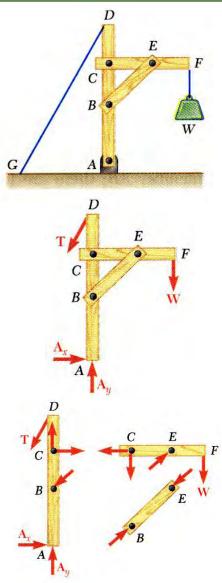
STATICS

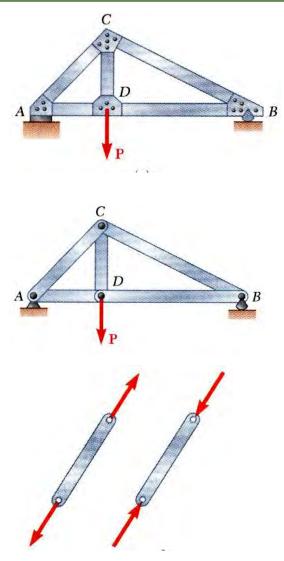
Analysis of Structures

Introduction



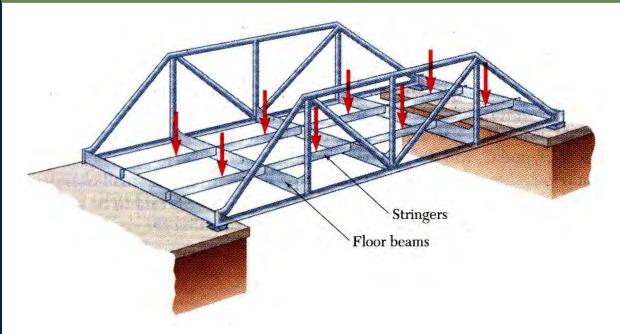
- For the equilibrium of structures made of several connected parts, the *internal forces* as well the *external forces* are considered.
- In the interaction between connected parts, Newton's 3rd Law states that the *forces of action and reaction* between bodies in contact have the same magnitude, same line of action, and opposite sense.
- Three categories of engineering structures are considered:
 a) Frames: contain at least one one multi-force member, i.e., member acted upon by 3 or more forces.
 - *b) Trusses*: formed from *two-force members*, i.e., straight members with end point connections
 - *c) Machines*: structures containing moving parts designed to transmit and modify forces.

Definition of a Truss



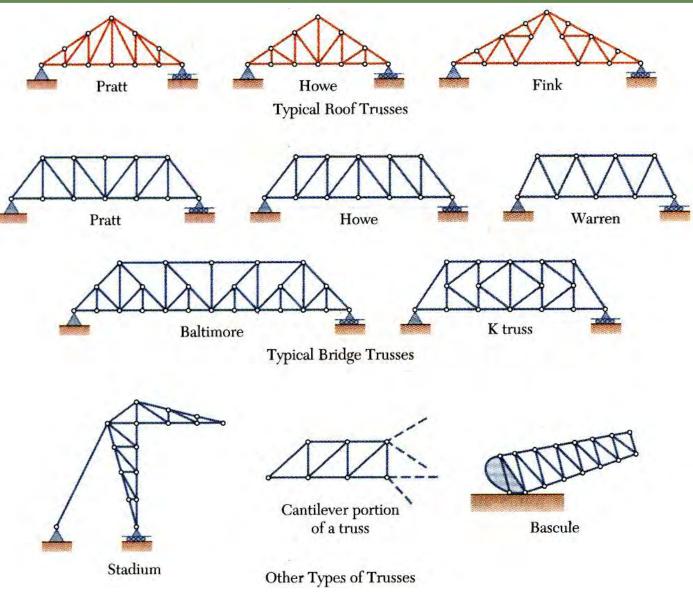
- A truss consists of straight members connected at joints. No member is continuous through a joint.
- Most structures are made of several trusses joined together to form a space framework. Each truss carries those loads which act in its plane and may be treated as a two-dimensional structure.
- Bolted or welded connections are assumed to be pinned together. Forces acting at the member ends reduce to a single force and no couple. Only *two-force members* are considered.
- When forces tend to pull the member apart, it is in *tension*. When the forces tend to compress the member, it is in *compression*.

