx \geq c$$

$$Ax = b$$

H : positive semi-definite

SVM

Remember: Dual Problem



Reminder: Dual Problem

$y^* = \min_x f(x)$ <p>subject to</p> $g(x) \leq \vec{0}$ $h(x) = \vec{0}$	Primal	$z^* = \max_{\lambda, \mu} f^*(\lambda, \mu)$ <p>subject to</p> $\lambda \geq 0$	Obj. Dual problem
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Lagrangian

$$L(x, \lambda, \mu) = f(x) + \lambda^T g(x) + \mu^T h(x)$$

$$g(x) \leq 0, h(x) = 0, \lambda \geq 0 \Rightarrow L(x, \lambda, \mu) \leq f(x)$$

$$f^*(\lambda, \mu) = \min_x L(x, \lambda, \mu)$$

$z^* \leq y^*$ weak duality / $y^* = z^*$ duality gap

if $z^* = y^* \Rightarrow$ strong duality hold \Rightarrow duality gap = 0

Suboptimality check



$z^* \leq y^*$ weak duality / $y^* - z^*$ duality gap
 if $z^* = y^* \Rightarrow$ strong duality hold \Rightarrow duality gap = 0

ϵ -suboptimal solution: $\tilde{x} \quad g(\tilde{x}) \leq 0, h(\tilde{x}) = 0, f(\tilde{x}) - y^* \leq \epsilon$

$x, \mu, \lambda: g(x) \leq 0, h(x) = 0, \lambda \geq 0 \quad f(x) \geq f^*(\lambda, \mu)$

stop when $f(x) - y^* \leq f(x) - f^*(\lambda, \mu) \leq \epsilon$

stop when $f(x) - f^*(\lambda, \mu) \leq \epsilon$

\Rightarrow

strong duality

Suboptimality



$z^* \leq y^*$ weak duality / $y^* - z^*$ duality gap
 if $z^* = y^* \Rightarrow$ strong duality hold \Rightarrow duality gap = 0

ϵ -suboptimal solution: $\tilde{x} \quad g(\tilde{x}) \leq 0, h(\tilde{x}) = 0, f(\tilde{x}) - y^* \leq \epsilon$
 $x, \mu, \lambda: g(x) \leq 0, h(x) = 0, \lambda \geq 0 \quad f(x) \geq f^*(\lambda, \mu)$
 stop when $f(x) - y^* \leq f(x) - f^*(\lambda, \mu) \leq \epsilon$
 stop when $f(x) - f^*(\lambda, \mu) \leq \epsilon$

~~stop when~~ $f(x) - y^* \leq f(x) - f^*(\lambda, \mu) \leq \epsilon$

strong duality

Dual of a QP



Dual for QP

$$\min_x \frac{1}{2} x^T H x + g^T x \quad \text{s.t.} \quad Gx \leq c, \quad Ax = b$$

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$$L(x, \lambda, \mu) = \frac{1}{2} x^T H x + g^T x + \lambda^T (Gx - c) + \mu^T (Ax - b)$$

$$f^*(\lambda, \mu) = \min_x L(x, \lambda, \mu)$$

$$v^T x \Rightarrow v$$

$$L(x, \lambda, \mu) = \frac{1}{2} x^T H x + (g + G^T \lambda + A^T \mu)^T x - \lambda^T c - \mu^T b$$

$$\frac{\partial L}{\partial x} = Hx + g + G^T \lambda + A^T \mu = 0 \Rightarrow x = -H^{-1}(g + G^T \lambda + A^T \mu)$$

Dual of a QP (simple case: no equality constraints)



⇒ حالت ساده، مقیود مساوی نداریم

$$\begin{aligned}
 \cancel{L} \times f^*(\lambda) &= \frac{1}{2} (g + G^T \lambda)^T H^{-1} (g + G^T \lambda) \\
 &\quad - (g + G^T \lambda)^T H^{-1} (g + G^T \lambda) - \lambda^T c \\
 &= -\frac{1}{2} (g + G^T \lambda)^T H^{-1} (g + G^T \lambda)
 \end{aligned}$$

$$f^*(\lambda) = -\frac{1}{2} \lambda^T G H^{-1} G^T \lambda - \underbrace{g^T H^{-1} G^T}_{\text{PD}} \lambda - \frac{1}{2} g^T H^{-1} g - c^T \lambda$$

dual problem

$$\begin{aligned}
 \max_{\lambda} \quad & -\frac{1}{2} \lambda^T \underbrace{G H^{-1} G^T}_{\text{PD}} \lambda - g^T H^{-1} G^T \lambda - \frac{1}{2} g^T H^{-1} g \\
 \text{s.t.} \quad & \lambda \geq 0
 \end{aligned}$$

