

# Move-based Algorithms for the Optimization of an Isotropic Gradient MRF Model

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5 December 2012



Australian Government  
Department of Broadband,  
Communications and the Digital Economy  
Australian Research Council

NICTA Funding and Supporting Members and Partners



- Total Variation
- Current Methods
- The 3-clique Model
- Move-based Algorithms
- Main Theorem
- Conclusion

# Total Variation

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- good **regularizer**.

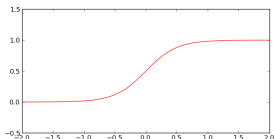
- good **regularizer**.
- For a function  $x: \Omega \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  Total Variation is defined as

$$\text{TV}(x) = \int_{\Omega} |\nabla_{\mathbf{t}} x(\mathbf{t})| d\mathbf{t}$$

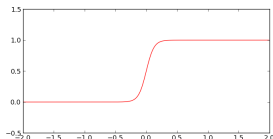
- good **regularizer**.
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$$\text{TV}(x) = \int_{\Omega} |\nabla_{\mathbf{t}} x(\mathbf{t})| d\mathbf{t}$$

- **discontinuity preserving** (edge preserving for images).



$x_1(t)$



$x_2(t)$

$$\text{TV}(x_1) = \text{TV}(x_2)$$

- Approximate Total Variation using an MRF,
- A set of nodes  $1, 2, \dots, n$ ,
- A set of labels  $\mathbf{x} = [x_1, x_2, \dots, x_n]$ ,  $x_i \in \mathcal{L}$ .
- Energy function

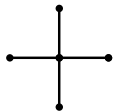
$$E(\mathbf{x}) = \sum_i f_i(x_i) + \tilde{T}V(\mathbf{x}),$$

- Approximate Magnitude of Gradient using **edge-based** potentials.

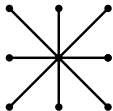
$$\tilde{T}V(\mathbf{x}) = \sum_{(i,j) \in \mathcal{C}^2} w_{ij} |x_i - x_j|$$

- Magnitude of Gradient (MoG) at each node  $i$  is approximated by

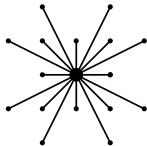
$$\text{MoG}(i) = \sum_{j \in \mathcal{N}_i} w_{ij} |x_i - x_j|$$



4 Neighbourhood

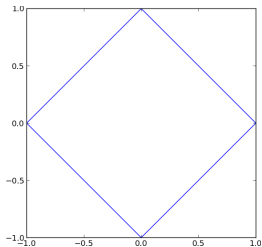


8 Neighbourhood

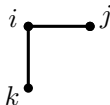
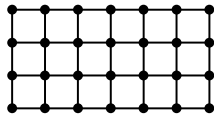


16 Neighbourhood

$$\text{MoG}(i) = |x_i - x_j| + |x_i - x_k|$$



$$\text{MoG}(i) = 1$$

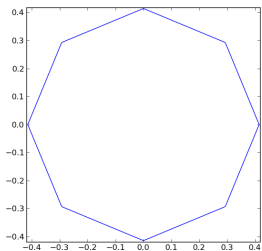




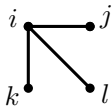
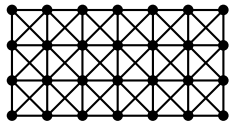
# Diagonal Edges



$$\text{MoG}(i) = |x_i - x_j| + |x_i - x_k| + \frac{\sqrt{2}}{2} |x_i - x_l|$$



$$\text{MoG}(i) = 1$$

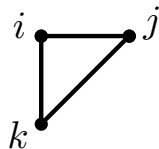
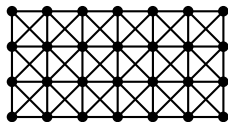


# The 3-Clique Model

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- The gradient vector  $\approx \begin{pmatrix} x_j - x_i \\ x_k - x_i \end{pmatrix}$ ,

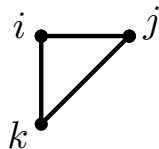
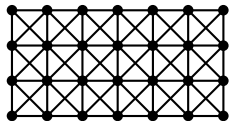


# The 3-Clique Model



- The gradient vector  $\approx \begin{pmatrix} x_j - x_i \\ x_k - x_i \end{pmatrix}$ ,
- For ordered labels  $x_i \in \{1, 2, \dots, M\}$

$$\text{MoG}(i) = \sqrt{(x_i - x_j)^2 + (x_i - x_k)^2}$$

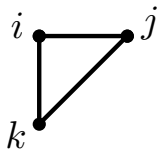
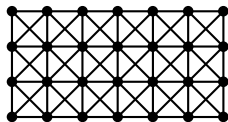


- The gradient vector  $\approx \begin{pmatrix} x_j - x_i \\ x_k - x_i \end{pmatrix}$ ,
- For ordered labels  $x_i \in \{1, 2, \dots, M\}$

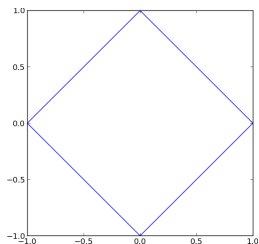
$$\text{MoG}(i) = \sqrt{(x_i - x_j)^2 + (x_i - x_k)^2}$$