Definition of a Truss

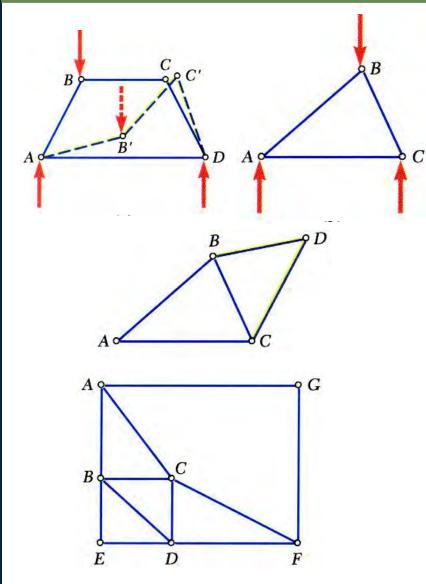


Members of a truss are slender and not capable of supporting large lateral loads. Loads must be applied at the joints.

Definition of a Truss

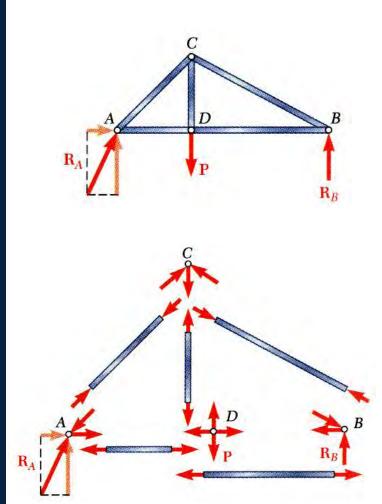


Simple Trusses



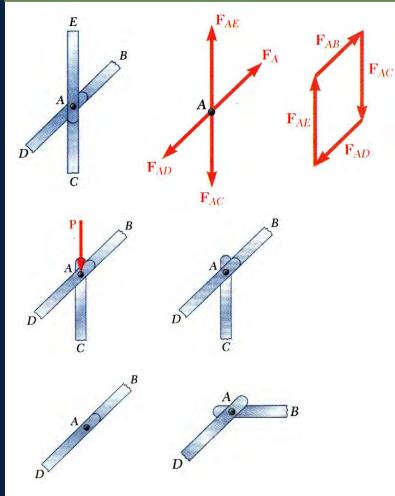
- A *rigid truss* will not collapse under the application of a load.
- A *simple truss* is constructed by successively adding two members and one connection to the basic triangular truss.
- In a simple truss, m = 2n 3 where m is the total number of members and n is the number of joints.

Analysis of Trusses by the Method of Joints

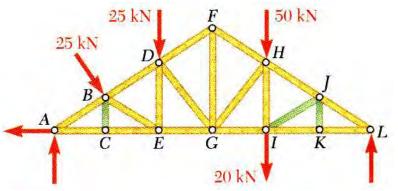


- Dismember the truss and create a freebody diagram for each member and pin.
- The two forces exerted on each member are equal, have the same line of action, and opposite sense.
- Forces exerted by a member on the pins or joints at its ends are directed along the member and equal and opposite.
- Conditions of equilibrium on the pins provide 2n equations for 2n unknowns. For a simple truss, 2n = m + 3. May solve for m member forces and 3 reaction forces at the supports.
- Conditions for equilibrium for the entire truss provide 3 additional equations which are not independent of the pin equations.

