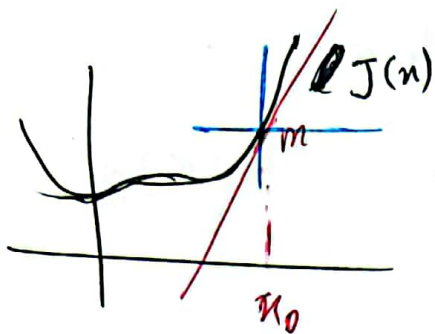


linearization & differentiability

MAIF (I)



$$\lim_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0} = m$$

$$J(x) - J(x_0) = m(x - x_0)$$

$$f(x) \approx f(x_0) + m(x - x_0)$$

\exists a linear map $l: \mathbb{R} \rightarrow \mathbb{R}$

$$\lim_{x \rightarrow x_0} \frac{|f(x) - f(x_0) - l(x - x_0)|}{|x - x_0|} = 0$$

$$l \text{ linear} \Rightarrow l(x - x_0) = \vec{m}(x - x_0)$$

$$f: \mathbb{R} \rightarrow \mathbb{R}^n$$

$$f(x) = \begin{bmatrix} f_1(x) \\ f_2(x) \\ \vdots \\ f_n(x) \end{bmatrix}$$

$$f' = \begin{bmatrix} f_1'(x) \\ f_2'(x) \\ \vdots \\ f_n'(x) \end{bmatrix} \in \mathbb{R}^n$$

$$\lim_{x \rightarrow x_0} \frac{|f(x) - f(x_0) - l(x - x_0)|}{|x - x_0|} = 0$$

$$\lim_{x \rightarrow x_0} \left| \frac{f(x) - f(x_0)}{x - x_0} - \frac{l(x - x_0)}{x - x_0} \right|$$

$$l: \mathbb{R} \rightarrow \mathbb{R}^n$$

$$l(x) = \vec{m} x$$

$$\vec{m} \begin{matrix} \downarrow \\ n \times 1 \end{matrix}$$

⊙ Multivariable functions (real valued) MA17 (II)

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$f(x_1, x_2, \dots, x_n) = f\left(\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}\right) = f(\vec{x})$$

$\vec{x} \in \mathbb{R}^n$

$$f(x, y) = \log(1+|x|) e^y$$

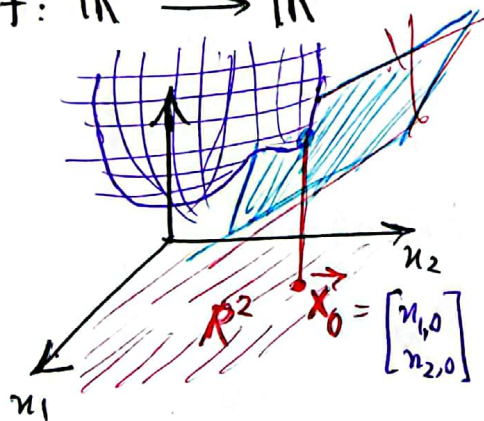
$$f: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$$

$$f(\vec{x}) = f\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \log(1+|x_1|) e^{x_2}$$

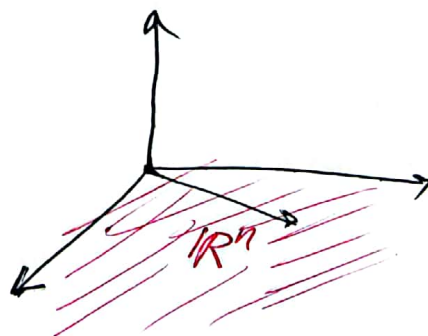
$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$f(\vec{x}) = \frac{1}{1 + e^{-a^T \vec{x}}}$$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$