Dual of a QP (General Case)



$$\min \frac{1}{2} x^T H x + g^T x \quad \text{s.t.} \quad Gx \preceq c, \quad Ax = b$$

$$\begin{aligned} L(x, \lambda, \mu) &= \frac{1}{2} x^T H x + g^T x + \lambda^T (Gx - c) + \mu^T (Ax - b) \\ &= \frac{1}{2} x^T H x + (g + G^T \lambda + A^T \mu)^T x - \lambda^T c - \mu^T b \end{aligned}$$

$$\frac{\partial L}{\partial x} = Hx + (g + G^T \lambda + A^T \mu) = 0$$

$$\Rightarrow x^* = -H^{-1} (g + G^T \lambda + A^T \mu)$$

Dual of a QP (General Case)



$$\frac{\partial L}{\partial x} = Hx + (g + G^T \lambda + A^T \mu) = 0$$
$$\Rightarrow x^* = -H^{-1}(g + G^T \lambda + A^T \mu)$$

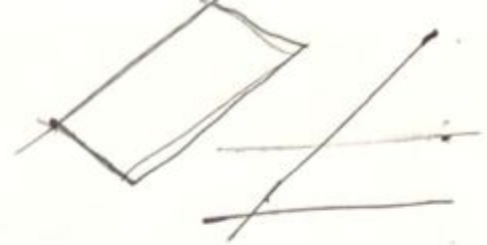
$$f^*(\lambda, \mu) = \min_x L(x, \lambda, \mu) = L(x^*, \lambda, \mu)$$
$$= \frac{1}{2} (g + G^T \lambda + A^T \mu)^T H^{-1} H H^{-1} (g + G^T \lambda + A^T \mu)$$
$$+ (g + G^T \lambda + A^T \mu)^T H^{-1} (g + G^T \lambda + A^T \mu) - \lambda^T c - \mu^T b$$
$$= -\frac{1}{2} (g + G^T \lambda + A^T \mu)^T H^{-1} (g + G^T \lambda + A^T \mu) - \lambda^T c - \mu^T b$$

$$\begin{bmatrix} \lambda \\ \mu \end{bmatrix}^T \underbrace{\begin{bmatrix} G^T \\ A^T \end{bmatrix}^T H^{-1} \begin{bmatrix} G^T \\ A^T \end{bmatrix}}_{\text{PD (or PSD)}} \begin{bmatrix} \lambda \\ \mu \end{bmatrix} - \underbrace{[c^T \ b^T]}_{\text{PD (or PSD)}} \begin{bmatrix} \lambda \\ \mu \end{bmatrix} - \frac{1}{2} g^T H^{-1} g$$

Dual of an LP



$$\begin{aligned} \min_x \quad & c^T x \\ & \cancel{Gx \leq d} \quad Gx \leq d \\ & Ax = b \end{aligned}$$



$$L(x, \lambda, \mu) = c^T x + \lambda^T (Gx - d) + \mu^T (Ax - b)$$

$$= (c + G^T \lambda + A^T \mu)^T x - \lambda^T d - \mu^T b$$

$$f^*(\lambda, \mu) = \min_x L(x, \lambda, \mu) = \begin{cases} -\infty & \text{if } c + G^T \lambda + A^T \mu \neq 0 \\ -\lambda^T d - \mu^T b & \text{if } c + G^T \lambda + A^T \mu = 0 \end{cases}$$

Dual of an LP



$$f^*(\lambda, \mu) = \min_x L(x, \lambda, \mu) = \begin{cases} -\infty & \text{if } c + G^T \lambda + A^T \mu \neq 0 \\ -\lambda^T d - \mu^T b & \text{if } c + G^T \lambda + A^T \mu = 0 \end{cases}$$

dual problem:

$$\begin{aligned} \max_{\lambda, \mu} & f^*(\lambda, \mu) \\ \text{s.t.} & \lambda \geq 0 \end{aligned}$$

\equiv

$$\begin{aligned} \max & -d^T \lambda - b^T \mu \\ \text{s.t.} & \lambda \geq 0 \\ & G^T \lambda + A^T \mu + c = 0 \end{aligned}$$

$$\begin{aligned} \min_x & c^T x \\ & Gx \leq d \\ & Ax = b \end{aligned}$$

$$\begin{aligned} \max & -d^T \lambda - b^T \mu \\ & \lambda \geq 0 \\ & G^T \lambda + A^T \mu = -c \end{aligned}$$

Optimal primal and dual solutions



Assume that we have found ~~optimal~~ an optimal solution x^* for primal, and an optimal solution λ^*, μ^* for the dual problem

$$y^* = f_1(x^*)$$

$$z^* = f^*(\lambda^*, \mu^*)$$

Optimal primal and dual solutions



$$x^* = \underset{x}{\operatorname{argmin}} f(x) \quad \text{s.t.} \quad g(x) \leq 0, h(x) = 0$$

$$\lambda^*, \mu^* = \underset{\lambda, \mu}{\operatorname{argmin}} f^*(\lambda, \mu) \quad \text{s.t.} \quad \lambda \geq 0$$