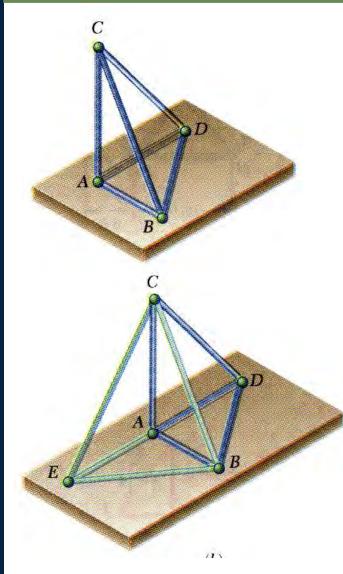
Joints Under Special Loading Conditions



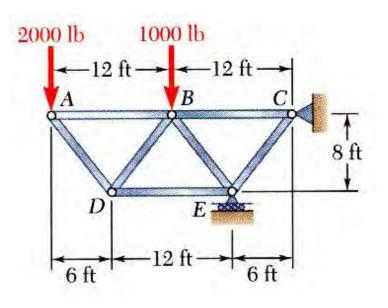
- Forces in opposite members intersecting in two straight lines at a joint are equal.
- The forces in two opposite members are equal when a load is aligned with a third member. The third member force is equal to the load (including zero load).
- The forces in two members connected at a joint are equal if the members are aligned and zero otherwise.
- Recognition of joints under special loading conditions simplifies a truss analysis.



Space Trusses



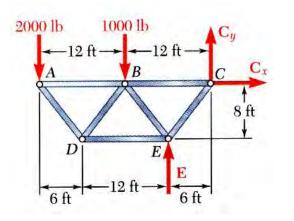
- An *elementary space truss* consists of 6 members connected at 4 joints to form a tetrahedron.
- A *simple space truss* is formed and can be extended when 3 new members and 1 joint are added at the same time.
- In a simple space truss, m = 3n 6 where *m* is the number of members and *n* is the number of joints.
- Conditions of equilibrium for the joints provide 3n equations. For a simple truss, 3n = m + 6 and the equations can be solved for m member forces and 6 support reactions.
- Equilibrium for the entire truss provides 6 additional equations which are not independent of the joint equations.



Using the method of joints, determine the force in each member of the truss.

SOLUTION:

- Based on a free-body diagram of the entire truss, solve the 3 equilibrium equations for the reactions at *E* and *C*.
- Joint *A* is subjected to only two unknown member forces. Determine these from the joint equilibrium requirements.
- In succession, determine unknown member forces at joints *D*, *B*, and *E* from joint equilibrium requirements.
- All member forces and support reactions are known at joint *C*. However, the joint equilibrium requirements may be applied to check the results.



SOLUTION:

• Based on a free-body diagram of the entire truss, solve the 3 equilibrium equations for the reactions at *E* and *C*.

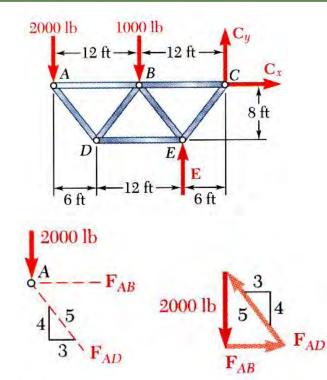
 $\sum M_C = 0$ = (2000 lb)(24 ft) + (1000 lb)(12 ft) - E(6 ft)

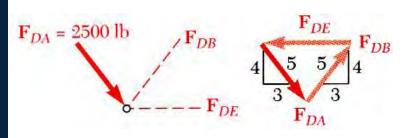
 $E = 10,000 \text{ lb} \uparrow$

$$\sum F_x = 0 = C_x \qquad \qquad C_x = 0$$

 $\sum F_y = 0 = -2000 \,\text{lb} - 1000 \,\text{lb} + 10,000 \,\text{lb} + C_y$

 $C_y = 7000 \, \text{lb} \downarrow$





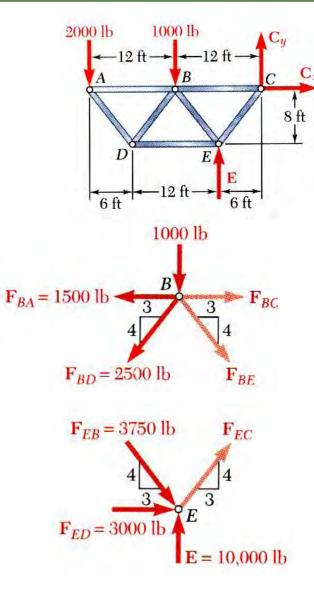
• Joint *A* is subjected to only two unknown member forces. Determine these from the joint equilibrium requirements.