- For general labels  $x_i \in \mathcal{L}$  with a semi-metric  $d$

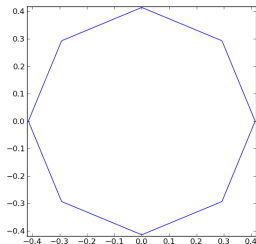
$$\text{MoG}(i) = \sqrt{d(x_i, x_j)^2 + d(x_i, x_k)^2}$$



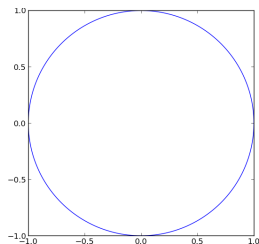
# The 3-clique Model



4 neighbours



8 neighbours

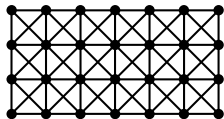


3-cliques

$$\min_{\mathbf{x} \in \mathcal{L}} \sum_i f_i(x_i) + \gamma \sum_{(i,j,k) \in \mathcal{C}^3} \sqrt{d(x_i, x_j)^2 + d(x_i, x_k)^2}$$

- **Move-based approach** is a popular way of optimizing Multi-label MRFs.
- Optimizing the multi-label MRF iteratively by solving a **series of binary MRF optimizations**.

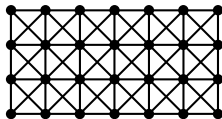
$x_1 \ x_2 \ x_3 \ x_4 \ \dots$



$x_i \in \mathcal{L}$



$u_1 \ u_2 \ u_3 \ u_4 \ \dots$



$u_i \in \{0, 1\}$

# The Alpha-Expansion Algorithm

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- Nodes have a choice to switch to  $\alpha$  or stay unchanged:

$$I_{\alpha}^0(x_i) = x_i \quad I_{\alpha}^1(x_i) = \alpha$$

- $\mathbf{I}_{\alpha}^{\mathbf{u}}(\mathbf{x}) = [I_{\alpha}^{u_1}(x_1), I_{\alpha}^{u_2}(x_2), \dots, I_{\alpha}^{u_n}(x_n)]$

**procedure** ALPHA-EXPANSION( $\mathbf{x}, \mathcal{L}$ )

**repeat**

**for each**  $\alpha \in \mathcal{L}$  **do**

$\mathbf{u}^* \leftarrow \operatorname{argmin}_{\mathbf{u}} E(\mathbf{I}_{\alpha}^{\mathbf{u}}(\mathbf{x}))$

$\mathbf{x} \leftarrow \mathbf{I}_{\alpha}^{\mathbf{u}^*}(\mathbf{x})$

**end for**

**until** *convergence*

**return**  $\mathbf{x}$

**end procedure**

# The Alpha-Beta Swap Algorithm



- Nodes with labels  $\alpha$  or  $\beta$  have a chance to swap.

$$I_{\alpha,\beta}^0(x_i) = \begin{cases} \alpha & \text{if } x_i \in \{\alpha, \beta\} \\ x_i & \text{otherwise} \end{cases} \quad I_{\alpha,\beta}^1(x_i) = \begin{cases} \beta & \text{if } x_i \in \{\alpha, \beta\} \\ x_i & \text{otherwise} \end{cases}$$

**procedure** ALPHA-BETA-SWAP( $\mathbf{x}$ ,  $\mathcal{L}$ )

**repeat**

**for each**  $\alpha, \beta \in \mathcal{L} \times \mathcal{L}$  **do**

$\mathbf{u}^* \leftarrow \operatorname{argmin}_{\mathbf{u}} E(I_{\alpha,\beta}^{\mathbf{u}}(\mathbf{x}))$

$\mathbf{x} \leftarrow I_{\alpha,\beta}^{\mathbf{u}^*}(\mathbf{x})$

**end for**

**until** *convergence*

**return**  $\mathbf{x}$

**end procedure**



- Take arbitrary  $I^0$  and  $I^1$

$$I^0(x_i) = \text{arbitrary}$$

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- Take arbitrary  $I^0$  and  $I^1$

$$I^0(x_i) = \text{arbitrary} \qquad I^1(x_i) = \text{arbitrary}$$

- The pair of functions  $(I^0, I^1)$  is called the **update policy**.
- **State Preservation Property**

$$\forall x \in \mathcal{L} \quad I^0(x) = x \quad \text{or} \quad I^1(x) = x$$

- How to solve

$$\mathbf{u}^* \leftarrow \operatorname{argmin}_{\mathbf{u}} E(\mathbf{I}^{\mathbf{u}}(\mathbf{x}))$$

- Energy functions consisting of **quadratic** and **cubic** terms are solvable by graph-cuts if and only if they are **submodular**<sup>1</sup>.
- The function  $f: \{0, 1\} \times \{0, 1\} \rightarrow \mathbb{R}$  is **submodular** if

$$f(0, 1) + f(1, 0) \geq f(0, 0) + f(1, 1).$$

- A pseudo-Boolean function of  $n$  variables is submodular if **any restriction** to any pair of variables is submodular.