Duality Gap = 0 $\Rightarrow f(x^*) = y^* = z^* = f^*(\lambda^*, \mu^*)$

Optimal primal and dual solutions



$$\begin{aligned} \text{Duality Gap} &= 0 \Rightarrow f(x^*) = y^* = z^* = f^*(\lambda^*, \mu^*) \\ f(x^*) &= f^*(\lambda^*, \mu^*) \\ &= \min_x L(x, \lambda^*, \mu^*) \\ &\stackrel{\text{I}}{\leq} L(x^*, \lambda^*, \mu^*) \\ &= f(x^*) + \lambda^{*T} g(x^*) + \mu^{*T} h(x^*) \\ &= f(x^*) + \lambda^{*T} g(x^*) + \cancel{f(x^*)} + \cancel{h(x^*)} \\ &= f(x^*) + \sum_{i=1}^q \lambda_i^* g_i(x^*) \\ &\stackrel{\text{II}}{\leq} f(x^*) \end{aligned}$$

$h(x^*) = 0$
 $g_i(x^*) \leq 0, \lambda_i^* \geq 0$

Optimal primal and dual solutions



$$\begin{aligned}
 f(x^*) &= f^*(\lambda^*, \mu^*) \\
 &= \min_x L(x, \lambda^*, \mu^*) \\
 &\stackrel{\text{I}}{\leq} L(x^*, \lambda^*, \mu^*) \\
 &= f(x^*) + \lambda^{*\top} g(x^*) + \mu^{*\top} h(x^*) \\
 &= f(x^*) + \lambda^{*\top} g(x^*) + \cancel{f(x^*)} + \cancel{0} \\
 &= f(x^*) + \sum_{i=1}^q \lambda_i^* g_i(x^*) \\
 &\stackrel{\text{II}}{\leq} f(x^*)
 \end{aligned}$$

$h(x^*) = 0$
 $g_i(x^*) \leq 0, \lambda_i^* \geq 0$

\Rightarrow

$$\text{I} \quad L(x^*, \lambda^*, \mu^*) = \min_x L(x, \lambda^*, \mu^*)$$

$$\text{II} \quad \sum_{i=1}^q \lambda_i^* g_i(x^*) = 0 \quad \xrightarrow[\lambda_i^* \geq 0, g_i(x^*) \leq 0]{} \lambda_i^* g_i(x^*) = 0 \quad \text{for all } i=1-q$$

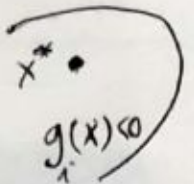
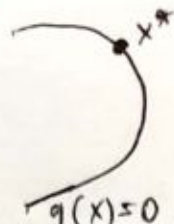
\Rightarrow find a solution to primal problem having a solution (λ^*, μ^*) to the dual problem

Optimal primal and dual solutions



$\leq f(x^*)$
 (I) $L(x^*, \lambda^*, \mu^*) = \min_x L(x, \lambda^*, \mu^*)$
 \Rightarrow find a solution to primal problem
 having a solution (λ^*, μ^*) to
 the dual problem

(II) $\sum_{i=1}^q \lambda_i^* g_i(x^*) = 0 \implies \lambda_i^* g_i(x^*) = 0$
 for all $i=1-q$
 $\lambda_i^* \geq 0$
 $g_i(x^*) \leq 0$

Find a primal solution from dual solutions



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(I) $L(x^*, \lambda^*, \mu^*) = \min_x L(x, \lambda^*, \mu^*)$
 \Rightarrow find a solution to primal problem
having a solution (λ^*, μ^*) to
the dual problem

Necessary conditions for optimality



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$$\left\{ \begin{array}{l} g(x^*) \geq 0 \\ h(x^*) = 0 \\ \lambda^* \geq 0 \\ \lambda_i^* g_i(x^*) = 0 \\ \cancel{x^*, \lambda^*, \mu^*} x^* = \arg \min L(x, \lambda^*, \mu^*) \end{array} \right.$$

Necessary conditions for optimality - differentiable case



for optimal x^*, λ^*, μ^*

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$$g(x^*) \leq 0$$

$$h(x^*) = 0$$

$$\lambda^* \geq 0$$

$$\lambda_i g_i(x^*) = 0$$

$$x^* = \arg \min_x L(x, \lambda^*, \mu^*) = \arg \min_x f(x) + \lambda^{*T} g(x) + \mu^{*T} h(x)$$

$$= \arg \min_x f(x) + \sum \lambda_i^* g_i(x) + \sum \mu_i^* h_i(x)$$

f, g_i

h_i

differentiable

$$\nabla f(x^*) + \sum \lambda_i^* \nabla g_i(x^*) + \sum \mu_i^* \nabla h_i(x^*) = 0$$

Karush-Kuhn-Tucker (KKT) Conditions



① Necessary conditions for optimal x^* , λ^* , μ^*

$$g(x^*) \leq 0$$

$$h(x^*) = 0$$

$$\lambda^* \geq 0$$

$$\lambda_i^* g_i(x^*) = 0 \quad i=1, 2, \dots, q$$

$$\nabla f(x^*) + \sum \lambda_i^* \nabla g_i(x^*) + \sum \mu_i^* \nabla h_i(x^*) = 0$$

Karush - Kuhn - Tucker (KKT)
conditions

Sometimes it is also sufficient for optimality