$$\frac{2000 \text{ lb}}{4} = \frac{F_{AB}}{3} = \frac{F_{AD}}{5} \qquad \begin{array}{c} F_{AB} = 1500 \text{ lb } T \\ F_{AD} = 2500 \text{ lb } C \end{array}$$

• There are now only two unknown member forces at joint D.

$$F_{DB} = F_{DA}$$
$$F_{DE} = 2\left(\frac{3}{5}\right)F_{DA}$$

$$F_{DB} = 2500 \text{ lb } T$$
$$F_{DE} = 3000 \text{ lb } C$$



• There are now only two unknown member forces at joint B. Assume both are in tension.

$$\sum F_y = 0 = -1000 - \frac{4}{5}(2500) - \frac{4}{5}F_{BE}$$

$$F_{BE} = -3750 \text{ lb}$$

$$F_{BE} = 3750 \text{ lb} C$$

$$\sum F_x = 0 = F_{BC} - 1500 - \frac{3}{5}(2500) - \frac{3}{5}(3750)$$

$$F_{BC} = +5250 \text{ lb}$$

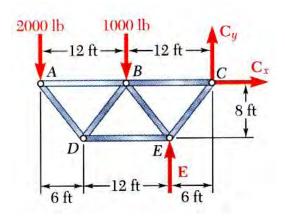
$$F_{BC} = 5250 \text{ lb} T$$

• There is one unknown member force at joint *E*. Assume the member is in tension.

$$\sum F_x = 0 = \frac{3}{5}F_{EC} + 3000 + \frac{3}{5}(3750)$$

$$F_{EC} = -8750 \text{ lb}$$

$$F_{EC} = 8750 \text{ lb}$$

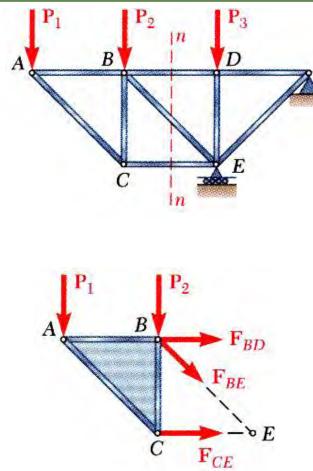


 $C_y = 7000 \text{ lb}$ $F_{CB} = 5250 \text{ lb}$ $C_x = 0$ $F_{CE} = 8750 \text{ lb}$

• All member forces and support reactions are known at joint *C*. However, the joint equilibrium requirements may be applied to check the results.

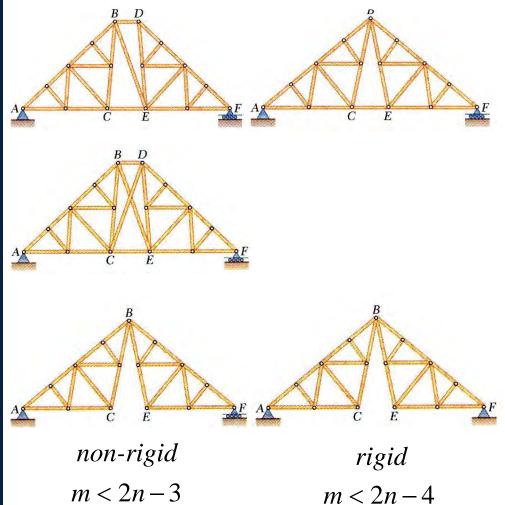
$$\sum F_x = -5250 + \frac{3}{5}(8750) = 0 \quad \text{(checks)}$$
$$\sum F_y = -7000 + \frac{4}{5}(8750) = 0 \quad \text{(checks)}$$

Analysis of Trusses by the Method of Sections



- When the force in only one member or the forces in a very few members are desired, the *method of sections* works well.
- To determine the force in member *BD*, *pass a section* through the truss as shown and create a free body diagram for the left side.
- With only three members cut by the section, the equations for static equilibrium may be applied to determine the unknown member forces, including F_{BD} .