$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$



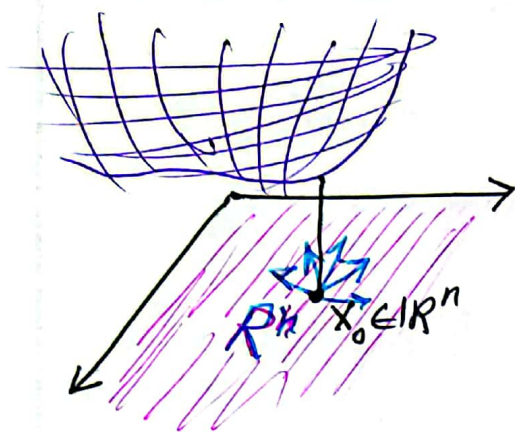
$$\underbrace{J(\vec{x}) - J(\vec{x}_0)}_{\mathbb{R}} = \underbrace{\vec{m}}_{1 \times 2}^T \underbrace{(\vec{x} - \vec{x}_0)}_{\mathbb{R}^2}$$

$$f(\vec{x}) - f(\vec{x}_0) \approx \vec{m}^T (\vec{x} - \vec{x}_0) \text{ around } \vec{x}_0$$

$$\exists f: \mathbb{R}^n \rightarrow \mathbb{R}$$

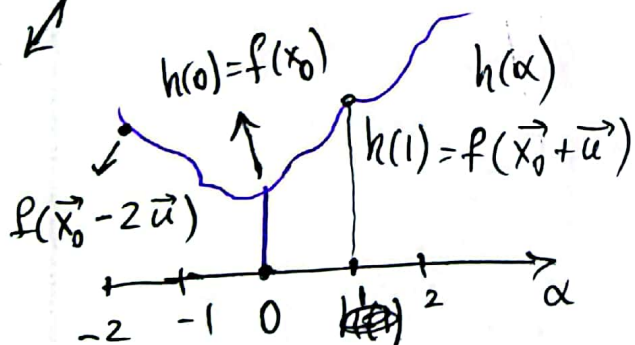
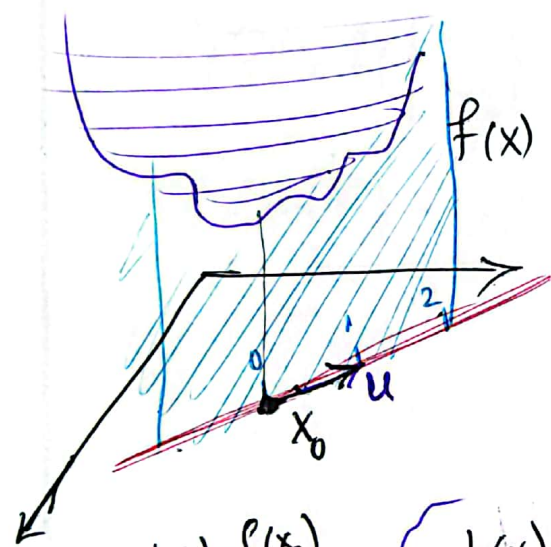
عقود

$f: \mathbb{R}^n \rightarrow \mathbb{R}$



directional derivative
of $f: \mathbb{R}^n \rightarrow \mathbb{R}$ at $\vec{x}_0 \in \mathbb{R}^n$
along the direction $\vec{u} \in \mathbb{R}^n$

$$\begin{aligned} \left. \frac{\partial f}{\partial \vec{u}} \right|_{x_0} &= \partial_{\vec{u}} f = D_{\vec{u}} f \Big|_{x_0} = (D_{\vec{u}} f)(x_0) \\ &= D[u]f \Big|_{x_0} = D[u]f(x_0) \\ &= (D[u]f)(x_0) \end{aligned}$$



$\|\vec{u}\| = 1$

$h: \mathbb{R} \rightarrow \mathbb{R}$

$h(\alpha) = f(\vec{x}_0 + \alpha \vec{u})$

$D[\vec{u}]f(\vec{x}_0) = \left. \frac{d}{d\alpha} h \right|_{\alpha=0} = h'(0)$

$= \left. \frac{d}{d\alpha} f(\vec{x}_0 + \alpha \vec{u}) \right|_{\alpha=0}$

easy to calculate

$= \lim_{\alpha \rightarrow 0} \frac{f(\vec{x}_0 + \alpha \vec{u}) - f(x_0)}{\alpha}$

Do away with $\|\vec{u}\|=1$. \vec{u} can be anything in \mathbb{R}^n .