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<sup>1</sup>Kolmogorov and Zabih 2004.

- **Main Question:** Given

$$E(\mathbf{x}) = \sum_{(i,j,k) \in \mathcal{C}^3} \sqrt{d(x_i, x_j)^2 + d(x_i, x_k)^2}$$

what choice of policy  $(I^0, I^1)$  results in a submodular  $E(I^{\mathbf{u}}(\mathbf{x}))$  as a function of  $\mathbf{u}$ , so we can solve

$$\mathbf{u}^* \leftarrow \operatorname{argmin}_{\mathbf{u}} E(I^{\mathbf{u}}(\mathbf{x}))$$

# Main Theorem (General Case)

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$$E(\mathbf{x}) = \sum_{(i,j,k) \in \mathcal{C}^3} \sqrt{d(x_i, x_j)^2 + d(x_i, x_k)^2}$$

## Theorem

Assume  $d: \mathcal{L} \times \mathcal{L} \rightarrow \mathbb{R}$  is a **semi-metric** and the update policy has the **state preservation property**, the energy function  $E_{\mathbf{x}}^u(\mathbf{u}) = E(I^u(\mathbf{x}))$  is submodular for all  $\mathbf{x}$ , **if and only if** for any three labels  $x, y, z \in \mathcal{L}$

$$(d(x, y^1) - d(x, y^0)) (d(x, z^1) - d(x, z^0)) \geq 0,$$

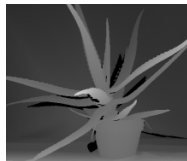
where  $x^u$  is a compact form for  $I^u(x)$ .

# Main Theorem (Ordered Labels)

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$$E(\mathbf{x}) = \sum_{(i,j,k) \in \mathcal{C}^3} \sqrt{(x_i - x_j)^2 + (x_i - x_k)^2}$$



(Middlebury Dataset)

## Proposition

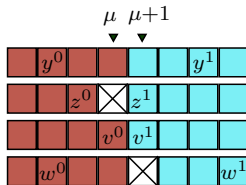
With  $\mathcal{L} = \{0, 1, \dots, M-1\}$  and  $d(x, y) = |x - y|$  (ordered labels), and having **state preservation property** for the update policy, the energy function  $E'_x(\mathbf{u}) = E(I^{\mathbf{u}}(\mathbf{x}))$  is submodular for all  $\mathbf{x}$  if and only if  $(I^0, I^1)$  is a **mirrored update policy**.

## Definition

An update policy  $(I^0, I^1)$  is called **mirrored** if

- (i)  $\forall x \in \mathcal{A} \quad I^0(x) < I^1(x)$  or  $\forall x \in \mathcal{A} \quad I^0(x) > I^1(x)$ ,
- (ii)  $\exists \mu \in \mathcal{L}$  such that  $\forall x \in \mathcal{A}$

$$\frac{I^0(x) + I^1(x)}{2} \in \left\{ \mu, \mu + \frac{1}{2}, \mu + 1 \right\}.$$



# Main Theorem (Unordered Labels)

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$$E(\mathbf{x}) = \sum_{(i,j,k) \in \mathcal{C}^3} \sqrt{1(x_i \neq x_j) + 1(x_i \neq x_k)}$$



(Buffalo-Xiph.org)

## Proposition

With  $d(x, y) = 1(x \neq y)$  (unordered labels), and assuming the **state preservation property** for the update policy, the energy function  $E'_x(\mathbf{u}) = E(\mathbf{l}^u(\mathbf{x}))$  is submodular for all  $\mathbf{x}$  if and only if for any pair of active labels  $y, z \in \mathcal{A}$ , we have  $l^0(y) \neq l^1(z)$ .



$$l_s^0(x) = \begin{cases} \min(x, s-x) & 0 \leq s-x < M, \\ x & \text{otherwise,} \end{cases} \quad l_s^1(x) = \begin{cases} \max(x, s-x) & 0 \leq s-x < M, \\ x & \text{otherwise.} \end{cases}$$

**procedure** MIRRORRED-SWAP( $\mathbf{x}$ ,  $M$ )

**repeat**

**for each**  $s \in \{1, 2, \dots, 2n-3\}$  **do**

$\mathbf{u}^* \leftarrow \operatorname{argmin}_{\mathbf{u}} E(\mathbf{l}_s^{\mathbf{u}}(\mathbf{x}))$

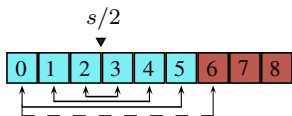
$\mathbf{x} \leftarrow \mathbf{l}_s^{\mathbf{u}^*}(\mathbf{x})$

**end for**

**until** *convergence*

**return**  $\mathbf{x}$

**end procedure**



- Suits MRFs with the **continuous** and **ordered** labels,
- Alpha-expansion cannot be applied to **ordered labels**,
- Mirrored Swap algorithm for the **ordered labels**,
- For **unordered labels**, the submodularity holds for vaster types of binary moves, including alpha-expansion and alpha-beta swap.

# Thanks

# Questions?

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