Trusses Made of Several Simple Trusses

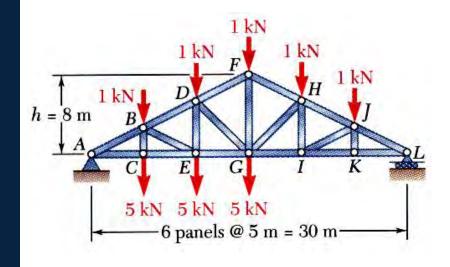


• *Compound trusses* are statically determinant, rigid, and completely constrained.

m = 2n - 3

- Truss contains a *redundant member* and is *statically indeterminate*. m > 2n - 3
- Additional reaction forces may be necessary for a rigid truss.
- Necessary but insufficient condition for a compound truss to be statically determinant, rigid, and completely constrained,

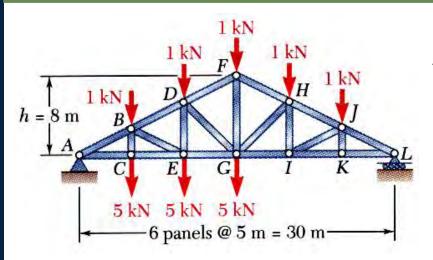
$$m + r = 2n$$



Determine the force in members *FH*, *GH*, and *GI*.

SOLUTION:

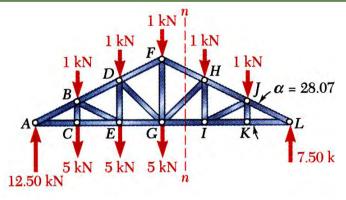
- Take the entire truss as a free body. Apply the conditions for static equilibrium to solve for the reactions at *A* and *L*.
- Pass a section through members *FH*, *GH*, and *GI* and take the right-hand section as a free body.
- Apply the conditions for static equilibrium to determine the desired member forces.



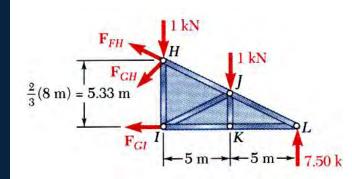
SOLUTION:

• Take the entire truss as a free body. Apply the conditions for static equilibrium to solve for the reactions at *A* and *L*.

$$\sum M_A = 0 = -(5 \text{ m})(6 \text{ kN}) - (10 \text{ m})(6 \text{ kN}) - (15 \text{ m})(6 \text{ kN}) -(20 \text{ m})(1 \text{ kN}) - (25 \text{ m})(1 \text{ kN}) + (25 \text{ m})L L = 7.5 \text{ kN} \uparrow \sum F_y = 0 = -20 \text{ kN} + L + A A = 12.5 \text{ kN} \uparrow$$



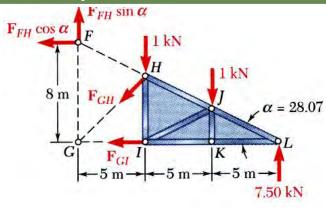
• Pass a section through members *FH*, *GH*, and *GI* and take the right-hand section as a free body.



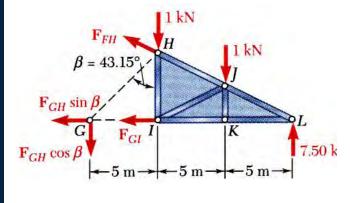
• Apply the conditions for static equilibrium to determine the desired member forces.

 $\sum M_{H} = 0$ (7.50 kN)(10 m) - (1 kN)(5 m) - F_{GI} (5.33 m) = 0 F_{GI} = +13.13 kN