$D[\vec{u}]f(\vec{x}_0) = \left. \frac{d}{d\alpha} f(\vec{x}_0 + \alpha \vec{u}) \right|_{\alpha=0}$

$D[2\vec{u}]f(\vec{x}_0) = \left. \frac{d}{d\alpha} f(\vec{x}_0 + \alpha 2\vec{u}) \right|_{\alpha=0} = 2 \left. \frac{d}{d\alpha} f(\vec{x}_0 + \alpha \vec{u}) \right|_{\alpha=0}$
 $= \lim_{\alpha \rightarrow 0} \frac{f(\vec{x}_0 + 2\alpha \vec{u}) - f(x_0)}{\alpha} = \lim_{2\alpha \rightarrow 0} 2 \frac{f(\vec{x}_0 + 2\alpha \vec{u}) - f(x_0)}{2\alpha}$

$D[\cdot]f(x_0) : \mathbb{R}^n \rightarrow \mathbb{R}$ (as a function of \vec{u}) MA17 (II)

Fixing x_0 , is $D[u]f(x_0)$ linear as a function of $\vec{u} \in \mathbb{R}^n$?

$$D[\beta u]f(x_0) = \beta D[u]f(x_0) \checkmark$$

$$D[u+v]f(x_0) \stackrel{?}{=} D[u]f(x_0) + D[v]f(x_0)$$

$f: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$f(\vec{x}) = f\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = x_1^2 \sin x_2$$

$$f(\vec{x} + \alpha \vec{u}) = f\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \alpha \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}\right) = (x_1 + \alpha u_1)^2 \sin(x_2 + \alpha u_2)$$

$$\frac{d}{d\alpha} f(\vec{x} + \alpha \vec{u}) \Big|_{\alpha=0} = 2(x_1 + \alpha u_1) u_1 \sin(x_2 + \alpha u_2) + (x_1 + \alpha u_1)^2 \cos(x_2 + \alpha u_2) u_2 \Big|_{\alpha=0}$$

$$= 2x_1 u_1 \sin(x_2) + u_2 x_1^2 \cos(x_2)$$

$$= \begin{bmatrix} 2x_1 \sin(x_2), & x_1^2 \cos(x_2) \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

2×1 2×1

$$\frac{d}{d\alpha} f(\vec{x} + \alpha(\vec{u} + \vec{v})) = \frac{d}{d\alpha} f\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \alpha \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \end{bmatrix}\right)$$

$$D[\vec{u} + \vec{v}]f(x) = D[\vec{u}]f(x) + D[\vec{v}]f(x)$$

For a differentiable function f at \vec{x}_0

$D[u]f(x_0)$ is linear as a function of \vec{u} .
 $\vec{u} \in \mathbb{R}^n$

$\exists M \in \mathbb{R} \Rightarrow D[u]f(x_0)$

$D[u]f(x_0)$ is linear as a function of $\vec{u} \in \mathbb{R}^n$ MAIT (V)

$$\exists M \in \mathbb{R}^{1 \times n} \quad D[u]f(x_0) = M \vec{u} = M(x_0) \vec{u}$$

$[m_1 \ m_2 \ \dots \ m_n]$ $1 \times n$ $n \times 1$

M is a function of \vec{x}_0

$$\exists \vec{m} \in \mathbb{R}^n \quad D[u]f(x_0) = \vec{m}^T \vec{u} = \langle \vec{m}, \vec{u} \rangle$$

$\vec{m} = \vec{m}(x_0)$ is call the gradient of f at \vec{x}_0 .

(گريڊينٽ)

How to compute the gradient vector at \vec{x}_0 ?
calculate

The hard way (usually)

$$\vec{m} \in \mathbb{R}^n \Rightarrow \vec{m} = \begin{bmatrix} m_1 \\ m_2 \\ \vdots \\ m_n \end{bmatrix}$$