 $F_{GI} = 13.13 \,\mathrm{kN} \, T$

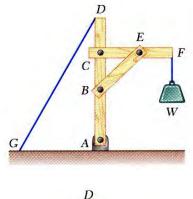


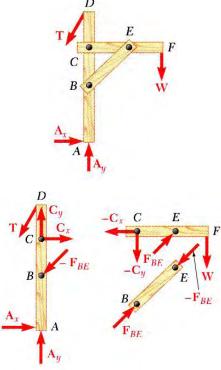
$$\tan \alpha = \frac{FG}{GL} = \frac{8 \text{ m}}{15 \text{ m}} = 0.5333 \qquad \alpha = 28.07^{\circ}$$
$$\sum M_G = 0$$
$$(7.5 \text{ kN})(15 \text{ m}) - (1 \text{ kN})(10 \text{ m}) - (1 \text{ kN})(5 \text{ m})$$
$$+ (F_{FH} \cos \alpha)(8 \text{ m}) = 0$$
$$F_{FH} = -13.82 \text{ kN}$$
$$F_{FH} = 13.82 \text{ kN}$$



$$\tan \beta = \frac{GI}{HI} = \frac{5 \text{ m}}{\frac{2}{3}(8 \text{ m})} = 0.9375 \qquad \beta = 43.15^{\circ}$$
$$\sum M_L = 0$$
$$(1 \text{ kN})(10 \text{ m}) + (1 \text{ kN})(5 \text{ m}) + (F_{GH} \cos \beta)(10 \text{ m}) = 0$$
$$F_{GH} = -1.371 \text{ kN}$$
$$F_{GH} = 1.371 \text{ kN}$$

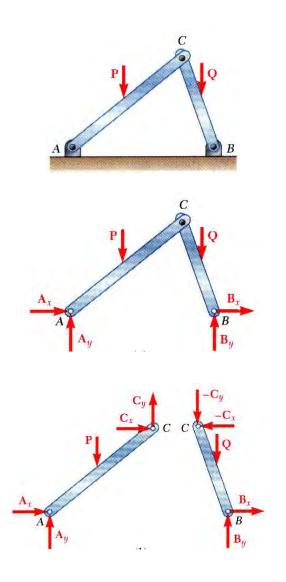
Analysis of Frames



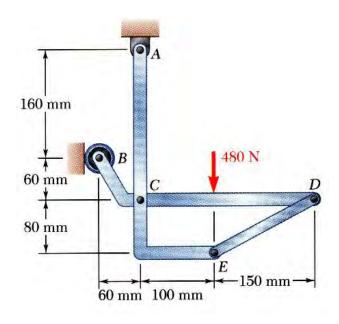


- *Frames* and *machines* are structures with at least one *multiforce* member. Frames are designed to support loads and are usually stationary. Machines contain moving parts and are designed to transmit and modify forces.
- A free body diagram of the complete frame is used to determine the external forces acting on the frame.
- Internal forces are determined by dismembering the frame and creating free-body diagrams for each component.
- Forces on two force members have known lines of action but unknown magnitude and sense.
- Forces on multiforce members have unknown magnitude and line of action. They must be represented with two unknown components.
- Forces between connected components are equal, have the same line of action, and opposite sense.

Frames Which Cease To Be Rigid When Detached From Their Supports



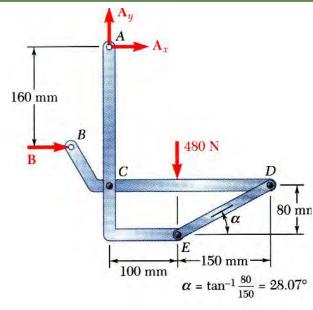
- Some frames may collapse if removed from their supports. Such frames can not be treated as rigid bodies.
- A free-body diagram of the complete frame indicates four unknown force components which can not be determined from the three equilibrium conditions.
- The frame must be considered as two distinct, but related, rigid bodies.
- With equal and opposite reactions at the contact point between members, the two free-body diagrams indicate 6 unknown force components.
- Equilibrium requirements for the two rigid bodies yield 6 independent equations.



Members *ACE* and *BCD* are connected by a pin at *C* and by the link *DE*. For the loading shown, determine the force in link *DE* and the components of the force exerted at *C* on member *BCD*.

SOLUTION:

- Create a free-body diagram for the complete frame and solve for the support reactions.
- Define a free-body diagram for member *BCD*. The force exerted by the link *DE* has a known line of action but unknown magnitude. It is determined by summing moments about *C*.
- With the force on the link *DE* known, the sum of forces in the *x* and *y* directions may be used to find the force components at *C*.
- With member *ACE* as a free-body, check the solution by summing moments about *A*.



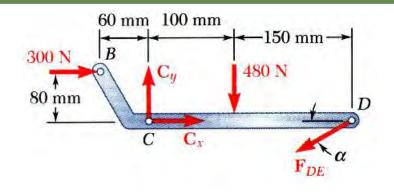
SOLUTION:

• Create a free-body diagram for the complete frame and solve for the support reactions.

$\sum F_y = 0 = A_y - 480 \text{ N}$	$A_y = 480 \text{ N} \uparrow$
$\sum M_A = 0 = -(480 \text{ N})(100 \text{ mm}) +$	$-B(160 \mathrm{mm})$
	$B = 300 \text{ N} \rightarrow$
$\sum F_x = 0 = B + A_x$	$A_x = -300 \text{ N} \leftarrow$

Note: $\alpha = \tan^{-1} \frac{80}{150} = 28.07^{\circ}$

• Define a free-body diagram for member *BCD*. The force exerted by the link *DE* has a known line of action but unknown magnitude. It is determined by summing moments about *C*.



$$\sum M_C = 0 = (F_{DE} \sin \alpha)(250 \text{ mm}) + (300 \text{ N})(60 \text{ mm}) + (480 \text{ N})(100 \text{ mm})$$

$$F_{DE} = -561 \text{ N}$$

$$F_{DE} = 561 \text{ N}$$

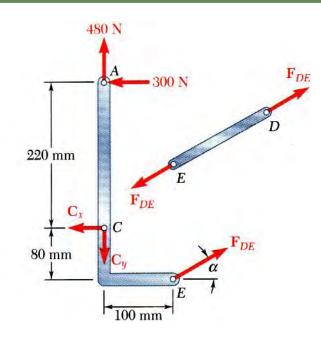
• Sum of forces in the *x* and *y* directions may be used to find the force components at *C*.

$$\sum F_x = 0 = C_x - F_{DE} \cos \alpha + 300 \text{ N}$$
$$0 = C_x - (-561 \text{ N}) \cos \alpha + 300 \text{ N}$$

$$\sum F_{y} = 0 = C_{y} - F_{DE} \sin \alpha - 480 \text{ N}$$
$$0 = C_{y} - (-561 \text{ N}) \sin \alpha - 480 \text{ N}$$

$$C_x = -795 \text{ N}$$

$$C_y = 216 \text{ N}$$

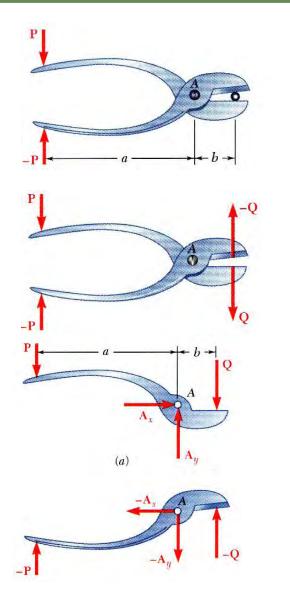


• With member *ACE* as a free-body, check the solution by summing moments about *A*.

 $\sum M_A = (F_{DE} \cos \alpha)(300 \text{ mm}) + (F_{DE} \sin \alpha)(100 \text{ mm}) - C_x(220 \text{ mm})$ $= (-561 \cos \alpha)(300 \text{ mm}) + (-561 \sin \alpha)(100 \text{ mm}) - (-795)(220 \text{ mm}) = 0$

(checks)

Machines



-Q

- Machines are structures designed to transmit and modify forces. Their main purpose is to transform *input forces* into *output forces*.
- Given the magnitude of *P*, determine the magnitude of *Q*.
 - Create a free-body diagram of the complete machine, including the reaction that the wire exerts.
 - The machine is a nonrigid structure. Use one of the components as a free-body.
 - Taking moments about A,

$$\sum M_A = 0 = aP - bQ \qquad Q = \frac{a}{b}P$$