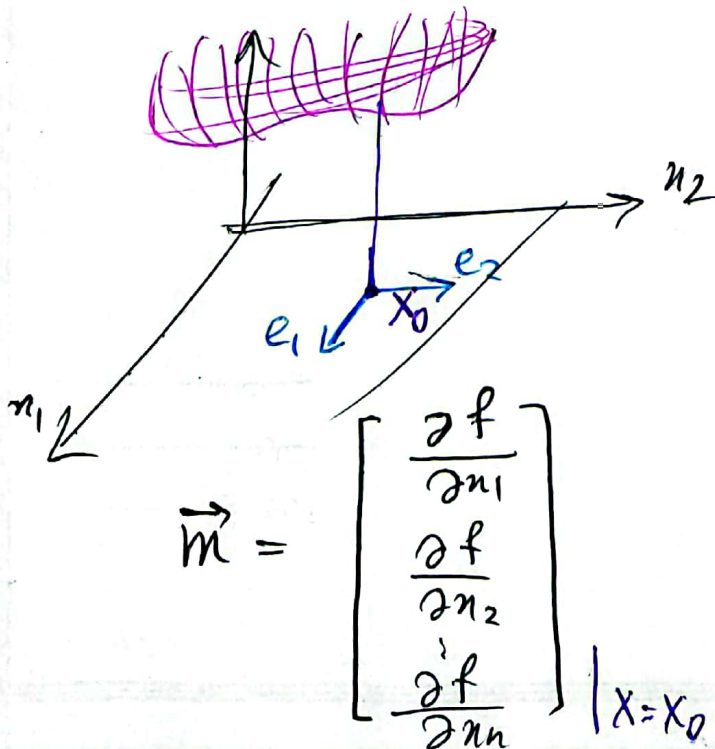
what is m_1 ?

$$m_1 = [m_1 \ m_2 \ \dots \ m_n] \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \\ e_1 \end{bmatrix} = m^T e_1 = D[e_1]f(x_0)$$

$$= \frac{\partial f}{\partial x_1} \Big|_{x_0}$$

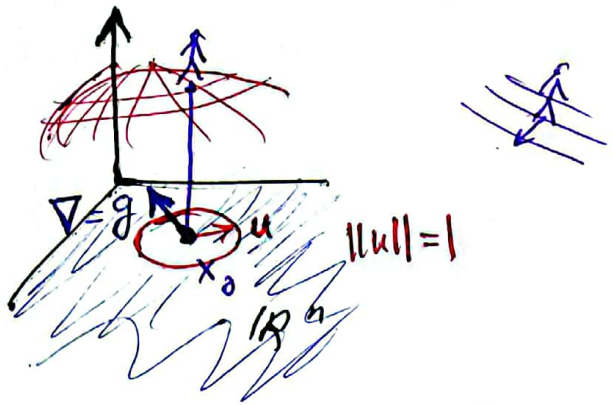
$$= \frac{d}{d\alpha} f\left(\vec{x}_0 + \alpha \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}\right)$$

$$= \frac{d}{d\alpha} f\left(\begin{bmatrix} x_1 + \alpha \\ x_2 \\ \vdots \\ x_n \end{bmatrix}\right)$$



$$\vec{m} = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix} \Big|_{x=x_0}$$

gradient is usually denoted by $\vec{\nabla} f|_{x_0}$
 $\nabla f(x_0)$ arg



$$\nabla = \begin{bmatrix} g_1 \\ g_2 \\ \vdots \\ g_n \end{bmatrix} \in \mathbb{R}^n$$

$$\max_{\|u\|=1} D[u]f(x_0) = \max_{\|u\|=1} \langle \vec{u}, \vec{\nabla} \rangle \quad \vec{u} = \frac{\vec{\nabla}}{\|\nabla\|}$$

$$\min_{\|u\|=1} D[u]f(x_0) = \min_{\|u\|=1} \langle \vec{u}, \vec{\nabla} \rangle \quad \vec{u} = \frac{-\vec{\nabla}}{\|\nabla\|}$$

$$\vec{u} = \frac{\vec{\nabla}}{\|\nabla\|}$$

$$\begin{aligned} \langle \vec{u}, \vec{\nabla} \rangle &= \left\langle \frac{\vec{\nabla}}{\|\nabla\|}, \vec{\nabla} \right\rangle \\ &= \frac{1}{\|\nabla\|} \langle \vec{\nabla}, \vec{\nabla} \rangle = \frac{\|\nabla\|^2}{\|\nabla\|} \\ &= \|\nabla\| \end{aligned}$$

$$u \perp \nabla \Rightarrow \langle \vec{u}, \vec{\nabla} \rangle = 0$$

